126-DRI-10-004 **SAFETY COMPLIANCE TESTING FOR FMVSS 126 Electronic Stability Control Systems**

Nissan Motor Co., Ltd. 2010 Nissan Rogue NHTSA No. CA5207

DYNAMIC RESEARCH, INC.

355 Van Ness Avenue, STE 200 Torrance, California 90501



26 May, 2010

Final Report

Prepared Under Contract No.: DTNH22-08-D-00098

U. S. DEPARTMENT OF TRANSPORTATION **National Highway Traffic Safety Administration Enforcement** Office of Vehicle Safety Compliance 1200 New Jersey Avenue, SE West Building, 4th Floor (NVS-221) Washington, DC 20590

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1.0 PURPOSE OF COMPLIANCE TEST

The purpose of this test is to determine if the test vehicle, a 2010 Nissan Rogue, meets the minimum equipment and performance requirements stated in Federal Motor Vehicle Safety Standard (FMVSS) 126, "Electronic Stability Control Systems."

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS

Testing of the 2010 Nissan Rogue was conducted at Dynamic Research, Inc (DRI) in accordance with NHTSA TP-126-02, dated November 19, 2008.

The vehicle was inspected to ensure it was equipped with an ESC system that:

- Augments vehicle directional stability by applying and adjusting brake torques individually at each wheel to induce a correcting yaw moment to a vehicle;
- Is computer controlled with the computer using a closed-loop algorithm to limit vehicle oversteer and to limit vehicle understeer;
- Has a means to determine the vehicle's yaw rate and to estimate its side slip or side slip derivative with respect to time;
- Has a means to monitor driver steering inputs;
- Has an algorithm to determine the need, and a means to modify engine torque, as necessary, to assist the driver in maintaining control of the vehicle; and
- Is operational over the full speed range of the vehicle (except at vehicle speeds less than 20 km/h (12.4 mph), when being driven in reverse, or during system initialization).

The vehicle was subjected to a 0.7 Hz Sine with Dwell steering maneuver to ensure that it would meet the stability and responsiveness requirements of the standard as follows:

 At 1.0 second after completion of a required Sine with Dwell steering input, the yaw rate of the vehicle must not exceed 35 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTINUED)

- At 1.75 seconds after completion of a required Sine with Dwell steering input, the yaw rate of the vehicle must not exceed 20 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).
- The lateral displacement of the vehicle center of gravity with respect to its initial straight path must be at least 1.83 m (6 feet) (for vehicles with a GVWR of 3,500kg (7,716 lb) or less) when computed 1.07 seconds after the Beginning of Steer (BOS) at the specified steering wheel angles.

System malfunction simulations were executed to verify vehicle could identify and indicate a malfunction.

The vehicle's ESC System appears to meet the performance and equipment requirements as required by FMVSS 126. The test results are summarized on the following summary sheet.

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTD)

Data Summary Sheet (Page 1 of 2)

Vehicle: 2010 Nissan Rogue

NHTSA No. <u>CA5207</u> VIN: <u>JN8AS5MT1AW503961</u>

Vehicle Type: MPV Manufacture Date: 12/09

Laboratory: Dynamic Research, Inc.

REQUIREMENTS: PASS/FAIL

ESC Equipment and Operational Characteristics (Data Sheet 2)

The vehicle is to be equipped with an ESC system that meets the equipment and operational characteristics requirements.

(S126, S5.1, S5.6)

ESC Malfunction Telltale (Data Sheet 3)

Vehicle is equipped with a telltale that indicates one or more <u>PASS</u>

PASS

ESC system malfunctions. (S126, S5.3)

"ESC Off" and other System Controls and Telltale (Data Sheet 3,4)

Vehicle is equipped with an ESC off telltale indicating the vehicle has been put into a mode that renders the ESC system unable to satisfy the performance requirements of the standard,

if such a mode exists. (S5.5.1)

If provided, off control and other system controls as well as the <u>PASS</u>

ESC off telltale meets the operational requirements (S126, S5.4, S5.4.1,S5.4.2, S5.5.4, and S5.5.9)

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTD)

Data Summary Sheet (Page 2 of 2)

REQUIREMENTS:	PASS/FAIL
Vehicle Lateral Stability (Data Sheet 8) Yaw Rate Ratio at 1 second after COS is less than 35% of peak value. (S126, S5.2.1)	<u>PASS</u>
Yaw Rate Ratio at 1.75 seconds after COS is less than 20% of peak value. (S126, S5.2.2)	<u>PASS</u>
Vehicle Responsiveness (Data Sheet 8) Lateral displacement at 1.07 seconds after BOS is at least 1.83 m (6 feet) for vehicles with a GVWR of 3,500kg (7,716 lb) or less, and 1.52 m (5 feet) for vehicles with a GVWR greater than 3,500 Kg (7,716 lb). (S126, S5.2.3)	<u>PASS</u>
ESC Malfunction Warning (Data Sheet 9) Warning is provided to driver after malfunction occurrence. (S126. S5.3)	<u>PASS</u>
Malfunction telltale stayed illuminated as long as malfunction existed and must extinguish after malfunction was corrected. (S126, S5.3.7)	<u>PASS</u>

3.0 TEST DATA

Data Sheet 1 (Page 1 of 2) TEST VEHICLE INSPECTION AND TEST PREPARATION

NHTSA No. <u>CA5207</u> Data Sheet Completion Date: <u>2/22/</u>	2010		
VIN JN8AS5MT1AW503961 Manufacture Date: 12/09			
GVWR (kg): <u>1968.2</u> Front GAWR (kg): <u>1038.7</u> Rear GAWR (kg):	<u>948.9</u>		
Seating Positions Front: $\underline{2}$ Mid: Rear: $\underline{3}$			
Odometer reading at time of inspection: <u>5 miles (8 km)</u>			
DESIGNATED TIRE SIZE(S) FROM VEHICLE LABELING:			
Front axle: <u>P225/60 R17</u> Rear axle: <u>P225/60 R17</u>			
INSTALLED TIRE SIZE(S) ON VEHICLE (from tire sidewall)			
Front Axle Rear Axle			
Tire Manufacturer: <u>Continental</u> <u>Continental</u>	<u>a/</u>		
Tire Model: <u>4x4 Contact</u> <u>4x4 Contact</u>	<u>ct</u>		
Tire Size: <u>P225/60 R17</u> <u>P225/60 R</u>	17		
TIN Left Front: FDFC 3AK 4909 Right Front: FDFC 3AK 45	909		
Left Rear: FDFC 3AK 4909 Right Rear: FDFC 3AK 45	<u>909</u>		
Are installed tire sizes same as labeled tire sizes? Yes			
If no, contact COTR for further guidance			
DRIVE CONFIGURATION(S):(mark all that apply)			
X Two Wheel Drive (2WD) X Front Wheel Drive Rear Wheel D	rive		
All Wheel Drive (AWD)			
Four Wheel Drive Automatic - differential no locked full time (4WD Automatic)			
Four Wheel Drive (High Gear Locked Differential 4WD HGLD)			
Four Wheel Drive Low Gear (4WD Low)			
Other (Describe)			

Data Sheet 1 (Page 2 of 2) TEST VEHICLE INSPECTION AND TEST PREPARATION

DRIVE CONFIGURATIONS AND MODES: (ex. default, performance, off) (For each of the vehicle's drive configurations identify available operating modes) Drive Configuration: FWD Mode: Normal **Drive Configuration:** Mode: **Drive Configuration:** Mode: **VEHICLE STABILITY SYSTEMS (Check applicable technologies):** List other systems: **Traction Control** Roll Stability Control X **ESC** Active Suspension | X | Electronic Throttle Control **Active Steering ABS REMARKS:** 2/22/2010 **RECORDED BY:** J Lenkeit DATE RECORDED: B Kebschull DATE APPROVED: 3/4/2010 APPROVED BY:

Data Sheet 2 (Page 1 of 2) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

Vehicle: 2010 Nissan Rogue MPV	
NHTSA No <u>CA5207</u> Data Sheet Completion Date: <u>4/6/20</u>	<u>)10</u>
ESC SYSTEM IDENTIFICATION	
Manufacturer/Model Hitachi Automotive Systems ABS/VDC/TCS/ LX	X5-VDC
ESC SYSTEM HARDWARE (Check applicable hardware)	
X Electronic Control Unit X Hydraulic Control Unit	
X Wheel Speed Sensors X Steering Angle Sensor	
X Yaw Rate Sensor X Lateral Acceleration Sensor	
List other Components: ABS motor, pump, valves and accumulator	<u>rs</u>
ESC OPERATIONAL CHARACTERISTICS	
System is capable of generating brake torque at each wheel	X Yes (Pass
Brief explanation: ABS motor and pump supplies brake actuating	No (Fail)
pressure, routed through individual brake circuit and wheel valves,	
under control of ESC component of ECU	V (D
System is capable of determining yaw rate	X Yes (Pass)
Brief explanation: Yaw rate sensor	No (Fail)
System is capable of monitoring driver steering input	x Yes (Pass
Brief explanation: <i>Steering angle sensor</i>	
21101 Oxplanations <u>Crooming arigin contact</u>	No (Fail)
System is capable of estimating side slip or side slip derivative	x Yes (Pass
Brief explanation: A vehicle slip angle model is used to estimate the	No (Fail)
vehicle's slip angle from measured steering angle, yaw rate, lateral	
acceleration and estimated vehicle speed data	

Data Sheet 2 (Page 2 of 2) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

ESC OPERATIONAL CHARACTERISTICS (co	ontinued)
System is capable of modifying engine torque Method used to modify torque: The engine of receives the engine torque request from the modifies the engine torque by differentiating fuel delivery.	<u>controller module</u> <u>ESC controller unit and</u> No (Fail)
System is capable of activation at speeds of and higher	f 20 km/h (12.4 mph) X Yes (Pass) No (Fail)
Speed system becomes active: <u>15 km</u> ,	
_	ollowing driving phases: activation of ABS or control X Yes (Pass) No (Fail)
Driving phases during which ESC is capable The ESC system is active during ALL of the phases: acceleration, deceleration, coasting ABS or traction control. The ESC system when ESC activated.	following driving during activation of the vill not activate during
Vehicle manufacturer submitted documenta ESC mitigates understeer	tion explaining how the X Yes (Pass) No (Fail)
DATA IN	NDICATES COMPLIANCE: X Yes (Pass) No (Fail)
REMARKS:	
	DATE RECORDED: <u>4/6/2010</u> DATE APPROVED: <u>4/6/2010</u>

5.6)

