126-DRI-10-001 **SAFETY COMPLIANCE TESTING FOR FMVSS 126 Electronic Stability Control Systems**

Nissan Motor Co., Ltd. 2010 Nissan Altima NHTSA No. CA5206

DYNAMIC RESEARCH, INC.

355 Van Ness Avenue, STE 200 Torrance, California 90501



March 24, 2010

Final Report

Prepared Under Contract No.: DTNH22-08-D-00098

U. S. DEPARTMENT OF TRANSPORTATION **National Highway Traffic Safety Administration Enforcement** Office of Vehicle Safety Compliance 1200 New Jersey Avenue, SE West Building, 4th Floor (NVS-221) Washington, DC 20590

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		Email: tis@nhtsa.dot.gov FAX: (202) 493-2833	
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1.0 PURPOSE OF COMPLIANCE TEST

The purpose of this test is to determine if the test vehicle, a 2010 Nissan Altima, meets the minimum equipment and performance requirements stated in Federal Motor Vehicle Safety Standard (FMVSS) 126, "Electronic Stability Control Systems."

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS

Testing of the 2010 Nissan Altima was conducted at Dynamic Research, Inc (DRI) in accordance with NHTSA TP-126-02, dated November 19, 2008.

The vehicle was inspected to ensure it was equipped with an ESC system that:

- Augments vehicle directional stability by applying and adjusting brake torques individually at each wheel to induce a correcting yaw moment to a vehicle;
- Is computer controlled with the computer using a closed-loop algorithm to limit vehicle oversteer and to limit vehicle understeer;
- Has a means to determine the vehicle's yaw rate and to estimate its side slip or side slip derivative with respect to time;
- Has a means to monitor driver steering inputs;
- Has an algorithm to determine the need, and a means to modify engine torque, as necessary, to assist the driver in maintaining control of the vehicle; and
- Is operational over the full speed range of the vehicle (except at vehicle speeds less than 20 km/h (12.4 mph), when being driven in reverse, or during system initialization).

The vehicle was subjected to a 0.7 Hz sine with dwell steering maneuver to ensure that it would meet the stability and responsiveness requirements of the standard as follows:

 At 1.0 second after completion of a required sine with dwell steering input, the yaw rate of the vehicle must not exceed 35 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTINUED)

- At 1.75 seconds after completion of a required sine with dwell steering input, the yaw rate of the vehicle must not exceed 20 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).
- The lateral displacement of the vehicle center of gravity with respect to its initial straight path must be at least 1.83 m (6 feet) (for vehicles with a GVWR of 3,500kg (7,716 lb) or less) when computed 1.07 seconds after the Beginning of Steer (BOS) at the specified steering wheel angles.

System malfunction simulations were executed to verify vehicle could identify and indicate a malfunction.

The vehicle's ESC System appears to meet the performance and equipment requirements as required by FMVSS 126. The test results are summarized on the following summary sheet.

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTD)

Data Summary Sheet (Page 1 of 2)

Vehicle: 2010 Nissan Altima

NHTSA No. <u>CA5206</u> VIN: <u>1N4AL2AP3AN403449</u>

Vehicle Type: Passenger Car Manufacture Date: 9/09

Laboratory: Dynamic Research, Inc.

REQUIREMENTS: PASS/FAIL

ESC Equipment and Operational Characteristics (Data Sheet 2)

The vehicle is to be equipped with an ESC system that meets the equipment and operational characteristics requirements. (S126, S5.1, S5.6)

ESC Malfunction Telltale (Data Sheet 3)

Vehicle is equipped with a telltale that indicates one or more ESC system malfunctions. (S126, S5.3)

PASS

"ESC Off" and other System Controls and Telltale (Data Sheet 3,4)

Vehicle is equipped with an ESC off telltale indicating the vehicle has been put into a mode that renders the ESC system unable to satisfy the performance requirements of the standard, if such a mode exists. (S5.5.1)

If provided, off control and other system controls as well as the <u>PASS</u> ESC off telltale meets the operational requirements (S126, S5.4, S5.4.1,S5.4.2, S5.5.4, and S5.5.9)

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTD)

Data Summary Sheet (Page 2 of 2)

REQUIREMENTS:	PASS/FAIL
Vehicle Lateral Stability (Data Sheet 8) Yaw Rate Ratio at 1 second after COS is less than 35% of peak value. (S126, S5.2.1)	<u>PASS</u>
Yaw Rate Ratio at 1.75 seconds after COS is less than 20% of peak value. (S126, S5.2.2)	<u>PASS</u>
Vehicle Responsiveness (Data Sheet 8) Lateral displacement at 1.07 seconds after BOS is at least 1.83 m (6 feet) for vehicles with a GVWR of 3,500kg (7,716 lb) or less, and 1.52 m (5 feet) for vehicles with a GVWR greater than 3,500 Kg (7,716 lb). (S126, S5.2.3)	<u>PASS</u>
ESC Malfunction Warning (Data Sheet 9) Warning is provided to driver after malfunction occurrence. (S126. S5.3)	<u>PASS</u>
Malfunction telltale stayed illuminated as long as malfunction existed and must extinguish after malfunction was corrected. (S126, S5.3.7)	<u>PASS</u>

3.0 TEST DATA

Data Sheet 1 (Page 1 of 2)

	TEST VEH	HICLE INSPI	ECTION AND	TEST PREPA	RATION_
Vehicle:	2010 Nissa	n Altima Pas	ssenger Car		
NHTSA N	o. <u>CA52</u>	<u>206</u> I	Data sheet c	ompletion	<u>1/5/2010</u>
VIN <u>1</u> N	I4AL2AP3AN	<u>403449</u> I	Manufacture	Date: <u>9/0</u>	<u>9</u>
GVWR (k	g): <u>1941</u>	Front G	AWR (kg):	<u>1017</u> Rea	r GAWR (kg): <u>993</u>
Seating Po	ositions Fro	nt: <u>2</u>	Mid:	Rear: <u>3</u>	
Odometer	reading at ti	me of inspe	ction: <u>13</u>	3 miles (20.8 k	<u>m)</u>
DESIGNA	TED TIRE SIZ	E(S) FROM	VEHICLE LA	BELING:	
Fro	nt Axle: <u><i>P21</i>:</u>	5/60 R16	Rear Ax	de: <i>P215/60 R</i>	<u>16</u>
INSTALLE	D TIRE SIZE	S) ON VEHI	CLE (from ti	re sidewall)	
			Front A	<u> Axle</u>	Rear Axle
	Tire Manufa	acturer:	Contine	ental	<u>Continental</u>
	Tire	Model:	<u>ContiProC</u>	<u>Contact</u>	<u>ContiProContact</u>
	Tiı	re Size:	P215/60) R16	P215/60 R16
TIN	Left Front:	<u>A3X8 3W</u>	H 3609	Right Front:	A3X8 3WH 3609
	Left Rear:	<u>A3X8 3W</u>	H 3609	Right Rear:	A3X8 3WH 3609
	led tire sizes act COTR for			es? Yes	
DRIVE COI	NFIGURATION	(S):(mark all	that apply)		
X Two V	Wheel Drive (2	2WD) X	Front Whe	eel Drive	Rear Wheel Drive
All Wh	neel Drive (A\	ND)			
Four W	/heel Drive Au	tomatic - diff	erential no lo	cked full time (4	WD Automatic)
Four W	/heel Drive (Hi	gh Gear Lock	ed Differentia	al 4WD HGLD)	
Four W	heel Drive Lov	w Gear (4WD	Low)		
Other ((Describe)				