Data Sheet 3 (Page 1 of 2) ESC MALFUNCTION AND OFF TELLTALES

Vehicle: 2010 Nissan Rogue MPV NHTSA No. CA5207 Data Sheet completion date: 3/1/2010 **ESC Malfunction Telltale** Vehicle is equipped with malfunction telltale? Yes Telltale Location: Center of tachometer (see Figure 5.6) Telltale Color: *Amber* Telltale symbol or abbreviation used Vehicle uses this symbol Vehicle uses this abbreviation Neither symbol or abbreviation is used If different than identified above, make note of any message, symbol or abbreviation used. If a malfunction occurs in the system, both the "Slip" indicator (shown above left) and the VDC OFF indicators illuminate (see Figure 5.6) Is telltale part of a common space? No Is telltale also used to indicate activation of the ESC system? Yes If yes explain telltale operation during ESC activation: The "Slip" indicator (shown above left) blinks when ESC is operating (see Figure

Data Sheet 3 (Page 2 of 2) ESC MALFUNCTION AND OFF TELLTALES

"ESC OFF" Telltale (if provided)		
Vehicle is equipped v	with "ESC OFF" te	elltale? <u>Yes</u>	
Is "ESC Off" telltale telltale? <u>No</u>	combined with "	ESC Malfunction" telltale	e utilizing a two part
Telltale Location: Ce	enter of tachomete	er (see Figure 5.6)	
Telltale Color: <u>Am</u>	<u>ber</u>		
Telltale symbol or ab	breviation used		
OFF or E	SC OFF	Vehicle uses this Vehicle uses this X Neither symbol oused	·
If different than identifused. <u>VDC OFF</u>	ïed above, make no	ote of any message, symb	ool or abbreviation
Is telltale part of a co	ommon space? <u><i>No</i></u>	<u>.</u>	
DATA INDICATES C	OMPLIANCE <u>Ye</u>	<u>s</u>	
(Vehicle is compliant	if equipped with	a malfunction telltale)	
		en ESC is switched off; ' d "Slip" indicators illumii	
RECORDED BY: APPROVED BY:	J Lenkeit B Kebschull	DATE RECORDED: DATE APPROVED:	3/1/2010 3/8/2010

Data Sheet 4 (Page 1 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

Vehicle: <u>2010 Nis</u>	ssan Rogue	<u>MPV</u>
NHTSA No. <i>CA52</i>	<u> 207</u>	Data Sheet completion date: 3/1/2010
"ESC OFF" Contr	ols Identific	ation and Operational Check:
the ESC system of	or place the	a control or controls whose purpose is to deactivate ESC system in a mode or modes that may no ce requirements of the standard? X Yes No
Type of contro controls provid (mark all that a	ed? ipply)	X Dedicated "ESC Off" Control Multi-functional control with an "ESC Off" mode Other (describe)
Identify each con	trol location	n, labeling and selectable modes.
First Control:	Location	Lower left of steering column, (see Figure 5.7)
	Labeling Modes	VDC OFF Turns ESC on and off
Second Control:	Location Labeling Modes	
Identify standard of	or default dri	ve configuration FWD
Verify standard or	default drive	e configuration selected X Yes No
Does the "ESC Off" telltale illuminate upon activation of the dedicated ESC off control or selection of the "ESC Off" mode on the multi-function control?		
Daga the "ESC Of	f" talltala avi	X Yes No (Fail)
		inguish when the ignition is cycled from "on" ("Run") to again to the "On" ("Run") position?
If no, describe how	v the "Off" co	X Yes No (Fail) ontrol functions

Data Sheet 4 (Page 2 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

If a multi-function control is provided, cycle through each mode setting on the control and record which modes illuminate the "ESC Off" telltale. Also, for those modes that illuminate the ESC Off" telltale identify if the telltale extinguishes upon cycling the ignition system.

"ESC Off" telltale "ESC Off" telltale

		illuminates upon	extinguishes
Conti	rol Mode	activation of control? (Yes/No)	upon cycling ignition? (Yes/No)
NA		(100,000)	.g
	t illuminates the "ESC was cycled from "On" ("Run") position?	("Run") to "Lock" or '	•
Other System Con	trols that have an anci	llary effect on ESC Op	eration:
deactivate the ESC	oped with any ancillary C system or place the E he performance require	SC system in a mode	or modes that may
Ancillary Control:	System None		
	Control Description		
	Labeling		
Ancillary Control:	System		
	Control Description		
	Labeling		
Ancillary Control:	System		
	Control Description		
	Labeling		

Data Sheet 4 (Page 3 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

Activate each control listed above and record whether the control illuminates the "ESC Off" telltale. Also, record warnings or messages provided regarding the ESC system.

	Control Activates "ESC Off"	
Ancillary Control	Telltale? (Yes/No)	Warnings or Messages Provided
None		

For those controls that illuminate the "ESC Off" telltale above identify if the "ESC Off" telltale extinguishes upon cycling the ignition system.

	"ESC Off" telltale extinguishes
Ancillary Control	upon cycling ignition? (Yes/No)
None	

For each control that illuminates the "ESC Off" telltale, did the telltale extinguish when the ignition is cycled from "On" ("Run") to "Lock" or "Off" and then back again to the "On" ("Run") position? If activating the control places the vehicle into a low-range four-wheel drive configuration designed for low-speed, off-road driving, the ESC system may remain turned off after the ignition has been cycled off and then back on and therefore the "ESC Off" telltale may not extinguish.

off and then back	on and therefore the	e ESC Off telitale may	Yes No (Fail)
	DATA	INDICATES COMPLIAN	CE: PASS
Remarks:			
RECORDED BY:	J Lenkeit	DATE RECORDED:	3/1/2010
APPROVED BY:	B Kebschull	DATE APPROVED:	3/8/2010

Data Sheet 5 (Page 1 of 3) TEST TRACK AND VEHICLE DATA

Vehicle: 2010 Nissan Roque MPV NHTSA No. CA5207 Data Sheet completion date: 3/3/2010 **Test Track Requirements:** Test surface slope (0-1%): 0.5% Peak Friction Coefficient (at least 0.9) 0.93 Test track data meets requirements: Yes If no, explain: **Full Fluid Levels:** Fuel Yes Other Fluids *Yes* (specify) Washers, Brakes, transmission Coolant Yes Tire Pressures: Front Axle 230 Rear Axle 230 Required; KPA **KPA** Actual; LF 230 KPA RF *230* **KPA** LR *230* KPA RR *230* KPA **Vehicle Dimensions:** Front Track Width 154.3 cm Wheelbase 269.0 cm Rear Track Width 153.7 cm **Vehicle Weight Ratings:** GAWR Front 1038.7 KG GAWR Rear *948.9* KG **Unloaded Vehicle Weight (UVW):** Front Axle 911.3 KG Left Front *461.3* KG Right Front 450.0 KG Rear Axle 616.5 KG Left Rear *304.4* KG Right Rear 312.1 KG Total UVW 1527.8 KG Baseline Weight and Outrigger Selection (only for MPVs, Trucks, Buses) Calculated baseline weight (UVW + 73kg) *1600.8* KG Standard Outrigger size required ("Standard" or "Heavy") Standard - Baseline weight under 2772 kg (6000 lb) Heavy - Baseline weight equal to or greater than 2772 kg (6000 lb)

Data Sheet 5 (Page 2 of 3) TEST TRACK AND VEHICLE DATA

UVW with Outriggers: (only for MPVs, Trucks, Buses)

Loaded Vehicle Weight w/Driver and Instrumentation (no Ballast)

Total Loaded Vehicle Weight w/Driver and Instrumentation and Ballast

Data Sheet 5 (Page 3 of 3) TEST TRACK AND VEHICLE DATA

Center of Gravity and Inertial Sensing System Location at Loaded Vehicle Condition:

x-distance (longitudinal)

Point of reference is the front axle centerline.

(Positive from front axle toward rear of vehicle.)

y-distance (lateral)

Point of reference is the vehicle centerline.

(Positive from the center toward the right.)

Point of reference is the ground plane. (Positive from the ground up.)

Locations:

z-distance (vertical)

	<u>Center of</u>	of Gravity		Inertia	I Sensing System
x-distance	<u>44.5</u> in	<i>113.1</i> cm		66.0	in <u>167.7</u> cm
y-distance	<i>-0.3</i> in	<i>-0.7</i> cm		-0.3	in <u>-0.7</u> cm
z-distance	in	<i>62.6</i> cm		21.4	in <u>54.2</u> cm
		Roof Height _	64.9	in	_ <i>164.7</i> _ cm
Distance between ultrasonic sensors			83	in	<i>210.8</i> cm

Remarks:

RECORDED BY: B Kebschull DATE RECORDED: 3/3/2010
APPROVED BY: J Lenkeit DATE APPROVED: 3/8/2010

Data Sheet 6 (Page 1 of 3) BRAKE AND TIRE CONDITIONING

Vehicle: 2010 Nissan Rogue MPV

NHTSA No. CA5207

Measured tire pressure: LF 232 KPA RF 234 KPA

LR 233 KPA RR 232 KPA

Wind Speed $\underline{4.2}$ m/s (10 m/sec (22 mph) max for passenger cars;

5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 11.5 °C

Brake Conditioning Time: <u>9:10:00 AM</u> Date: <u>3/4/2010</u>

56 km/h (35 mph) Brake Stops

Number of stops executed (10 required) <u>10</u> Stops

Observed deceleration rate range (.5g target) 0.45-0.55 g

72 km/h (45 mph) Brake Stops

Number of stops executed (3 required) $\underline{3}$ Stops

Number of stops ABS activated (3 required) 3 Stops

Observed deceleration rate range 0.80 g

72 km/h (45 mph) Brake Cool Down Period

Duration of cool down period (5 minutes min.) 5 Minutes

Data Sheet 6 (Page 2 of 3) BRAKE AND TIRE CONDITIONING

Tire Conditioning series No. 1	Time:	9:35:00 AM			Date:		<u> 2010</u>
Measured cold tire pressure	LF	<u>241</u>	KPA	RF	RF <u>243</u>		KPA
	LR	<u>240</u>	KPA	RR	23	38	KPA
Wind Speed3.8 m/s	(10 m/sec (22 mph) max for passenger cars;						cars;
	5m/sec (11 mph) max for MPVs and trucks)						ıcks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 11.4°C

30 meter (100 ft) Diameter Circle Maneuver								
Test Run	Steering Direction	Target Lateral Acceleration (g)	Observed Lateral Acceleration (g)	Observed Vehicle Speed (Km/h)				
1-3	Clockwise	0.5 – 0.6	0.5-0.6	32.8 - 33.6				
4-6	Counterclockwise	0.5 - 0.6	<u>0.5-0.6</u>	<u>32 - 33.6</u>				

	5-1 Hz Cycle Sinusoidal Steering Maneuver to Determine Steering Wheel Angle for 0.5-0.6 g Lateral Acceleration										
Test Run	Data File	Vehicle Speed Km/h(mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)						
1	3	56 ± 2 (35 ± 1)	<u>60</u>	0.5 - 0.6	<u>0.38</u>						
2		56 ± 2 (35 ± 1)		0.5 - 0.6							
3		56 ± 2 (35 ± 1)		0.5 - 0.6							
4		56 ± 2 (35 ± 1)		0.5 - 0.6							