Data Sheet 1 (Page 2 of 2) TEST VEHICLE INSPECTION AND TEST PREPARATION

DRIVE CONFIGURATION	IS AND MODES	S: (ex. default, per	formance, off)
(For each of the vehicle	s drive configu	rations identify ava	ailable operating modes)
Drive Configuration: Mode:	FWD Standard		
Drive Configuration: Mode: Drive Configuration:			
Mode:			
VEHICLE STABILITY SY	STEMS (Check	applicable technol	ogies):
List other systems:			
X ESC	X Traction	n Control	Roll Stability Control
Active Suspension	n X Electron	nic Throttle Contro	Active Steering
ABS			
REMARKS:			
	Broen Lenkeit	DATE RECORE	

Data Sheet 2 (Page 1 of 2) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

Vehicle: 2010 Nissan Altima Pa	essenger Car	
NHTSA No <u>CA5206</u>	Data Sheet Completion Date: 1/28	<u>/2010</u>
ESC SYSTEM IDENTIFICATION Manufacturer/Model Bosch AB ESC SYSTEM HARDWARE (CI	heck applicable hardware)	
X Electronic Control UnitX Wheel Speed SensorsX Yaw Rate Sensor	 X Hydraulic Control Unit X Steering Angle Sensor X Lateral Acceleration Sensor 	
List other Components: Stople	-	
System is capable of generating List and describe Components: individual wheel brake systems,	g brake torque at each wheel ESC controller, master cylinder,	X Yes (Pass) No (Fail)
System is capable of determining List and describe Components:_		X Yes (Pass) No (Fail)
System is capable of monitoring List and describe Components:		X Yes (Pass) No (Fail)
_	Observer module block of control ed on yaw rate, steer angle, vehicle	X Yes (Pass) No (Fail)

Data Sheet 2 (Page 2 of 2) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

ESC OPERATIONAL	CHARACTERISTIC	S (continued)		
Method used to mod receives the engine t	ify torque: <u>The eng</u> orque command fr nd modifies the en	torque during ESC activ gine controller module om the gine torque by varying	_	X Yes (Pass) No (Fail)
System is capable of and higher	activation at spee	ds of 20 km/h (12.4 m	ph) _	X Yes (Pass) No (Fail)
Speed system becom	nes active: 2.	8 km/h	_	<u> </u>
System is capable of – acceleration – braking – coasting	– dur	the following driving ph ring activation of ABS o ction control		X Yes (Pass) No (Fail)
the forward driving o	tivation under mos lirection - at full (A ive and acceleratio	t critical conditions in BS-control) and partial n (including TCS), engin	<u>пе</u>	
Vehicle manufacture ESC mitigates unders		entation explaining hov	v the - -	X Yes (Pass) No (Fail)
	DA	TA INDICATES COMPLI	ANCE: _	X Yes (Pass) No (Fail)
REMARKS:				
RECORDED BY: APPROVED BY:	J Lenkeit B Kebschull	DATE RECORDED: DATE APPROVED:	<u>1/28/2</u> 1/28/2	

Data Sheet 3 (Page 1 of 2) ESC MALFUNCTION AND OFF TELLTALES

Vehicle: 2010 Nissan Altima Passenger Car				
NHTSA No. CA5206	Data sheet completion date: 1/5/2010			
ESC Malfunction Telltale				
Vehicle is equipped with malfuncti	ion telltale? <u>Yes</u>			
Telltale Location: Inside tachomet	er on left side of instrument cluster (See Figure			
<u>5.6)</u>				
Telltale Color: <u>Amber</u>				
Telltale symbol or abbreviation use	ed			
or ESC	Vehicle uses this symbol Vehicle uses this abbreviation X Neither symbol or abbreviation is used			
	make note of any message, symbol or			
abbreviation used.				
"VDC OFF" "SLIP"; both are con	tinuously illuminated to indicate failure			
Is telltale part of a common space? <u>No</u>				
Is telltale also used to indicate activation of the ESC system? Yes				
If yes explain telltale operation during ESC activation:				
"SLIP" indicator blinks				

Data Sheet 3 (Page 2 of 2) ESC MALFUNCTION AND OFF TELLTALES

"ESC OFF" Telltale (if prov	rided)		
Vehicle is equipped with "I	ESC OFF" tellta	le? <i>Yes</i>	
Is "ESC Off" telltale comb telltale? <u>No</u>	oined with "ESC	C Malfunction" telltale	utilizing a two part
Telltale Location: <u>Inside t</u> 5.6)	achometer on l	eft side of instrument	cluster (See Figure
Telltale Color: <u>Amber</u>			
Telltale symbol or abbrevia	ition used		
or ESC	OFF	Vehicle uses this Vehicle uses this Neither symbol of used	abbreviation
If different than identified ab used. "VDC OFF"; ambe		of any message, symb	ol or abbreviation
Is telltale part of a commo	n space? <i>No</i>		
DATA INDICATES COMPL (Vehicle is compliant if equ Remarks:		alfunction telltale)	
RECORDED BY: P Bro	en bschull	DATE RECORDED:	1/5/2010 1/6/2010

Data Sheet 4 (Page 1 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

Vehicle: 2010 Nis	ssan Altima	Passenger Car
NHTSA No. <u>CA52</u>		Data sheet completion date: <u>1/6/2010</u>
"ESC OFF" Contro	ols Identific	ation and Operational Check:
the ESC system of	or place the	a control or controls whose purpose is to deactivate ESC system in a mode or modes that may no ce requirements of the standard? X Yes No
Type of centre	l or	X Dedicated "ESC Off" Control
Type of contro controls provid		Multi-functional control with an "ESC Off" mode
(mark all that a	L	Other (describe)
Identify each conf	trol location	n, labeling and selectable modes.
First Control:	Location	On dashboard, left of steering wheel (Figure 5.7)
	Labeling	VDC OFF
	Modes	ESC off/on
Second Control:	Location	
	Labeling	
	Modes	
Identify standard o	r default dri	ve configuration FWD Standard
Verify standard or	default drive	e configuration selected X Yes No
		minate upon activation of the dedicated ESC off control or de on the multi-function control?
		X Yes No (Fail)
		tinguish when the ignition is cycled from "on" ("Run") to again to the "On" ("Run") position?
If no, describe how	v the "Off" co	X Yes No (Fail)

Data Sheet 4 (Page 2 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

If a multi-function control is provided, cycle through each mode setting on the control and record which modes illuminate the "ESC Off" telltale. Also, for those modes that illuminate the ESC Off" telltale identify if the telltale extinguishes upon cycling the ignition system.

		"ESC Off" telltale	"ESC Off" telltale
		illuminates upon	extinguishes
		activation of	upon cycling
Cont	rol Mode	control? (Yes/No)	ignition? (Yes/No)
TCS off (ESC on)		No	
ESC and TCS off		Yes	Yes
when the ignition	at illuminates the "ESC was cycled from "On"	· · · · · · · · · · · · · · · · · · ·	•
again to the "On"	(Run) position?		X Yes No
Other System Con	trols that have an ancil	lary effect on ESC Op	eration:
deactivate the ESC	oped with any ancillary C system or place the E he performance require	SC system in a mode	or modes that may
Ancillary Control:	System		
	Control Description		
	Labeling		
Ancillary Control:			
	Control Description		
	Labeling		
Ancillary Control:	System		
	Control Description		
	Labeling		
	= =====================================		

Data Sheet 4 (Page 3 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

Activate each control listed above and record whether the control illuminates the "ESC Off" telltale. Also, record warnings or messages provided regarding the ESC system.

	Control Activates "ESC Off"	
Ancillary Control	Telltale? (Yes/No)	Warnings or Messages Provided
None		

For those controls that illuminate the "ESC Off" telltale above identify if the "ESC Off" telltale extinguishes upon cycling the ignition system.

	"ESC Off" telltale extinguishes		
Ancillary Control	upon cycling ignition? (Yes/No)		

For each control that illuminates the "ESC Off" telltale, did the telltale extinguish when the ignition is cycled from "On" ("Run") to "Lock" or "Off" and then back again to the "On" ("Run") position? If activating the control places the vehicle into a low-range four-wheel drive configuration designed for low-speed, off-road driving, the ESC system may remain turned off after the ignition has been cycled off and then back on and therefore the "ESC Off" telltale may not extinguish.

off and then back	on and therefore the	e "ESC Off" telltale may i X	not ext Yes	inguish. No (Fail)
	DATA		CE:	PASS
Remarks:				
RECORDED BY:	B Kebschull	DATE RECORDED:	1/6/2	010
APPROVED BY:	J Lenkeit	DATE APPROVED:	1/10/	/2009

Data Sheet 5 (Page 1 of 3) TEST TRACK AND VEHICLE DATA

Vehicle: 2010 Nissan Altima Passenger Car NHTSA No. CA5206 Data sheet completion date: 1/6/2010 **Test Track Requirements:** Test surface slope (0-1%): 0.5% Peak Friction Coefficient (at least 0.9) 0.96 If no, explain: Test track data meets requirements: Yes **Full Fluid Levels:** Fuel Yes Other Yes Coolant Yes (specify) washer, power steering, brakes Tire Pressures: Required; Front Axle 220 KPA Rear Axle 220 KPA Actual; LF 220 KPA RF *220* **KPA** LR 220 KPA RR *220* KPA Vehicle Dimensions: Front Track Width 154.9 cm Wheelbase 267.5 cm Rear Track Width 155.4 cm GAWR Front 1017 KG **Vehicle Weight Ratings:** GAWR Rear 993 KG Unloaded Vehicle Weight (UVW): Front axle 862.7 KG Left Front *438.1* KG Right Front 424.6 KG Left Rear *291.7* KG KG Rear axle *577.9* KG Right Rear 286.2 Total UVW 1440.6 KG Baseline Weight and Outrigger Selection (only for MPVs, Trucks, Buses) Calculated baseline weight (UVW + 73kg) *1513.6* KG Outrigger size required ("Standard" or "Heavy") none Standard - Baseline weight under 2772 kg (6000 lb) Heavy - Baseline weight equal to or greater than 2772 kg (6000 lb)

Data Sheet 5 (Page 2 of 3) TEST TRACK AND VEHICLE DATA

UVW with Outriggers: (only for MPVs, Trucks, Buses)

Front axle
$$N/A$$
 KG Left Front N/A KG Right Front N/A KG Rear axle N/A KG Left Rear N/A KG Right Rear N/A KG Total UVW with outriggers N/A KG

Loaded Vehicle Weight w/Driver and Instrumentation (no Ballast)

Ballast Required =
$$[Total UVW with Outriggers (if applicable)]$$
 $+ 168 \times G$ $+ 168 \times G$ $- [Loaded Weight w/Driver and Instrumentation)]$ = $1440.6 \times G$ $+ 168 \times G$ $+ 168 \times G$ $+ 168 \times G$ $+ 168 \times G$

Total Loaded Vehicle Weight w/Driver and Instrumentation and Ballast

Data Sheet 5 (Page 3 of 3) TEST TRACK AND VEHICLE DATA

Center of Gravity and Inertial Sensing System Location at Loaded Vehicle Condition:

x-distance (longitudinal)

Point of reference is the front axle centerline.

(Positive from front axle toward rear of vehicle.)

y-distance (lateral)

Point of reference is the vehicle centerline.

(Positive from the center toward the right.)

z-distance (vertical)

Point of reference is the ground plane.

(Positive from the ground up.)