Steering wheel angle that corresponds to a peak 0.5-0.6 g lateral acceleration: 87 degrees

	10-1 Hz Cycle Sinusoidal Steering Maneuver									
Test Run	Data File	Vehicle Speed Km/h (mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)					
1-3	<u>4-6</u>	56 ± 2 (35 ± 1)	<u>90</u> (cycles 1-10)	0.5 - 0.6	<u>0.51</u>					
4	7	E6 + 2 /2E + 1)	<u>90</u> (cycles 1-9)	0.5 - 0.6	<u>0.51</u>					
4	$\frac{7}{2}$ 56 ± 2 (35 ± 1)		<u>180</u> (cycle10) *	NA	<u>0.77</u>					

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9

Data Sheet 6 (Page 3 of 3) BRAKE AND TIRE CONDITIONING

Tire Conditioning series No. 2 Time: 11:12:00 AM Date: 3/4/2010

Measured cold tire pressure LF <u>240</u> KPA RF <u>245</u> KPA

LR <u>235</u> KPA RR <u>235</u> KPA

Wind Speed <u>2.6</u> m/s (10 m/sec (22 mph) max for passenger cars;

5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 12.8 °C

30 meter (100 ft) Diameter Circle Maneuver									
Test Run Steering Direction Target Lateral Acceleration (g) Observed Lateral Acceleration (g) Speed (Km/h)									
1-3	Clockwise	0.5 - 0.6	<u>0.5-0.6</u>	<u> 32.8 - 33.6</u>					
4-6	Counterclockwise	0.5 - 0.6	<u>0.5-0.6</u>	<u> 32.8 - 33.6</u>					

Steering wheel angle that corresponds to a peak 0.5-0.6 g lateral acceleration:

87 degrees

	10-1 Hz Cycle Sinusoidal Steering Maneuver									
Test Data Vehicle Speed Steering Wheel Angle (degrees) Target Peak Lateral Lateral Acceleration (g) Acceleration										
1-3	<u>18-20</u>	56 ± 2 (35 ± 1)	<u>90</u> (cycles 1-10)	0.5 - 0.6	<u>0.51</u>					
4	21 56 ± 2 (35 ± 1)		<u>90</u> (cycles 1-9)	0.5 - 0.6	<u>0.51</u>					
4			(cycle 10)*	NA	<u>0.77</u>					

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9

Remarks:

RECORDED BY: B Kebschull DATE RECORDED: 3/4/2010

APPROVED BY: J Lenkeit DATE APPROVED: 3/8/2010

Data Sheet 7 (Page 1 of 2) SLOWLY INCREASING STEER (SIS) MANEUVER

Vehicle: 2010 Nissan Rogue MPV

NHTSA No. *CA5207*

Measured tire pressure: LF 240 KPA RF 239 KPA

LR <u>238</u> KPA RR <u>234</u> KPA

Wind Speed 4.8 m/s

(10 m/sec (22 mph) max for passenger cars; 5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 13.1 °C

Selected drive configuration FWD

Selected Mode: Default

Preliminary Left Steer Maneuver:

Lateral Acceleration measured at 30 degrees steering wheel angle

Assuming a linear relationship the following ratio should be used to calculate the steering wheel angle at 0.55g:

$$\frac{30 \, \text{degrees}}{a_{\text{y,30 degrees}}} = \frac{\delta_{\text{SIS}}}{0.55 \, \text{g}}$$

$$\frac{\delta_{\text{sis}} = \underline{56.9} \, \text{degrees (@.55g)}}{\delta_{\text{sis}} = \underline{60} \, \text{degrees (rounded)}}$$

Steering Wheel Angle at Corrected 0.3g Lateral Acceleration:

		Time Clock	Steering Wheel Angle		
	Initial Steer	(5 min max	to nearest	Data	
Maneuver	Direction	between runs)	0.1° (degrees)	Run	Good/NG
1	Left	<u>10:12:00 AM</u>		<u>10</u>	<u>NG</u>
2	Left	<u>10:17:00 AM</u>	<u>32.6</u>	<u>11</u>	<u>Good</u>
3	Left	10:22:00 AM	<u>32.9</u>	<u>12</u>	Good
4	Left	<u>10:27:00 AM</u>	<u>32.4</u>	<u>13</u>	Good
5	Left				
1	Right	10:32:00 AM	<u>32.2</u>	<u>14</u>	Good
2	Right	10:37:00 AM	<u>32.7</u>	<u>15</u>	Good
3	Right	10:41:00 AM		<u>16</u>	<u>NG</u>
4	Right	10:45:00 AM	<u>32.9</u>	<u>17</u>	<u>Good</u>
5	Right				

Data Sheet 7 (Page 2 of 2) SLOWLY INCREASING STEER (SIS) MANEUVER

Average Overall Steering Wheel Angle:

$$\delta_{0.3\;g,\;overall} = (\left| \begin{array}{c|c} \delta_{0.3\;g,\;left\;(1)} \end{array} \right| + \left| \begin{array}{c|c} \delta_{0.3\;g,\;left\;(2)} \end{array} \right| + \left| \begin{array}{c|c} \delta_{0.3\;g,\;left\;(3)} \end{array} \right| + \delta_{0.3\;g,\;right\;(1)} + \delta_{0.3\;g,\;right\;(2)} + \delta_{0.3\;g,\;right\;(3)} \right) / 6$$

$$\delta_{0.3\;g,\;overall} = \underline{\qquad 32.6 \qquad} \quad \text{degrees}$$
 [to nearest 0.1 degree]

Remarks:			

RECORDED BY: B Kebschull DATE RECORDED: 3/4/2010
APPROVED BY: J Lenkeit DATE APPROVED: 3/8/2010

Data Sheet 8 (Page 1 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

Vehicle: 2010 Nissan Rogue MPV			
NHTSA No. <u>CA5207</u>	Data sheet complet	ion date:	3/4/2010
Tire conditioning completed		X Yes	No
ESC system is enabled		X Yes	No
On track calibration checks have	been completed	X Yes	No
On track static data file for each	sensor obtained	X Yes	No
Selected Drive Configuration:	FWD		
Selected Mode: Default			
Overall steering wheel angle (δο.3	3 g. overall) 32.6 d	legrees	

Lateral Stability Test Series No. 1 - Counterclockwise Initial Steer Direction

		Comm	anded	,	Yaw Rate	S	Y	'RR	`	/RR
	Clock	Steering	y Wheel	(c	(degrees/sec)		at 1.0 sec after		at 1.75 sec after	
Maneuver	Time	Ang	gle¹				C	os	COS	
#							[<	35%]	[< 20%]	
	(1.5 – 5.0 min max between runs)	Scalar (* δ _{0.3 g})	Angle (degrees)	$\dot{\psi}_{\it Peak}$	$\dot{\psi}_{ m 1.0sec}$	$\dot{\psi}_{1.75\mathrm{sec}}$	%	Pass/Fail	%	Pass/Fail
23	11:23 AM	1.5	49	12.3	-0.0	-0.1	-0.3	PASS	-0.8	PASS
24	11:25 AM	2.0	65	15.9	-0.0	-0.2	-0.3	PASS	-1.2	PASS
25	11:30 AM	2.5	82	20.6	-0.2	-0.2	-0.9	PASS	-0.7	PASS
26	11:33 AM	3.0	98	24.3	-0.2	-0.1	-1.0	PASS	-0.5	PASS
27	11:36 AM	3.5	114	28.5	-0.2	-0.1	-0.7	PASS	-0.3	PASS
28	11:39 AM	4.0	130	33.9	-0.2	-0.1	-0.6	PASS	-0.2	PASS
29	11:44 AM	4.5	147	40.2	-0.1	0.0	-0.2	PASS	0.0	PASS
30	11:48 AM	5.0	163	44.9	0.3	0.0	0.6	PASS	0.1	PASS
31	11:50 AM	5.5	179	49.9	1.0	-0.1	2.1	PASS	-0.3	PASS
32	11:53 AM	6.0	196	48.6	-0.3	-0.1	-0.5	PASS	-0.2	PASS
33	11:55 AM	6.5	212	48.9	0.6	0.8	1.3	PASS	1.6	PASS
34	11:58 AM	7.0	228	54.0	0.2	0.1	0.4	PASS	0.1	PASS
35	12:01 PM	7.5	245	52.4	-0.9	-0.9	-1.8	PASS	-1.7	PASS
36	12:05 PM	8.0	261	51.5	-0.6	-0.4	-1.1	PASS	-0.8	PASS
37	12:09 PM	-	270	48.4	-0.2	-0.1	-0.3	PASS	-0.1	PASS

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5 * \delta_0.3 g, overall or 270 degrees is utilized, whichever is greater provided the calculated magnitude of 6.5 * \delta_0.3 g, overall is less than or equal to 300 degrees. If 6.5 * \delta_0.3 g, overall is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5 * \delta_0.3 g, overall without exceeding the 270 degree steering wheel angle.

DATA SHEET 8 (2 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

LATERAL STABILITY TEST SERIES NO. 2 - Clockwise Initial Steer Direction

LATERAL STABILITY TEST SERIES NO. 2 - Clockwise Initial Steer Direction										
		Comm	anded	,	Yaw Rate	S	YRR		Y	′RR
	Clock	Steering	y Wheel	(c	(degrees/sec)		at 1.0 sec after		at 1.75 sec after	
Maneuver	Time	Ang	ale¹		_		cos		cos	
#		,					[< 35%]		[< 20%]	
	(1.5 –	Scalar	Angle	. •.	. •.	. •.	%	Pass/Fail	%	Pass/Fail
	5.0 min	(* δ _{0.3 g})	(degrees)	$\dot{\psi}_{\scriptscriptstyle Peak}$	$\psi_{1.0 { m sec}}$	$\dot{\psi}_{1.75\mathrm{sec}}$,0	i acc, i an	,,	1 000/1 011
	max	(00.3 g)	(degrees)							
	between									
	runs)									
38	12:11 PM	1.5	49	-12.4	0.0	-0.0	-0.3	PASS	0.3	PASS
39	12:15 PM	2.0	65	-16.5	0.1	-0.0	-0.8	PASS	0.1	PASS
40	12:19 PM	2.5	82	-21.0	0.1	0.1	-0.6	PASS	-0.4	PASS
41	12:21 PM	3.0	98	-25.9	0.2	0.1	-0.8	PASS	-0.4	PASS
42	12:24 PM	3.5	114	-29.7	0.6	0.4	-1.8	PASS	-1.3	PASS
43	12:29 PM	4.0	130	-35.2	-0.0	0.1	0.1	PASS	-0.2	PASS
44	12:31 PM	4.5	147	-39.9	0.3	0.2	-0.9	PASS	-0.6	PASS
45	12:34 PM	5.0	163	-45.1	0.3	0.3	-0.7	PASS	-0.7	PASS
48	12:36 PM	5.5	179	-46.2	0.6	0.5	-1.4	PASS	-1.0	PASS
49	12:41 PM	6.0	196	-49.0	0.5	0.4	-1.1	PASS	-0.8	PASS
51	12:43 PM	6.5	212	-49.7	1.1	1.0	-2.3	PASS	-2.0	PASS
52	12:47 PM	7.0	228	-50.8	1.9	1.6	-3.8	PASS	-3.2	PASS
54	12:50 PM	7.5	245	-52.8	0.3	0.1	-0.5	PASS	-0.1	PASS
55	12:53 PM	8.0	261	-52.0	0.3	0.1	-0.5	PASS	-0.1	PASS
56	12:57 PM	-	270	-51.1	0.2	0.0	-0.3	PASS	-0.0	PASS

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5*\delta_{0.3 g, overall} or 270 degrees is utilized, whichever is greater provided the calculated 6.5*\delta_{0.3 g, overall} is less than or equal to 300 degrees. If 6.5*\delta_{0.3 g, overall} is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5*\delta_{0.3 g, overall} without exceeding the 270 degree steering wheel angle.