Locations:

	Center of Gravity			<u>Inertial</u>	Sensing System
x-distance	<i>43.3</i> in	<i>110.1</i> cm	_	66.9	in <u>170.0</u> cm
y-distance	<u>-0.7</u> in	<i>-1.7</i> cm	_	-0.6	in <u>-1.5</u> cm
z-distance	<u>21.9</u> in	<i>55.5</i> cm	_	<u>17.0</u>	in <u>43.1</u> cm
		Roof Height _	57.52	in	<u>146.1</u> cm
Distance between ultrasonic sensors			87.8	in	<i>223.0</i> cm

Remarks:

RECORDED BY: B Kebschull DATE RECORDED: 1/6/2010
APPROVED BY: J Lenkeit DATE APPROVED: 1/10/2101

Data Sheet 6 (Page 1 of 3) BRAKE AND TIRE CONDITIONING

Vehicle: 2010 Nissan Altima Passenger Car

NHTSA No. *CA5206*

Measured tire pressure: LF 220 KPA RF 220 KPA

LR <u>220</u> KPA RR <u>220</u> KPA

Wind Speed <u>1.5</u> m/s (10 m/sec (22 mph) max for passenger cars; 5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 7.1 °C

Brake Conditioning Time: 8:40:00 AM Date: 1/6/2010

56 km/h (35 mph) Brake Stops

Number of stops executed (10 required) 10 Stops

Observed deceleration rate range (.5g target) 0.45 - 0.55 g

72 km/h (45 mph) Brake Stops

Number of stops executed (3 required) 3 Stops

Number of stops ABS activated (3 required) $\underline{3}$ Stops

Observed deceleration rate range 0.9 - .095 g

72 km/h (45 mph) Brake Cool Down Period

Duration of cool down period (5 minutes min.) 5 Minutes

Data Sheet 6 (Page 2 of 3) BRAKE AND TIRE CONDITIONING

Tire Conditioning series No. 1 Time: 8:55:00 AM Date: 1/6/2010

Measured cold tire pressure LF 235 KPA RF 241 KPA

LR <u>230</u> KPA RR <u>230</u> KPA

Wind Speed ______ m/s (10 m/sec (22 mph) max for passenger cars;

5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 7.2°C

30 meter (100 ft) Diameter Circle Maneuver					
Test Run	Steering Target Lateral Observed Lateral Observed Vehicle Direction Acceleration (g) Acceleration (g) Speed (Km/h)				
1-3	Clockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 32.8 - 33.6</u>	
4-6	Counterclockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 32 - 33.6</u>	

	5-1 Hz Cycle Sinusoidal Steering Maneuver to Determine Steering Wheel Angle for 0.5-0.6 g Lateral Acceleration						
Test Run	Data File	Vehicle Speed Km/h(mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)		
1	2	56 ± 2 (35 ± 1)	<u>60</u>	0.5 - 0.6	<u>0.41</u>		
2	3	56 ± 2 (35 ± 1)	<u>80</u>	0.5 - 0.6	<u>0.54</u>		
3		56 ± 2 (35 ± 1)		0.5 - 0.6			
4		56 ± 2 (35 ± 1)		0.5 - 0.6			

Steering wheel angle that corresponds to a peak 0.5-0.6 g lateral acceleration: 80 degrees

	10-1 Hz Cycle Sinusoidal Steering Maneuver					
Test Run	Data File	Vehicle Speed Km/h (mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)	
1-3	<u>4-6</u>	56 ± 2 (35 ± 1)	80 (cycles 1-10)	0.5 - 0.6	<u>0.54</u>	
4	7	FC + 2 (2F + 1)	<u>80</u> (cycles 1-9)	0.5 - 0.6	<u>0.54</u>	
4 $\frac{7}{}$ 56 ± 2 (35 ± 1)	<u>160</u> (cycle10) *	NA	<u>0.85</u>			

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9

Data Sheet 6 (Page 3 of 3) BRAKE AND TIRE CONDITIONING

Tire Conditioning series No. 2 Time: 11:22:00 AM 1/6/2010 Date: Measured cold tire pressure LF 236 243 **KPA** KPA RF LR *_230* _229 **KPA** KPA RR Wind Speed 0.5 m/s (10 m/sec (22 mph) max for passenger cars; 5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 7.9 °C

30 meter (100 ft) Diameter Circle Maneuver					
Test Run Steering Direction Target Lateral Acceleration (g) Acceleration (g) Observed Lateral Acceleration (g) Speed (Km/h)					
1-3	Clockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 32.8 - 33.6</u>	
4-6	Counterclockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 32.8 - 33.6</u>	

Steering wheel angle that corresponds to a peak 0.5-0.6 g lateral acceleration: 80 Degrees

	10-1 Hz Cycle Sinusoidal Steering Maneuver					
Test Data Vehicle Speed Steering Wheel Lateral Lateral				Observed Peak Lateral Acceleration (g)		
1-3	<u>17-19</u>	56 ± 2 (35 ± 1)	<u>80</u> (cycles 1-10)	0.5 - 0.6	<u>0.54</u>	
4	20	FC + 2 /2F + 1)	80 (cycles 1-9)	0.5 - 0.6	<u>0.54</u>	
4	<u>20</u>	56 ± 2 (35 ± 1)	(cycle 10)*	NA	<u>0.85</u>	

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9

Remarks:				
RECORDED BY:	B. Kebschull	DATE RECORDED:	1/6/2010	
APPROVED BY:	.l l enkeit	DATE APPROVED:	1/10/2010	

Data Sheet 7 (Page 1 of 2) SLOWLY INCREASING STEER (SIS) MANEUVER

Vehicle: 2010 Nissan Altima Passenger Car

NHTSA No. CA5206

Measured tire pressure: LF 234 KPA RF 239 KPA

LR <u>227</u> KPA RR <u>226</u> KPA

Wind Speed 0.6 m/s

(10 m/sec (22 mph) max for passenger cars; 5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 7.2 °C

Selected drive configuration FWD

Selected Mode: Normal

Preliminary Left Steer Maneuver:

Lateral Acceleration measured at 30 degrees steering wheel angle

$$a_{y,30\text{deg}rees} = \underline{0.3}$$
 g

Assuming a linear relationship the following ratio should be used to calculate the steering wheel angle at 0.55g:

$$\frac{30 \text{ degrees}}{a_{y,30 \text{ degrees}}} = \frac{\delta_{SIS}}{0.55 \text{ g}}$$

$$\frac{\delta_{sis} = 55.0 \text{ degrees (@.55g)}}{\delta_{sis} = 60 \text{ degrees (rounded)}}$$

Steering Wheel Angle at Corrected 0.3g Lateral Acceleration:

9	Thing White Angle at Confeded C.og Lateral Acceleration.					
		Time Clock	Steering Wheel Angle			
	Initial Steer	(5 min max	to nearest	Data		
Maneuver	Direction	between runs)	0.1° (degrees)	Run	Good/NG	
1	Left	<u>9:57:00 AM</u>	<u>-30.1</u>	<u>9</u>	<u>Good</u>	
2	Left	<u>10:02:00 AM</u>	<u>-29.2</u>	<u>10</u>	<u>Good</u>	
3	Left	<u>10:06:00 AM</u>	<u>-30.9</u>	<u>11</u>	<u>Good</u>	
4	Left					
5	Left					
1	Right	10:11:00 AM	<u>30.0</u>	<u>12</u>	Good	
2	Right	10:16:00 AM	<u>29.6</u>	<u>13</u>	Good	
3	Right	10:21:00 AM		<u>14</u>	<u>NG</u>	
4	Right	11:04:00 AM	<u>29.9</u>	<u>16</u>	Good	
5	Right					