During execution of the Sine with Dwell maneuvers were any of the

following events observed?				
Rim-to-pavement contact		Yes	X	No
Tire debeading		Yes	X	No
Loss of pavement contact of vehicle tires		Yes	X	No
Did the test driver experience any vehicle loss of control or spinout?		Yes	X	No
If "Yes" explain the event and consult with	the CO)TR		

DATA SHEET 8 (3 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

Responsiveness – Lateral Displacement

Maneuver	Initial Steer	Aı	Steering Wheel ngle _{erall} or greater)	Calculated Lateral Displacement ¹	
#	Direction	Scalar *δο.3 g	Angle (degrees)	Distance (m)	Pass/Fail
30	Counter Clockwise	5.0	163	-3.1	<u>PASS</u>
31	Counter Clockwise	5.5	179	-3.2	<u>PASS</u>
32	Counter Clockwise	6.0	196	-3.3	<u>PASS</u>
33	Counter Clockwise	6.5	212	-3.4	<u>PASS</u>
34	Counter Clockwise	7.0	228	-3.4	<u>PASS</u>
35	Counter Clockwise	7.5	245	-3.3	<u>PASS</u>
36	Counter Clockwise	8.0	261	-3.4	<u>PASS</u>
37	Counter Clockwise	-	270	-3.4	<u>PASS</u>
45	Clockwise	5.0	165	3.0	<u>PASS</u>
48	Clockwise	5.5	182	3.2	<u>PASS</u>
49	Clockwise	6.0	198	3.2	<u>PASS</u>
51	Clockwise	6.5	218	3.3	<u>PASS</u>
52	Clockwise	7.0	238	3.2	<u>PASS</u>
54	Clockwise	7.5	246	3.3	<u>PASS</u>
55	Clockwise	8.0	262	3.3	<u>PASS</u>
56	Clockwise	-	271	3.3	PASS

^{1.} Lateral displacement should be \geq 1.83 m (6 ft) for vehicle with a GVWR of 3,500 kg (7,716 lb) or less; and \geq 1.52 m (5 ft) for vehicles with GVWR greater than 3,500 kg (7,716 lb).

DATA INDICATES	COMPLIANCE:	☑ PASS	☐ FAIL	
Remarks:				
RECORDED BY:	B Kebschull	DATE RECORDED:	3/3/2010	
APPROVED BY:	J Lenkeit	DATE APPROVED:	3/8/2010	

Data Sheet 9 (Page 1 of 2) MALFUNCTION WARNING TESTS

Vehicle: 2010 Nissan Rogue MPV	
NHTSA No. <u>CA5207</u>	Data Sheet Completion Date: 3/4/2010
	TEST 1
MALFUNCTION SIMULATION:	Describe method of malfunction simulation
Disconnected the LF wheel spee	<u>d sensor</u>
MALFUNCTION TELLTALE ILL	UMINATION:
	minated after ignition locking system is cle is driven at least 2 minutes as specified in
	X Yes No
Time for telltale to illuminate after in of 48 \pm 8 km/h (30 \pm 5mph) is reac σ Seconds (must be within	
ESC SYSTEM RESTORATION	
Telltale extinguishes after ignition lot the vehicle is driven at least 2 minu	ocking system is activated and if necessary tes as specified in section 13.12.B X Yes No
Time for telltale to extinguish after speed of 48 \pm 8 km/h (30 \pm 5mph)	ignition system is activated and vehicle is reached.
O Seconds (must be within	2 minutes) X Pass Fail
TEST 1 DATA	A INDICATES COMPLIANCE: PASS
both illuminated immediately upon t	ESC telltales (car with curved lines below) turning the ignition on, after malfunction was d). All three extinguished immediately upon No driving was required. DATE RECORDED: 3/4/2010
APPROVED BY: J Lenkeit	DATE APPROVED 3/8/2010

Data Sheet 9 (Page 2 of 2) MALFUNCTION WARNING TESTS

Vehicle: 2010 Nissan Rogue MPV							
NHTSA No <u>. CA5207</u>	Data Sheet Completion Date: 3/4/2010						
	TEST 2						
MALFUNCTION SIMULATION: Describe method of malfunction simulation							
Disconnected steering angle ser	nsor.						
MALFUNCTION TELLTALE ILL	.UMINATION:						
	minated after ignition locking system is cle is driven at least 2 minutes as specified in						
	X Yes No						
Time for telltale to illuminate after of 48 \pm 8 km/h (30 \pm 5mph) is read 0 Seconds (must be within							
ESC SYSTEM RESTORATION							
	ocking system is activated and if necessary utes as specified in section 13.12.B X Yes No						
Time for telltale to extinguish after speed of 48 \pm 8 km/h (30 \pm 5mph)	ignition system is activated and vehicle is reached.						
0 Seconds (must be within	2 minutes) X Pass Fail						
TEST 2 DAT	A INDICATES COMPLIANCE: PASS						
both illuminated immediately upon	ESC telltales (car with curved lines below) turning the ignition on, after malfunction was ately upon ignition, after system was						
RECORDED BY: B Kebschull	DATE RECORDED: <u>3/4/2010</u>						
APPROVED BY: J Lenkeit	DATE APPROVED 3/8/2010						

4.0 TEST EQUIPMENT LIST AND CALIBRATION INFORMATION (1 OF 2)

TABLE 1. TEST INSTRUMENTATION

Туре	Output	Range	Resolution	Accuracy	Specifics	Serial Number	Calibration
Tire Pressure Gauge	Vehicle Tire Pressure	0-100 psi 0-690 kPa	1 psi 6.89 kPa	0.5 psi 3.45 kPa	Ashcroft D1005PS	1039350	By: DRI Date:2/25/10 Due: 2/25/11
Platform Scales	Vehicle Total, Wheel, and Axle Load	8000 lb 35.6 kN	0.5 lb 2.2 N	±1.0% of applied load	Intercomp Model SWII	24032361	By: American Scale Date: 2/25/10 Due: 2/25/11
Automated Steering Machine with Steering Angle Encoder	Handwheel Angle	±800 deg	0.25 deg	±0.25 deg	Heitz Automotive Testing Model: Sprint 3	60304	By: DRI Date: 2/25/10 Due: 2/25/11
Multi-Axis Inertial Sensing System	Longitudinal, Lateral, and Vertical Acceleration Roll, Yaw, and Pitch Rate	Accelerometer s: ±2 g Angular Rate Sensors: ±100 deg/s	Accelerometers: ≤10 ug Angular Rate Sensors: ≤0.004 deg/s	Acceleromete rs: ≤0.05% of full range Angular Rate Sensors: 0.05% of full range	BEI Technologies Model: MotionPAK MP-1	0767	By: Systron Donner Date: 11/23/09 Due: 11/23/10
Radar Speed Sensor and Dashboard Display	Vehicle Speed	0-125 mph 0-200 km/h	0.009 mph .014 km/h	±0.25% of full scale	A-DAT Corp. Radar Model: DRS- 6 Display Model: RD- 2	1400.604	By: DRI Date:3/2/10 Due:3/2/11
Ultrasonic Distance	Left and Right Side	5-24 inches	0.01 inches	±0.25% of	Massa Products Corporation	DOT-NHTSA D2646	By: DRI Date:2/26/10 Due: 2/26/11
Measuring System	Vehicle Height	127-610 mm	.254 mm	distance	Model: M- 5000/220	DOT-NHTSA D3272	By: DRI Date:2/26/10 Due: 2/26/11

4.0 TEST EQUIPMENT LIST AND CALIBRATION INFORMATION (2 OF 2)

TABLE 1. TEST INSTRUMENTATION (CONTD)

Туре	Output	Range	Resolution	Accuracy	Specifics	Serial Number	Calibration
Data Acquisition System [Includes amplification, anti-	Record Time; Velocity; Distance; Lateral, Longitudinal, and Vertical Accelerations; Roll, Yaw, and Pitch Rates; Steering Wheel Angle.	Sufficient to meet or exceed individual sensors	200 Hz	Sufficient to meet or exceed individual sensors	SoMat eDaq ECPU processor	MSHLB.03- 2476	By: DRI Date: 2/9/10 Due: 2/9/11
aliasing, and analog to digital conversion.]					SoMat High level Board EHLS	MSHLS.03- 3182	By: DRI Date: 2/9/10 Due: 2/9/11
Load Cell	Vehicle Brake Pedal Force	0-300 lb 0-1.33 kN	1 lb 4.44 N	±0.05% of full scale	Lebow 3663-300	767	Functionally verified by DRi prior to test
Coordinate Measurement Machine	Inertial Sensing System Coordinates	0-8 ft 0-2.4 m	±.0020 in. ±.051 mm	±.0020 in. ±.051 mm (Single point articulation accuracy)	Faro Arm Fusion	UO8-05-08- 06636	By: Faro Date: 8/18/09 Due: 8/18/10
Outriggers	No output. Safety Item.	N/A	N/A	N/A	DRI manufactured Aluminum meeting the weight and MOI specifications of Docket 2007- 27662-11	N/A	N/A

5.0 PHOTOGRAPHS (1 of 14)



Figure 5.1. Front View of Test Vehicle

5.0 PHOTOGRAPHS (2 of 14)



Figure 5.2. Rear View of Test Vehicle

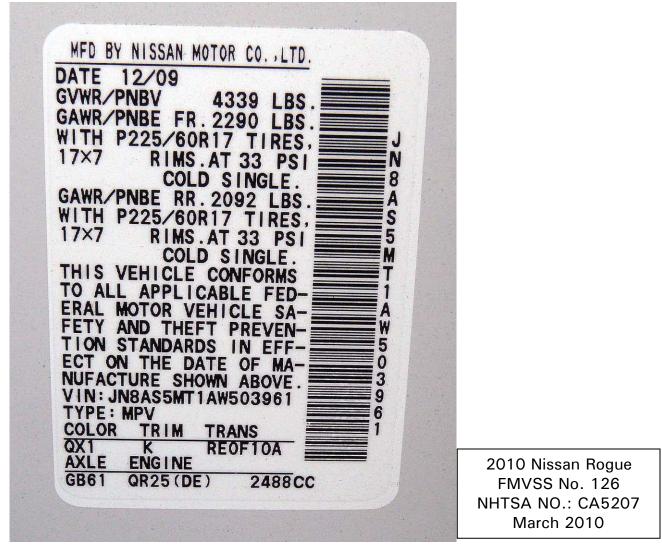


Figure 5.3. Vehicle Certification Label

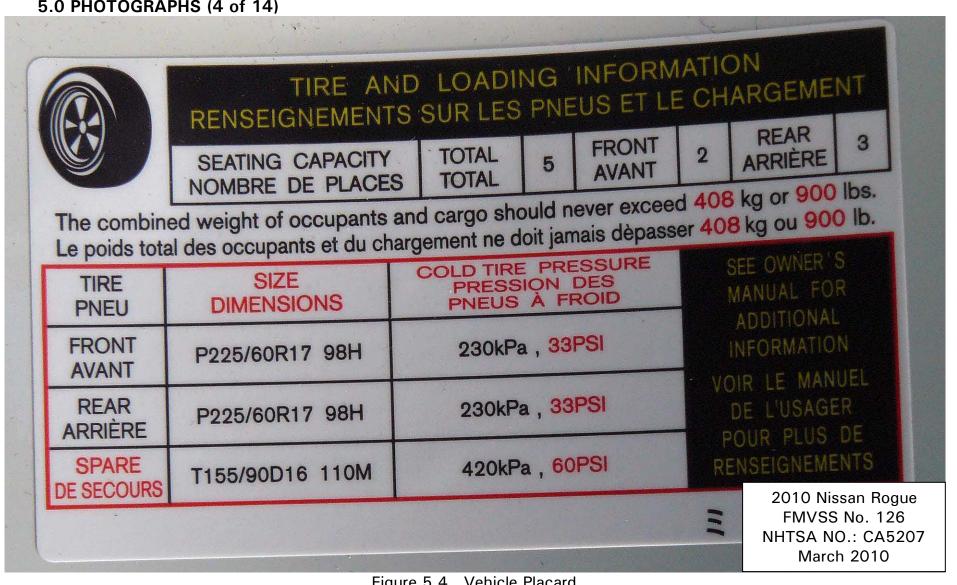


Figure 5.4. Vehicle Placard

5.0 PHOTOGRAPHS (5 of 14)

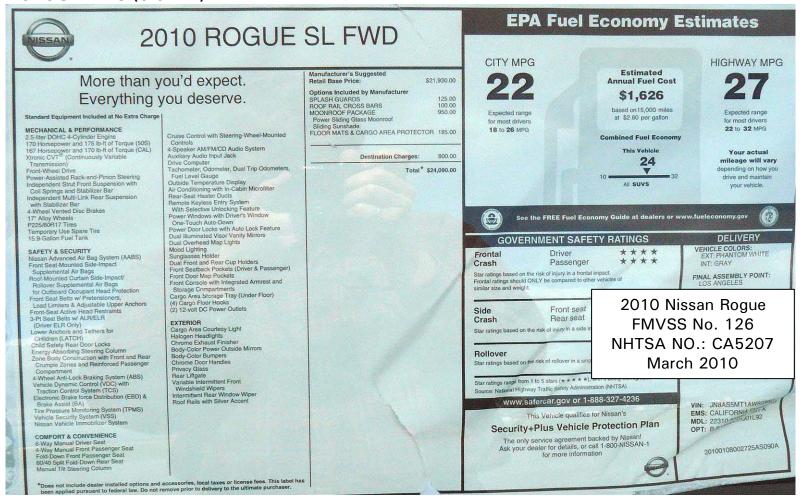


Figure 5.5. Window Sticker (Monroney Label)

5.0 PHOTOGRAPHS (6 of 14)



Figure 5.6. Telltale for ESC Malfunction and ESC Off

5.0 PHOTOGRAPHS (7 of 14)



Figure 5.7. ESC Off Control Switch

5.0 PHOTOGRAPHS (8 of 14)



Figure 5.8. Front View of Vehicle As-Tested

5.0 PHOTOGRAPHS (9 of 14)



Figure 5.9. Rear View of Vehicle As-Tested

5.0 PHOTOGRAPHS (10 of 14)

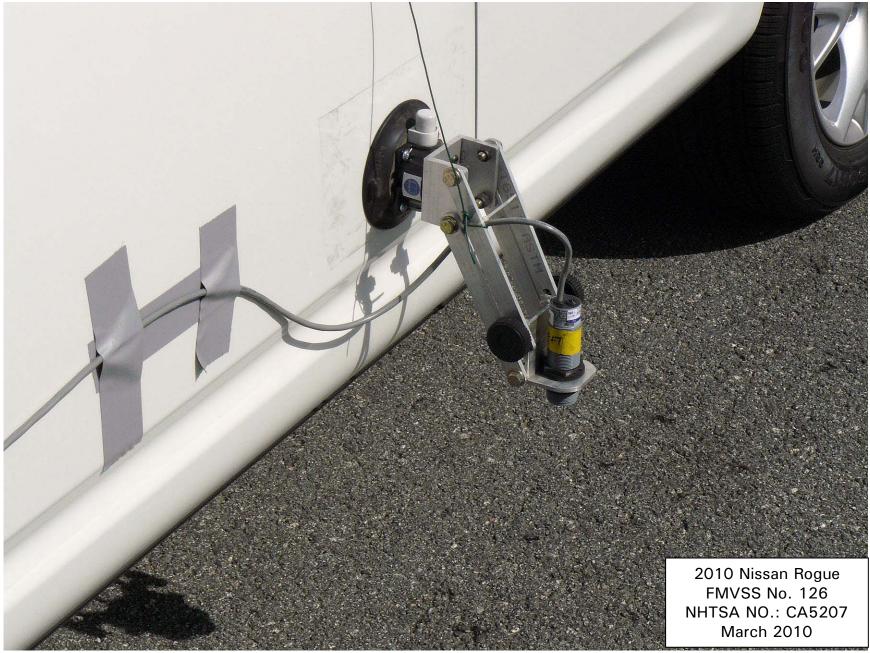


Figure 5.10. Ultrasonic Height Sensor Mounted on Left Side of Vehicle for Determining Body Roll Angle

5.0 PHOTOGRAPHS (11 of 14)



Figure 5.11. Rear Outrigger, Mount and Speed Sensor

5.0 PHOTOGRAPHS (12 of 14)

2010 Nissan Rogue FMVSS No. 126 NHTSA NO.: CA5207 March 2010 Figure 5.12. Steering Controller and Data Acquisition Computer

5.0 PHOTOGRAPHS (13 of 14)



Figure 5.13. Inertial Measurement Unit Mounted in Vehicle

5.0 PHOTOGRAPHS (14 of 14)

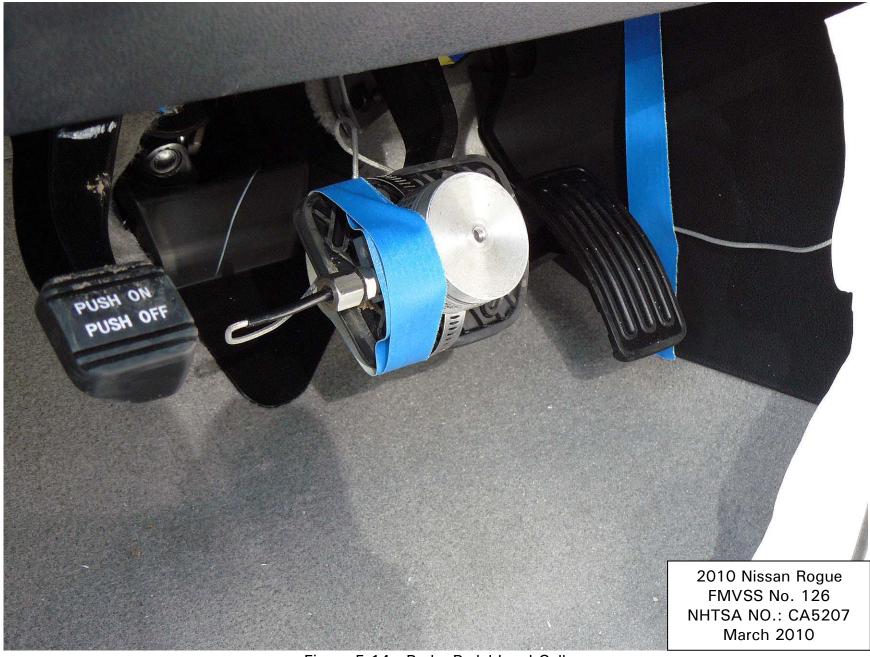


Figure 5.14. Brake Pedal Load Cell

6.0 DATA PLOTS (1 of 4)

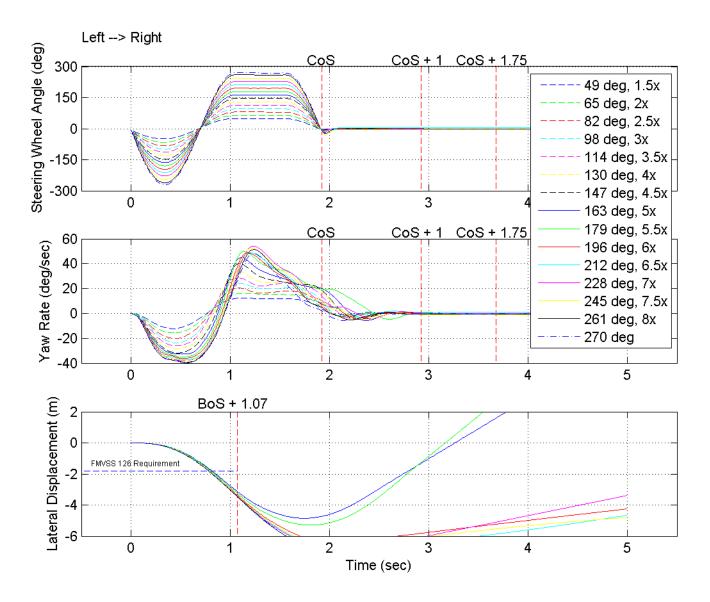


Figure 6.1. Steering Wheel Angle, Yaw Rate and Lateral Displacement for L-R Series