Data Sheet 7 (Page 2 of 2) SLOWLY INCREASING STEER (SIS) MANEUVER

Average Overall Steering Wheel Angle:

$$\delta_{0.3\;g,\;overall} = (\mid \delta_{0.3\;g,\;left\;(1)} \mid + \mid \delta_{0.3\;g,\;left\;(2)} \mid + \mid \delta_{0.3\;g,\;left\;(3)} \mid + \delta_{0.3\;g,\;right\;(1)} + \delta_{0.3\;g,\;right\;(2)} + \delta_{0.3\;g,\;right\;(3)}) \mid 6$$

$$\delta_{0.3\;g,\;overall} = \underline{29.9} \quad \text{degrees}$$
[to nearest 0.1 degree]

Remarks:			

RECORDED BY: B Kebschull DATE RECORDED: 1/6/2010 APPROVED BY: DATE APPROVED: 1/10/2010

Data Sheet 8 (Page 1 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

Vehicle: 2010 Nissan Altima Passeng	er Car :	_
NHTSA No. <u>CA5206</u>	ion date: <u>1/6/2010</u>	
Tire conditioning completed		X Yes No
ESC system is enabled		X Yes No
On track calibration checks have	been completed	X Yes No
On track static data file for each	sensor obtained	X Yes No
Selected Drive Configuration:	FWD	
Selected Mode: Standard		
Overall steering wheel angle (δο.3	g, overall) <i>29.9</i> d	earees

Lateral Stability Test Series No. 1 - Counterclockwise Initial Steer Direction

		Comm	anded		Yaw Rate	S	Υ	′RR	`	/RR
	Clock	Steering	Wheel	(0	(degrees/sec)		at 1.0 sec after		at 1.75 sec after	
Maneuver	Time	Ang	Jle¹				COS		cos	
#	45 50						[<	35%]	[<	20%]
	(1.5 – 5.0 min max between runs)	Scalar (* δ _{0.3 g})	Angle (degrees)	$\dot{\psi}_{\it Peak}$	$\dot{\psi}_{1.0 ext{sec}}$	$\dot{\psi}_{1.75\mathrm{sec}}$	%	Pass/Fail	%	Pass/Fail
1	11:42 AM	1.5	44.9	12.6	-0.2	-0.1	-1.3	PASS	-1.0	PASS
2	11:47 AM	2.0	59.8	16.2	-0.2	0.0	-1.2	PASS	-0.3	PASS
3	11:51 AM	2.5	74.8	19.8	-0.2	-0.2	-1.2	PASS	-1.1	PASS
4	11:54 AM	3.0	89.7	23.6	-0.2	-0.2	-1.0	PASS	-0.8	PASS
5	11:57 AM	3.5	104.7	26.5	-0.2	0.0	-0.8	PASS	0.1	PASS
6	12:00 PM	4.0	119.6	29.6	-0.3	-0.1	-1.2	PASS	-0.4	PASS
7	12:04 PM	4.5	134.6	33.4	-0.2	0.0	-0.6	PASS	0.1	PASS
8	12: 06 PM	5.0	149.5	37.0	-0.3	0.0	-0.7	PASS	0.0	PASS
9	12: 09 PM	5.5	164.5	39.3	-0.1	0.0	-0.1	PASS	-0.1	PASS
10	12: 12 PM	6.0	179.4	42.6	0.4	-0.1	0.9	PASS	-0.1	PASS
11	12: 15 PM	6.5	194.4	44.4	0.4	-0.6	0.8	PASS	-1.3	PASS
12	12:18 PM	7.0	209.3	47.3	0.8	0.0	1.6	PASS	0.0	PASS
13	12:21 PM	7.5	224.3	48.6	0.4	-0.2	0.7	PASS	-0.3	PASS
14	12:25 PM	8.0	239.2	49.3	0.7	-0.3	1.5	PASS	-0.6	PASS
15	12:28 PM	8.5	254.2	52.8	3.0	-0.1	5.7	PASS	-0.2	PASS
16	12:32 PM	9.0	269.1	52.7	1.0	-0.1	1.8	PASS	-0.3	PASS
17	12:36 PM	-	270.0	55.2	1.0	-0.3	1.8	PASS	-0.5	PASS

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5 * $\delta_{0.3~g,~overall}$ or 270 degrees is utilized, whichever is greater provided the calculated magnitude of 6.5 * $\delta_{0.3~g,~overall}$ is less than or equal to 300 degrees. If 6.5 * $\delta_{0.3~g,~overall}$ is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5 * $\delta_{0.3~g,~overall}$ without exceeding the 270 degree steering wheel angle.