6.0 DATA PLOTS (2 of 4)

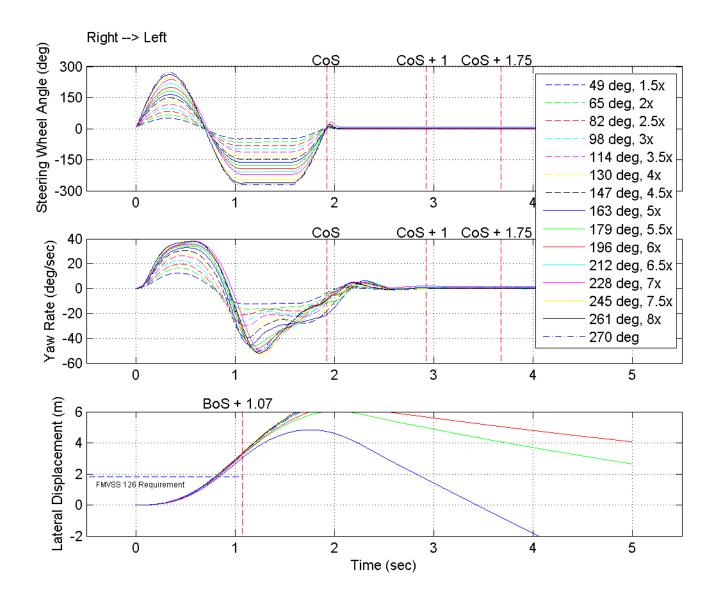


Figure 6.2. Steering Wheel Angle, Yaw Rate and Lateral Displacement for R-L Series

6.0 DATA PLOTS (3 of 4)

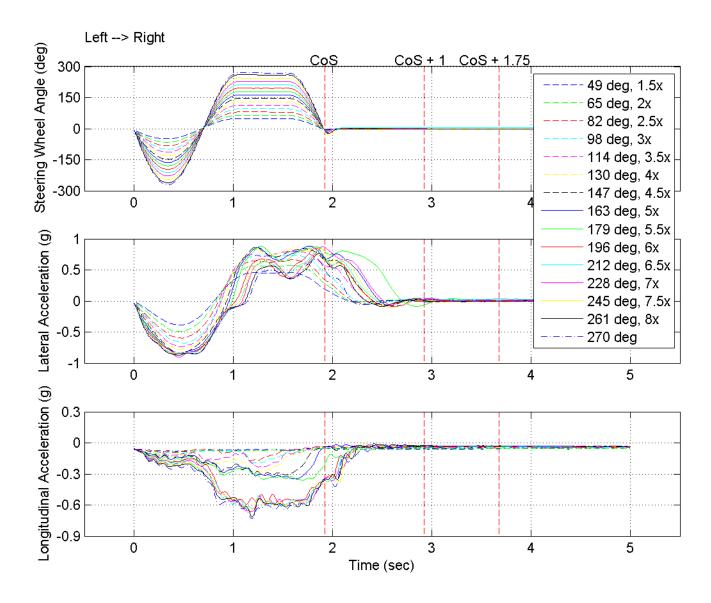


Figure 6.3. Steering Wheel Angle, Lateral Acceleration and Longitudinal Acceleration for L-R Series

6.0 DATA PLOTS (4 of 4)

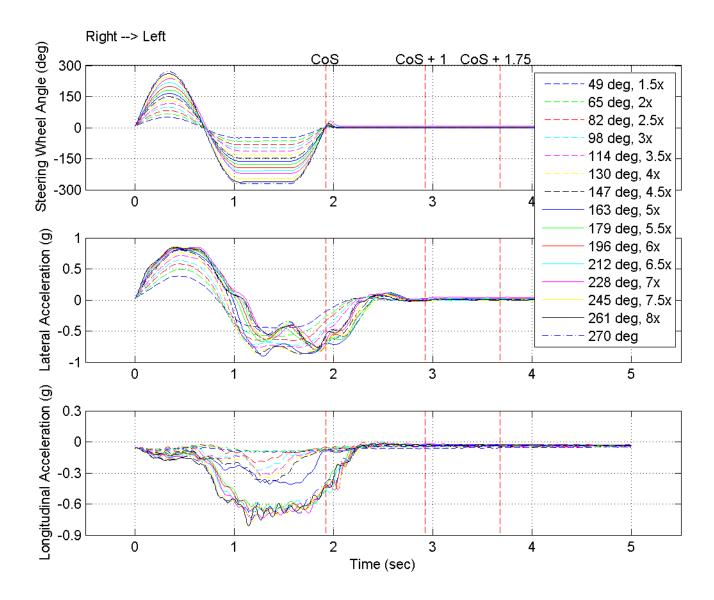
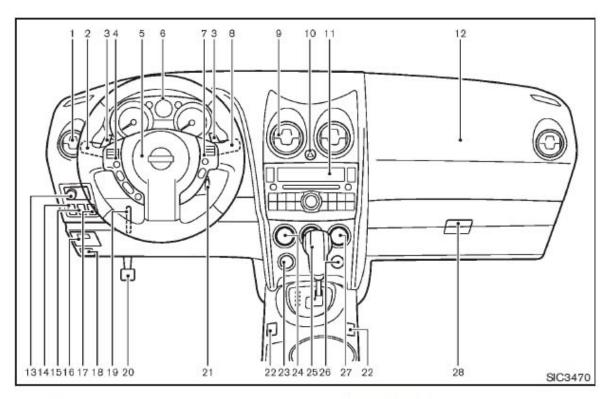


Figure 6.4. Steering Wheel Angle, Lateral Acceleration and Longitudinal Acceleration for R-L Series

7.0 OTHER DOCUMENTATION

- 7.1 OWNER'S MANUAL PAGES
- 7.2 VEHICLE ARRIVAL CONDITION REPORT
- 7.3 VEHICLE COMPLETION CONDITION REPORT
- 7.4 SINE WITH DWELL TEST RESULTS
- 7.5 SLOWLY INCREASING STEER TEST RESULTS
- 7.6 INERTIAL SENSING SYSTEM LOCATION COORDINATES

INSTRUMENT PANEL



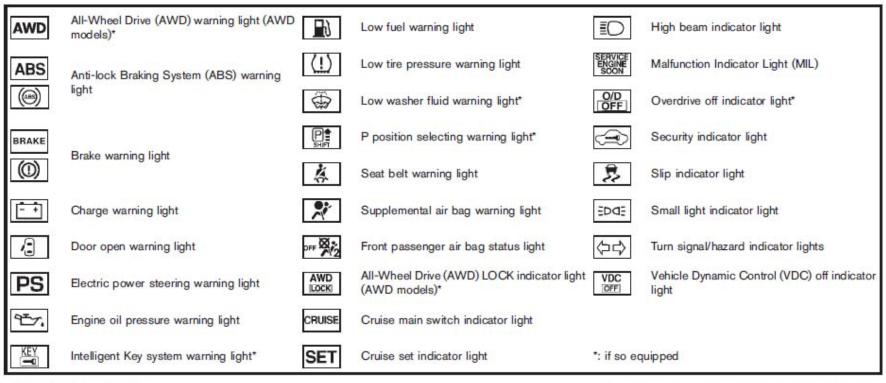
- 1. Side ventilator
- Headlight, fog light (if so equipped) and turn signal switch
- 3. Paddle shifter (if so equipped)

2-2 Instruments and controls

- 4. Steering-wheel-mounted controls (left side)
 - Audio control
 - Bluetooth® Hands-Free Phone system control
- Steering wheel
 - Horn
 - Driver supplemental air bag
- 6. Meters and gauges
- 7. Steering-wheel-mounted controls (right side)
 - Cruise control switches
- 8. Wiper and washer switch

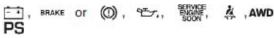
- 9. Center ventilator
- 10. Hazard warning flasher switch
- 11. Audio system
 - Clock
- 12. Front passenger supplemental air bag
- 13. Outside remote mirror control switch
- 14. Headlight aiming control (if so equipped)
- All-Wheel Drive (AWD) LOCK switch (if so equipped)
- 16. Fuse box cover
- 17. Vehicle Dynamic Control (VDC) OFF switch
- 18. Hood release handle
- 19. Tilting steering wheel lever
- 20. Parking brake
- 21. Ignition switch
- 22. Heated seat switch (if so equipped)
- 23. Power outlet
- 24. Heater/air conditioner control
- 25. Selector lever
- 26. Front passenger air bag status light
- Rear window and outside mirror (if so equipped) defroster switch
- 28. Glove box

WARNING/INDICATOR LIGHTS AND AUDIBLE REMINDERS



CHECKING BULBS

With all doors closed, apply the parking brake and turn the ignition switch to the ON position without starting the engine. The following lights will come on:



The following lights come on briefly and then go off (if so equipped):



If any light does not come on, it may indicate a burned-out bulb or an open circuit in the electrical system. Have the system checked by a NISSAN dealer.

Instruments and controls 2-11



Security indicator light

The light blinks when the ignition switch is in the ACC. OFF or LOCK position. This function indicates the security system equipped on the vehicle is operational.

If the security system is malfunctioning, this light will remain on while the ignition switch is in the ON position. For additional information, see "SECURITY SYSTEMS" later in this section.



Slip indicator light

The light will blink when the Vehicle Dynamic Control (VDC) system is operating, thus alerting the driver to the fact that the road surface may be slippery and the vehicle is nearing its traction limits.



EDGE Small light indicator light

The light illuminates when the headlight switch is turned to the EDGE position.



The light flashes when the turn signal switch lever or hazard switch is turned on.

2-18 Instruments and controls

VDC Vehicle Dynamic Control (VDC) off indicator light

The light illuminates when the Vehicle Dynamic Control (VDC) off switch is pushed to OFF. This indicates that the VDC system is not operating. When the VDC off indicator light and slip indicator light illuminate with the VDC system turned on, this light alerts the driver to the fact that the VDC system's fail-safe mode is operating, for example the VDC system may not be functioning properly. Have the system checked by a NISSAN dealer. If a malfunction occurs in the system, the VDC system function will be canceled but the vehicle is still driveable. For additional information, see "VEHICLE DYNAMIC CONTROL (VDC) SYSTEM" in the "5. Starting and driving" section of this manual.

AUDIBLE REMINDERS

Key reminder chime

The key reminder chime sounds if the driver's side door is opened while the key is left in the ignition switch and the ignition switch is in the ACC, OFF or LOCK position. Remove the key and take it with you when leaving the vehicle.

Light reminder chime

The light reminder chime will sound when the driver side door is opened with the light switch in the EDGE or (D) position, and the ignition switch is in the ACC, OFF or LOCK position.

Turn the light switch off when you leave the vehicle.

Brake pad wear warning

The disc brake pads have audible wear warnings. When a brake pad requires replacement, it will make a high pitched scraping sound when the vehicle is in motion. This scraping sound will first occur only when the brake pedal is depressed. After more wear of the brake pad, the sound will always be heard even if the brake pedal is not depressed. Have the brakes checked as soon as possible if the warning sound is heard.

Parking brake reminder chime

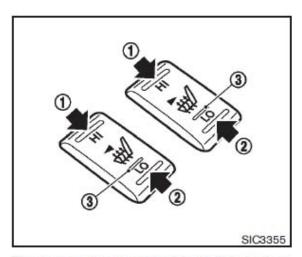
The parking brake reminder chime will sound if the vehicle is driven at more than 4 MPH (7 km/h) with the parking brake applied. Stop the vehicle and release the parking brake.

Seat belt warning chime

The seat belt warning chime will sound for about 6 seconds unless the driver's seat belt is securely fastened.

Intelligent Key door buzzer (if so equipped)

When the chime or buzzer sounds from inside and outside the vehicle, check for the following:



The front seats are warmed by built-in heaters. The switches located on the center console can be operated independently of each other.

- 1. Start the engine.
- Select heat range.
 - For high heat, push the HI (High) side of the switch.
 - (2) For low heat, push the LO (Low) side of the switch.

The indicator light in the switch ③ will illuminate when low or high is selected.

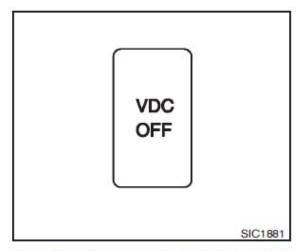
To turn off the heater, return the switch to the level position. Make sure the indicator

light goes off.

The heater is controlled by a thermostat, automatically turning the heater on and off. The indicator light will remain on as long as the switch is on.

When the vehicle's interior is warmed, or before you leave the vehicle, be sure to turn off the switch.

VEHICLE DYNAMIC CONTROL (VDC) OFF SWITCH



The vehicle should be driven with the Vehicle Dynamic Control (VDC) system on for most driving conditions.

If the vehicle is stuck in mud or snow, the VDC system reduces the engine output to reduce wheel spin. The engine speed will be reduced even if the accelerator is depressed to the floor. If maximum engine power is needed to free a stuck vehicle, turn the VDC system off.

To turn off the VDC system, push the VDC OFF switch. The one indicator will illuminate.

Push the VDC OFF switch again or restart the engine to turn on the system. (See "VEHICLE DYNAMIC CONTROL (VDC) SYSTEM" in the "5. Starting and driving" section.)

Instruments and controls 2-31

locking up. Steer the vehicle to avoid obstacles.



WARNING

Do not pump the brake pedal. Doing so may result in increased stopping distances.

Self-test feature

The ABS includes electronic sensors, electric pumps, hydraulic solenoids and a computer. The computer has a built-in diagnostic feature that tests the system each time you start the engine and move the vehicle at a low speed in forward or reverse. When the self-test occurs, you may hear a "clunk" noise and/or feel a pulsation in the brake pedal. This is normal and does not indicate a malfunction. If the computer senses a malfunction, it switches the ABS off and illuminates the ABS warning light on the instrument panel. The brake system then operates normally, but without anti-lock assistance.

If the ABS warning light illuminates during the self-test or while driving, have the vehicle checked by a NISSAN dealer.

Normal operation

The ABS operates at speeds above 3 to 6 MPH (5 to 10 km/h). The speed varies according to road conditions.

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When the ABS senses that one or more wheels are close to locking up, the actuator rapidly applies and releases hydraulic pressure. This action is similar to pumping the brakes very quickly. You may feel a pulsation in the brake pedal and hear a noise from under the hood or feel a vibration from the actuator when it is operating. This is normal and indicates that the ABS is operating properly. However, the pulsation may indicate that road conditions are hazardous and extra care is required while driving.

VEHICLE DYNAMIC CONTROL (VDC) SYSTEM

When accelerating or driving on slippery surfaces, the tires may spin or slide. With the Vehicle Dynamic Control (VDC) system, sensors detect these movements and control the braking and engine output to help improve vehicle stability.

- When the VDC system is operating, the "SLIP" indicator in the instrument panel blinks.
- If the "SLIP" indicator blinks, the road conditions are slippery. Be sure to adjust your speed and driving to these conditions. Be sure to drive carefully. (See "Slip indicator light" in the "2. Instruments and controls" section, and "Vehicle Dynamic Control (VDC) off indicator light" in the "2. Instruments and controls" section.)
- Indicator light

If a malfunction occurs in the system, the "SLIP" and "VDC OFF" indicator lights illuminate in the instrument panel. As long as these indicators are illuminated, the VDC system function is canceled.

The VDC system uses an Active Brake Limited Slip (ABLS) function to improve vehicle traction. The ABLS system works when one of the driving wheels is spinning on a slippery surface. The ABLS system brakes the spinning wheel, which distributes the driving power to the other drive

wheel. If the vehicle is operated with the VDC OFF switch pushed and the VDC system turned off, all VDC systems will be turned off. The ABLS system and ABS will still operate with the VDC system off. If the ABLS system is activated, the "SLIP" indicator will blink and you may hear a clunk noise and/or feel a pulsation in the brake pedal. This is normal and is not an indication of a malfunction.

While the VDC system is operating, you may feel a pulsation in the brake pedal and hear a noise or feel a vibration from under the hood. This is normal and indicates that the VDC system is working properly.

The VDC system computer has a built-in diagnostic feature that tests the system each time you start the engine and move the vehicle at a low speed forward or backward. When the self-test occurs, you may hear a "clunk" noise and/or feel a pulsation in the brake pedal. This is normal and is not an indication of a malfunction.

A

WARNING

 The VDC system is designed to help improve driving stability but does not prevent accidents due to abrupt steering operation at high speeds or due to careless or dangerous driving techniques. Reduce vehicle

- speed and be especially careful when driving and cornering on slippery surfaces and always drive carefully.
- Do not modify the vehicle's suspension. If suspension parts such as shock absorbers, struts, springs, stabilizer bars and bushings and wheels are not NISSAN approved or are extremely deteriorated the VDC system may not operate properly. This could adversely affect vehicle handling performance, and the "VDC OFF" indicator or "SLIP" indicator or both indicator lights may illuminate.
- If brake related parts such as brake pads, rotors and calipers are not standard equipment or are extremely deteriorated, the "VDC OFF" indicator or "SLIP" indicator or both indicator lights may illuminate.
- If engine related parts such as muffler are not standard equipment or are extremely deteriorated, the "VDC OFF" indicator or "SUP" indicator or both indicator lights may illuminate.

- When driving on extremely inclined surfaces such as higher banked corners, the VDC system may not operate properly and the "VDC OFF" indicator or "SLIP" indicator or both indicator lights may illuminate. Do not drive on these types of roads.
- When driving on unstable surfaces such as a turntable, ferry, elevator or ramp, the "VDC OFF" indicator or "SLIP" indicator or both indicator lights may illuminate. This is not a malfunction. Restart the engine after driving onto a stable surface.
- If wheels or tires other than those recommended are used, the VDC system may not operate properly and "VDC OFF" indicator or "SLIP" indicator or both indicator lights may illuminate.
- The VDC system is not a substitute for winter tires or tire chains on a snow covered road.

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hooks.

- Always pull the cable straight out from the front of the vehicle. Never pull on the vehicle at an angle.
- Pulling devices should be routed so they do not touch any part of the suspension, steering, brake or cooling systems.
- Pulling devices such as ropes or canvas straps are not recommended for use in vehicle towing or recovery.

Rocking a stuck vehicle

If your vehicle is stuck in sand, snow, mud, etc., use the following procedure:

- Turn off the Vehicle Dynamic Control (VDC) system.
- Make sure the area in front and behind the vehicle is clear of obstructions.
- Turn the steering wheel right and left to clear an area around the front tires.
- Slowly rock the vehicle forward and backward.
 - Shift back and forth between R (Reverse) and D (Drive).

- Apply the accelerator as little as possible to maintain the rocking motion.
- Release the accelerator pedal before shifting between R and D.
- Do not spin the tires above 35 MPH (55 km/h).
- If the vehicle cannot be freed after a few tries, contact a professional towing service to remove the vehicle.

In case of emergency 6-17

7.2 VEHICLE ARRIVAL CONDITION REPORT

CONTRACT NO.: DTNH22-08-D-00098 DATE: From: Automotive Allies Purpose X Initial Receipt Received via Transfer Present Vehicle Condition To: Dynamic Research, Inc. Vehicle VIN: JN8AS5MT1AW503961 NHTSA NO.: CA5207 Model Year: 2010 Odometer Reading: 5 Miles Make Body Style: MPV Nissan Model: Body Color: White Rogue Manufacture Date: Dealer: Automotive Allies 12/09 1968/4339 GVWR (kg/lb) Price: Leased | All options listed on the "Window Sticker" are present on the test vehicle Tires and wheel rims are new and the same as listed There are no dents or other interior or exterior flaws The vehicle has been properly prepared and is in running condition The glove box contains an owner's manual, warranty document, consumer information, and extra set of keys Roper fuel filler cap is supplied on the test vehicle Place vehicle in storage area INSPECT THE VEHICLE'S INTERIOR and exterior, including all windows, seats, doors, etc., to confirm that each system is complete and functional per the manufacturer's specifications. Any damage, misadjustment, or other unusual condition that could influence the test program or test results shall be recorded. Report any abnormal condition to the NHTSA COTR before beginning any test. NOTES: *No extra key* RECORDED BY: J Lenkeit DATE RECORDED: 2/19/2010

DATE APPROVED: 2/22/2010

APPROVED BY:

B Kebschull

7.3 VEHICLE COMPLETION CONDITION REPORT

CONTRACT NO.: <u>DTNH22-08-D-0</u> DATE: <u>3/24/2010</u>	00098
Vehicle VIN: JN8AS5MT1AW5	503961 NHTSA NO.: <i>CA5207</i>
Model Year: 2010	Odometer Reading: <u>149</u> Miles
Make: <u>Nissan</u>	Body Style: MPV
Model: Rogue	Body Color: White
Manufacture Date: 12/09	Dealer:
GVWR (kg/lb) <u>1968 (4339)</u>	Price: <u>Leased</u>
LIST OF FMVSS TESTS PERFORME	D BY THIS LAB:
☑ THERE ARE NO DENTS OR	OTHER INTERIOR OR EXTERIOR FLAWS
	ROPERLY MAINTAINED AND IS IN RUNNING
	S AN OWNER'S MANUAL, WARRANTY NFORMATION, AND EXTRA SET OF KEYS
☑ PROPER FUEL FILLER CAP I REMARKS:	S SUPPLIED ON THE TEST VEHICLE
Equipment that is no longer on the condition Report:	test vehicle as noted on Vehicle Arrival
Explanation for equipment removal:	
Test Vehicle Condition:	
As delivered, as new	
RECORDED BY: J Lenkeit	DATE RECORDED: <u>3/24/2010</u>
APPROVED BY: P Broen	DATE APPROVED: 3/23/2010

7.4 SINE WITH DWELL TEST RESULTS

2010 Nissan Rogue MPV

NHTSA No.: <u>CA5207</u>
Date of Test: <u>3/4/2010</u>
Date Created: <u>3/4/2010</u>