DATA SHEET 8 (2 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

LATERAL STABILITY TEST SERIES NO. 2 - Clockwise Initial Steer Direction

LATERAL STABILITY TEST SERIES NO. 2 - Clockwise Initial Steer Direction										
		Comm	anded	Yaw Rates		١	/RR	Υ	′RR	
	Clock	Steering	y Wheel	(degrees/sec)		at 1.0 sec after		at 1.75 sec after		
Maneuver	Time	Ang	gle¹				C	cos	COS	
#							[<	35%]	[< 20%]	
	(1.5 – 5.0 min max between runs)	Scalar (* δ _{0.3 g})	Angle (degrees)	$\dot{\psi}_{{\scriptscriptstyle Peak}}$	$\dot{\psi}_{1.0\mathrm{sec}}$	$\dot{\psi}_{1.75\mathrm{sec}}$	%	Pass/Fail	%	Pass/Fail
1	12:40 PM	1.5	44.9	-12.2	0.1	-0.1	-1.0	PASS	0.7	PASS
2	12:46 PM	2.0	59.8	-16.4	0.0	0.0	-0.3	PASS	-0.1	PASS
3	12:50 PM	2.5	74.8	-20.3	0.2	0.1	-0.8	PASS	-0.5	PASS
4	12:52 PM	3.0	89.7	-24.6	0.2	0.1	-0.6	PASS	-0.3	PASS
5	12:55 PM	3.5	104.7	-28.8	0.2	0.1	-0.7	PASS	-0.5	PASS
6	12:59 PM	4.0	119.6	-30.9	0.2	0.2	-0.8	PASS	-0.6	PASS
7	1:02 PM	4.5	134.6	-35.6	0.2	0.2	-0.7	PASS	-0.4	PASS
8	1:05 PM	5.0	149.5	-38.0	0.1	-0.1	-0.3	PASS	0.2	PASS
9	1:08 PM	5.5	164.5	-42.7	0.2	0.1	-0.4	PASS	-0.3	PASS
10	1:11 PM	6.0	179.4	-46.4	0.4	0.1	-0.8	PASS	-0.3	PASS
11	1:14 PM	6.5	194.4	-48.1	0.0	0.1	-0.1	PASS	-0.2	PASS
12	1:18 PM	7.0	209.3	-51.5	-0.4	0.0	0.7	PASS	0.0	PASS
13	1:21 PM	7.5	224.3	-52.6	0.1	0.1	-0.2	PASS	-0.1	PASS
14	2:24 PM	8.0	239.2	-54.6	-0.1	0.0	0.1	PASS	0.0	PASS
15	2:27 PM	8.5	254.2	-55.9	0.1	0.0	-0.2	PASS	0.0	PASS
16	2:30 PM	9.0	269.1	-57.0	0.1	0.1	-0.3	PASS	-0.2	PASS
17	2:33 PM	-	270.0	-56.3	0.0	-0.1	0.0	PASS	0.1	PASS

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5*\delta_0.3 g, overall or 270 degrees is utilized, whichever is greater provided the calculated 6.5*\delta_0.3 g, overall is less than or equal to 300 degrees. If 6.5*\delta_0.3 g, overall is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5*\delta_0.3 g, overall without exceeding the 270 degree steering wheel angle.

During execution of the sine with dwell maneuve	rs were	e any o	of th	е
following events observed?				
Rim-to-pavement contact		Yes	X	No
Tire debeading		Yes	X	No
Loss of pavement contact of vehicle tires		Yes	X	No
Did the test driver experience any vehicle loss of control or spinout?		Yes	X	No
If "Yes" explain the event and consult with	the CO	TR.		

DATA SHEET 8 (3 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

Responsiveness - Lateral Displacement

Responsiveness – Lateral Displacement								
		Commanded S	•		ed Lateral			
		An	_	Displac	ement ¹			
Maneuver	Initial Steer	(5.0* $\delta_{0.3 \text{ g, overall}}$ or greater)			, 			
#	Direction	Scalar	Angle	Distance	Pass/Fail			
		* 8 _{0.3 g}	(degrees)	(m)				
8	Counter Clockwise	5.0	149.5	-3.1	<u>PASS</u>			
9	Counter Clockwise	5.5	164.5	-3.1	<u>PASS</u>			
10	Counter Clockwise	6.0	179.4	-3.3	<u>PASS</u>			
11	Counter Clockwise	6.5	194.4	-3.3	<u>PASS</u>			
12	Counter Clockwise	7.0	209.3	-3.3	<u>PASS</u>			
13	Counter Clockwise	7.5	224.3	-3.4	<u>PASS</u>			
14	Counter Clockwise	8.0	239.2	-3.4	<u>PASS</u>			
15	Counter Clockwise	8.5	254.2	-3.4	<u>PASS</u>			
16	Counter Clockwise	9.0	269.1	-3.4	<u>PASS</u>			
17	Counter Clockwise	-	270.0	-3.4	<u>PASS</u>			
25	Clockwise	5.0	149.5	3.0	<u>PASS</u>			
26	Clockwise	5.5	164.5	3.1	<u>PASS</u>			
27	Clockwise	6.0	179.4	3.1	<u>PASS</u>			
28	Clockwise	6.5	194.4	3.2	<u>PASS</u>			
29	Clockwise	7.0	209.3	3.3	<u>PASS</u>			
30	Clockwise	7.5	224.3	3.3	<u>PASS</u>			
31	Clockwise	8.0	239.2	3.3	<u>PASS</u>			
32	Clockwise	8.5	254.2	3.3	<u>PASS</u>			
33	Clockwise	9.0	269.1	3.4	<u>PASS</u>			
34	Clockwise	-	270.0	3.4	PASS			

^{1.} Lateral displacement should be \geq 1.83 m (6 ft) for vehicle with a GVWR of 3,500 kg (7,716 lb) or less; and \geq 1.52 m (5 ft) for vehicles with GVWR greater than 3,500 kg (7,716 lb).

DATA INDICATES C	COMPLIANCE:	✓ PASS	FAIL
Remarks:			
RECORDED BY:	B Kebschull	DATE RECORDED:	1/6/2010
APPROVED BY:	J Lenkeit	DATE APPROVED:	1/10/2010

Data Sheet 9 (Page 1 of 2) MALFUNCTION WARNING TESTS

Vehicle: <u>2010 Nissan Altima Passe</u>	enger Car :
NHTSA No. <u>CA5206</u>	Data Sheet Completion Date: 1/6/2010
	TEST 1
MALFUNCTION SIMULATION	1: Describe method of malfunction simulation
Disconnected steering angle se	<u>ensor</u>
MALFUNCTION TELLTALE IL	LUMINATION:
	uminated after ignition locking system is nicle is driven at least 2 minutes as specified X Yes No
Time for telltale to illuminate after speed of 48 ± 8 km/h (30 ± 5 mph 0 Seconds (must be within	
ESC SYSTEM RESTORATION	I
	locking system is activated and if necessary nutes as specified in section 13.12.B X Yes No
Time for telltale to extinguish afte speed of 48 \pm 8 km/h (30 \pm 5mph	er ignition system is activated and vehicle n) is reached.
O Seconds (must be within	n 2 minutes) X Pass Fail
TEST 1 DAT	TA INDICATES COMPLIANCE: PASS
malfunction is simulated and ignit	LIP" telltales illuminate immediately after ion is activated. tales extinguish immediately when ignition is
RECORDED BY: B Kebschull	DATE RECORDED: 1/6/2010
APPROVED BY: J Lenkeit	DATE APPROVED 1/10/2010