Lateral Stability Test Series No. 1 - Counterclockwise Initial Steer Direction

File	SWA @ 5deg Ct	MES	Time @ 5deg	cos	Time @ COS	MO S	Time @ MOS	YRR1	YR1	YRR 1 Ct	YRR 175	YR175	YRR17 5 Ct	2nd Yaw Peak	2nd Yaw Peak Ct	Lat Disp	Lat. Acc. 1.07 s	1st SWA Peak	1st SWA Peak Ct	2nd SWA Mean
	(deg)	(mph)	(s)		(s)		(sec)	(%)	(deg/s)		(%)	(deg/s)		(deg/s)		(ft)	(g)	(deg)		(deg)
23	710	50.28	3.542	1091	5.447	847	4.227	-0.29	-0.04	1291	-0.75	-0.09	1441	12.31	939	-3.87	0.39	49.0	775	48.96
24	709	50.19	3.536	1091	5.447	847	4.226	-0.26	-0.04	1291	-1.19	-0.19	1441	15.87	934	-5.15	0.47	64.8	775	64.84
25	708	50.31	3.531	1091	5.446	847	4.226	-0.9	-0.18	1291	-0.72	-0.15	1441	20.6	926	-6.28	0.55	81.8	775	81.9
26	707	50.36	3.528	1090	5.445	847	4.226	-0.97	-0.24	1290	-0.53	-0.13	1440	24.27	927	-7.31	0.58	97.7	775	97.81
27	707	50.13	3.526	1090	5.443	846	4.225	-0.67	-0.19	1290	-0.33	-0.09	1440	28.46	922	-8.14	0.61	113.6	775	113.69
28	706	50.28	3.524	1090	5.443	846	4.225	-0.59	-0.2	1290	-0.2	-0.07	1440	33.85	922	-8.89	0.62	129.7	775	129.66
29	706	50.21	3.524	1090	5.443	847	4.226	-0.24	-0.1	1290	0.03	0.01	1440	40.19	925	-9.54	0.6	146.8	775	146.62
30	706	50.1	3.523	1090	5.442	846	4.225	0.62	0.28	1290	0.08	0.04	1440	44.88	930	-10.15	0.53	162.8	775	162.54
31	706	50.18	3.523	1090	5.444	847	4.226	2.08	1.04	1290	-0.26	-0.13	1440	49.86	935	-10.5	0.41	178.9	775	178.48
32	706	50.25	3.522	1090	5.441	846	4.225	-0.52	-0.25	1290	-0.24	-0.11	1440	48.55	942	-10.84	0.1	195.9	775	195.47
33	706	50.11	3.523	1090	5.441	847	4.227	1.32	0.64	1290	1.55	0.76	1440	48.86	947	-11	0	211.9	775	211.46
34	706	50.14	3.523	1090	5.441	847	4.226	0.38	0.2	1290	0.1	0.05	1440	54.04	954	-11.11	-0.07	228.1	775	227.55
35	706	50.34	3.523	1090	5.441	847	4.226	-1.79	-0.94	1290	-1.71	-0.9	1440	52.44	950	-10.99	-0.01	245.0	775	244.53
36	706	50.22	3.524	1090	5.443	847	4.227	-1.07	-0.55	1290	-0.77	-0.39	1440	51.49	955	-11.21	-0.08	261.0	775	260.48
37	706	50.24	3.523	1090	5.443	847	4.227	-0.3	-0.15	1290	-0.14	-0.07	1440	48.42	954	-11.11	-0.07	270.0	775	269.48

7.4 SINE WITH DWELL TEST RESULTS

2010 Nissan Rogue MPV

NHTSA No.: <u>CA5207</u>
Date of Test: <u>3/4/2010</u>
Date Created: <u>3/4/2010</u>

Lateral Stability Test Series No. 2 - Clockwise Initial Steer Direction

File	SWA @ 5deg Ct	MES	Time @ 5deg	cos	Time @ COS	MO S	Time @ MOS	YRR1	YR1	YRR 1 Ct	YRR 175	YR175	YRR17 5 Ct	2nd Yaw Peak	2nd Yaw Peak Ct	Lat Disp	Lat. Acc. 1.07 s	1st SWA Peak	1st SWA Peak Ct	2nd SWA Mean
	(deg)	(mph)	(s)		(s)		(sec)	(%)	(deg/s)		(%)	(deg/s)		(deg/s)		(ft)	(g)	(deg)		(deg)
38	710	50.33	3.541	1091	5.447	847	4.227	-0.33	0.04	1291	0.28	-0.03	1441	-12.4	935	3.98	-0.37	49.7	775	49.54
39	708	50.2	3.535	1091	5.446	847	4.227	-0.8	0.13	1291	0.14	-0.02	1441	-16.51	936	5.1	-0.45	65.7	775	65.41
40	707	50.23	3.53	1090	5.445	847	4.226	-0.61	0.13	1290	-0.36	0.08	1440	-21.02	928	6.19	-0.52	82.6	775	82.33
41	707	50.14	3.528	1091	5.446	847	4.226	-0.76	0.2	1291	-0.41	0.11	1441	-25.9	927	7.07	-0.57	98.5	775	98.36
42	707	50.14	3.527	1091	5.446	849	4.236	-1.83	0.55	1291	-1.33	0.4	1441	-29.73	928	8.01	-0.55	115.8	777	112.77
43	706	50.32	3.523	1090	5.443	846	4.225	0.07	-0.03	1290	-0.22	0.08	1440	-35.18	929	8.56	-0.6	130.4	775	130.37
44	706	50.42	3.523	1091	5.446	848	4.234	-0.85	0.34	1291	-0.56	0.22	1441	-39.9	930	9.26	-0.52	148.8	776	145.94
45	707	50.09	3.528	1091	5.449	849	4.24	-0.74	0.33	1291	-0.67	0.3	1441	-45.11	938	9.8	-0.36	165.2	777	161.53
48	707	50.36	3.529	1091	5.448	850	4.241	-1.38	0.64	1291	-1.03	0.48	1441	-46.19	944	10.36	-0.15	181.9	778	176.92
49	706	50.32	3.522	1090	5.444	849	4.236	-1.07	0.53	1290	-0.8	0.39	1440	-49.04	947	10.47	-0.06	198.5	776	194.25
51	707	50.23	3.526	1091	5.446	850	4.245	-2.28	1.14	1291	-2.02	1.01	1441	-49.71	955	10.68	0.02	217.9	778	206.82
52	707	50.04	3.526	1092	5.453	853	4.259	-3.76	1.91	1292	-3.18	1.61	1442	-50.79	962	10.58	0.1	237.8	780	219.13
54	706	50.14	3.522	1089	5.439	847	4.226	-0.47	0.25	1289	-0.14	0.08	1439	-52.79	958	10.97	0.05	245.7	775	245.19
55	706	50.24	3.522	1090	5.441	847	4.226	-0.54	0.28	1290	-0.12	0.06	1440	-51.99	955	10.78	0.04	261.6	775	261.17
56	706	50.14	3.522	1090	5.442	847	4.227	-0.32	0.16	1290	-0.01	0.01	1440	-51.07	950	10.7	0.02	270.6	775	270.13

7.5 SLOWLY INCREASING STEER TEST RESULTS

2010 Nissan Rogue MPV NHTSA No.: <u>CA5207</u> Date of Test: <u>3/4/2010</u> Date Created: <u>3/4/2010</u>

File	EventPt	DOS	MES	Mean SPD	AYcount_3	THETAENCF_3	AYCG_CD2_3	r_squared	ZeroBegin	ZeroEnd
			(mph)	(mph)		(deg)	(g)			
11	716	1	49.531	49.4767	1190	-32.5985	-0.30727	0.996907	516	716
12	700	1	50.138	50.38277	1195	-32.8666	-0.29673	0.994882	500	700
13	637	1	49.272	50.47689	1185	-32.3636	-0.30574	0.998168	437	637
14	716	0	49.421	50.14148	1181	32.24218	0.310336	0.990134	516	716
15	700	0	50.116	50.01676	1187	32.69659	0.308198	0.982114	500	700
17	695	0	50.157	50.28188	1190	32.8555	0.296305	0.994742	495	695

Averages 32.6 0.304096

Scalars	Steering Angles
	(deg)
1.5	49
2.0	65
2.5	82
3.0	98
3.5	114
4.0	130
4.5	147
5.0	163

Scalars	Steering Angles (deg)
5.5	179
6.0	196
6.5	212
7.0	228
7.5	245
8.0	261
-	270

7.6 INERTIAL SENSING SYSTEM LOCATION COORDINATES

Vehicle:2010 Nissan Rogue MPVNHTSA No.:CA5207Wheelbase:105.9 InchesFaro Arm S/N: U08-05-08-06636

Measurement date: 2/26/2010 Certification date: 8/18/2009

CMM Measurements

Coordinate system: SAE (X,Y,Z positive forward, to the right, and downward, respectively)

Origin defined at 48" point on lateral arm of measurement fixture, projected onto the ground plane

	Ref X	Ref Y	Ref Z
M_PLANE001_Ground_Plane	-	-	0.000
M_Line_Y_Axis	-1.537	-3.928	0.000
M_Point_48_Ref	0.000	0.000	-
M_CIRCLE001_I_Left_Rear_Wheel_Axle	-38.530	13.625	-13.332
M_Point_IMU_side	1.342	46.182	-21.357
M_Point_ROOF	-	-	-64.862
Motion Pak reference point taken from mid height of unit left side			
Motion Pak Width = 3.05" ==> 1/2 W = 1.525			
Motion_PAK_Location	1.342	47.707	-21.357

Measurement Notes

- 1. The Faro arm is positioned just to the left of the vehicle, near the rear door.
- 2. A "centerline jig" is used in the Faro arm measurement. The jig consists of a long beam with a 4 ft lateral arm that is perpendicular to the beam. The jig is placed on the ground underneath the vehicle with the long beam positioned along the centerline of the vehicle, such that the lateral arm extends to the left, slightly forward of the left rear tire. The lateral arm has a marked indentation point which is located 48.00" from the edge of the centerline beam.
- 3. The Faro arm is used to make the following measurements:
 - Three points on the ground, which establishes the ground plane.
 - Two points along the lateral arm, and projected onto the ground plane. This establishes the y axis.
 - One point at the 48 inch reference point on the lateral arm. This establishes the origin.
 - Three points on the left rear wheel or wheel cover. The Faro arm then computes the center point of the wheel.
 - One point to establish the height of the highest point on the roof of the vehicle.

Coordinate Measurements Calculated for S7D (Matlab Program)

Coordinate system: X,Y,Z positive rearward, to the right, and upward, respectively

Origin defined as follows: X axis: front axle, Y axis: vehicle centerline, Z axis: ground plane

	Ref X	Ref Y	Ref Z
Motion_PAK_Location in S7D (Matlab program) coordinate system	66.028	-0.293	21.357

Calculation Notes:

- 1. X axis value is the difference between the wheelbase and the calculated distance from the rear axle centerline to the IMU (the value must be positive and less than the wheelbase).
- 2. Y axis value is -48.00 (the Y axis offset of the measurement origin in the S7D coordinate system) plus the measured Y axis value (a negative value indicates the IMU is to the left of the vehicle centerline, and a positive value indicates it is to the right)
- 3. Z axis value is from the ground plane up to the center of the IMU (value must be positive).