Data Sheet 9 (Page 2 of 2) MALFUNCTION WARNING TESTS

Vehicle: <u>2010 Nissan Altima Passen</u>	ger Car :
NHTSA No <i>. CA5206</i>	Data Sheet Completion Date: 1/6/2010
	TEST 2
MALFUNCTION SIMULATION	: Describe method of malfunction simulation
Disconnected LF wheel speed s	<u>sensor</u>
MALFUNCTION TELLTALE IL	LUMINATION:
	uminated after ignition locking system is icle is driven at least 2 minutes as specified
	X Yes No
Time for telltale to illuminate after speed of 48 ± 8 km/h (30 ± 5 mph 0 Seconds (must be within	
ESC SYSTEM RESTORATION	I
	locking system is activated and if necessary nutes as specified in section 13.12.B X Yes No
Time for telltale to extinguish afte speed of 48 \pm 8 km/h (30 \pm 5mph	r ignition system is activated and vehicle) is reached.
O Seconds (must be within	n 2 minutes) X Pass Fail
TEST 2 DAT	A INDICATES COMPLIANCE: PASS
malfunction is simulated and igniti	d "ABS" telltales illuminate immediately after on is activated. tales extinguish immediately when ignition is
RECORDED BY: B Kebschull	DATE RECORDED: 1/6/2010
APPROVED BY: J Lenkeit	DATE APPROVED <u>1/10/2010</u>

4.0 TEST EQUIPMENT LIST AND CALIBRATION INFORMATION (1 OF 2)

TABLE 1. TEST INSTRUMENTATION

Туре	Output	Range	Resolution	Accuracy	Specifics	Serial Number	Calibration
Tire Pressure Gauge	Vehicle Tire Pressure	0-100 psi 0-690 kPa	1 psi 6.89 kPa	0.5 psi 3.45 kPa	Ashcroft D1005PS	1039350	By: Innocal Date:1/15/09 Due: 1/15/10
Platform Scales	Vehicle Total, Wheel, and Axle Load	8000 lb 35.6 kN	0.5 lb 2.2 N	±1.0% of applied load	Intercomp Model SWII	24032361	By: Intercomp Date:1/29/09 Due: 1/29/10
Automated Steering Machine with Steering Angle Encoder	Handwheel Angle	±800 deg	0.25 deg	±0.25 deg	Heitz Automotive Testing Model: Sprint 3	60304	By: Heitz Date:1/29/09_ Due: 1/29/10
Multi-Axis Inertial Sensing System	Longitudinal, Lateral, and Vertical Acceleration Roll, Yaw, and Pitch Rate	Accelerometers: ±2 g Angular Rate Sensors: ±100 deg/s	Acceleromet ers: ≤10 ug Angular Rate Sensors: ≤0.004 deg/ s	Acceleromete rs: ≤0.05% of full range Angular Rate Sensors: 0.05% of full range	BEI Technologies Model: MotionPAK MP-1	0767	By:Systron Donner Date:11/18/09 Due: 11/18/10
Radar Speed Sensor and Dashboard Display	Vehicle Speed	0-125 mph 0-200 km/h	0.009 mph .014 km/h	±0.25% of full scale	A-DAT Corp. Radar Model: DRS-6 Display Model: RD-2	1400.604	By: ADAT Date:1/5/09 Due:1/5/10*
Ultrasonic Distance	Left and Right Side	5-24 inches	0.01 inches	±0.25% of	Massa Products Corporation	DOT-NHTSA D2646	By: DRI Date:3/16/09 Due: 3/16/10
Measuring System	Vehicle Height	127-610 mm	.254 mm	distance	Model: M- 5000/220	DOT-NHTSA D2647	By: DRI Date:3/16/09 Due: 3/16/10

^{*} Speed sensor was checked and verified on the test track prior to test

4.0 TEST EQUIPMENT LIST AND CALIBRATION INFORMATION (2 OF 2)

TABLE 1. TEST INSTRUMENTATION (CONTD)

Туре	Output	Range	Resolution	Accuracy	Specifics	Serial Number	Calibration
Data Acquisition System [Includes amplification, anti-	Record Time; Velocity; Distance; Lateral, Longitudinal, and	Sufficient to meet	200 Hz	Sufficient to meet or	SoMat eDaq ECPU processor	MSHLB.03- 2476	By: Somat Date:1/13/09 Due: 1/14/10
aliasing, and analog to digital conversion.]	Vertical Accelerations; Roll, Yaw, and Pitch Rates; Steering Wheel Angle.	or exceed individual sensors		exceed individual sensors	SoMat High level Board EHLS	MSHLS.03- 3182	By: Somat Date:1/14/09 Due: 1/15/10
Load Cell	Vehicle Brake Pedal Force	0-300 lb 0-1.33 kN	1 lb 4.44 N	±0.05% of full scale	Lebow 3663-300	767	By: Davis Date:2/3/09 Due: 2/3/10
Coordinate Measurement Machine	Inertial Sensing System Coordinates	0-8 ft 0-2.4 m	±.0020 in. ±.051 mm	±.0020 in. ±.051 mm (Single point articulation accuracy)	Faro Arm Fusion	UO8-05-08- 06636	By: Faro Date: 8/18/09 Due: 8/18/10
Outriggers	No output. Safety Item.	N/A	N/A	N/A	DRI manufactured Aluminum meeting the weight and MOI specifications of Docket 2007- 27662-11	N/A	N/A

5.0 PHOTOGRAPHS (29 of 14)



Figure 5.1. Front View of Test Vehicle as Delivered

5.0 PHOTOGRAPHS (2 of 14)



Figure 5.2. Rear View of Test Vehicle as Delivered

5.0 PHOTOGRAPHS (3 of 14)

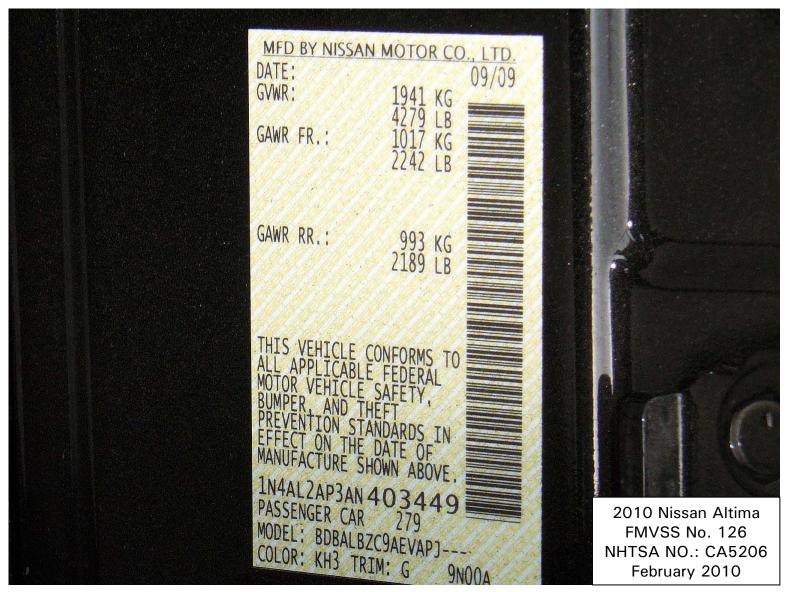


Figure 5.3. Vehicle Certification Label

5.0 PHOTOGRAPHS (4 of 14)

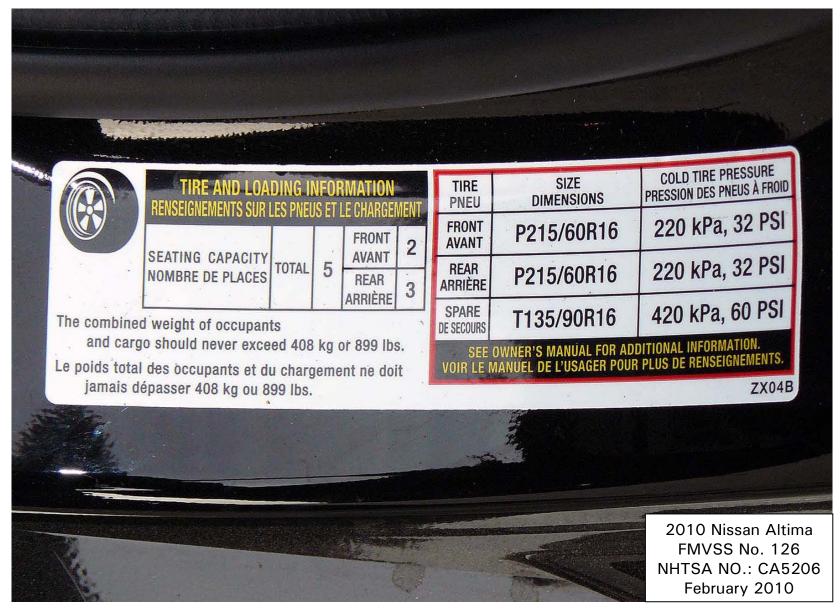


Figure 5.4. Vehicle Placard

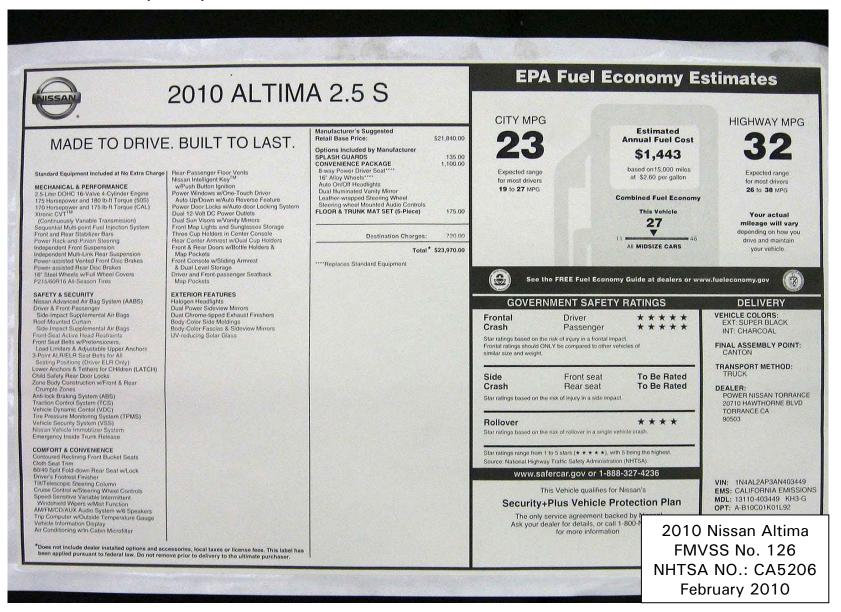


Figure 5.5. Window Sticker (Monroney Label)

5.0 PHOTOGRAPHS (6 of 14)



Figure 5.6. Telltale for ESC Malfunction and ESC Off

5.0 PHOTOGRAPHS (7 of 14)



Figure 5.7. ESC Off Control Switch

5.0 PHOTOGRAPHS (8 of 14)



Figure 5.8. Front View of Vehicle as Tested

5.0 PHOTOGRAPHS (9 of 14)



Figure 5.9. Rear View of Vehicle as Tested

5.0 PHOTOGRAPHS (10 of 14)

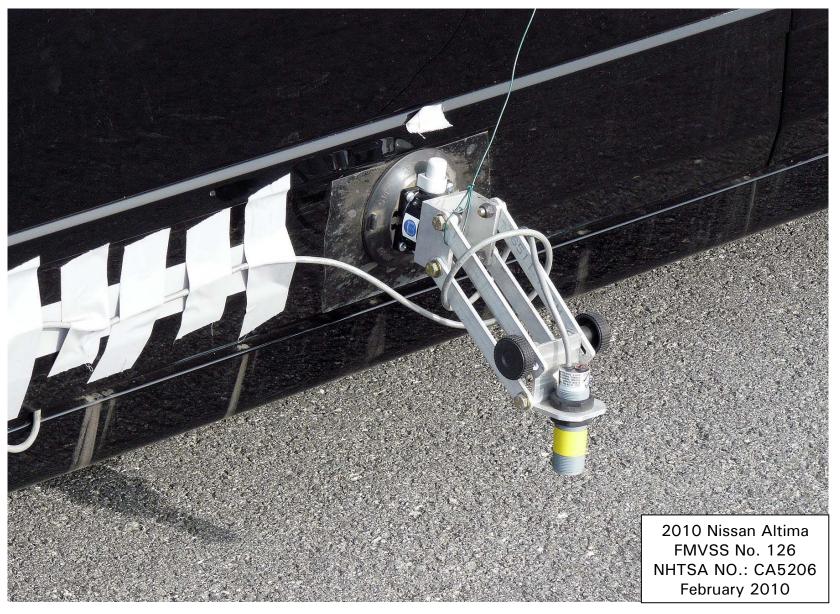


Figure 5.10. Ultrasonic Height Sensor Mounted on Left side of Vehicle for Determining Body Roll Angle

5.0 PHOTOGRAPHS (11 of 14)



Figure 5.11. Rear Bumper Mounted Speed Sensor

5.0 PHOTOGRAPHS (12 of 14)



Figure 5.12. Steering Controller and Data Acquisition Computer

5.0 PHOTOGRAPHS (13 of 14)



Figure 5.13. Inertial Measurement Unit Mounted in Vehicle

5.0 PHOTOGRAPHS (14 of 14)



Figure 5.14. Brake Pedal Load Cell

6.0 DATA PLOTS (1 of 4)

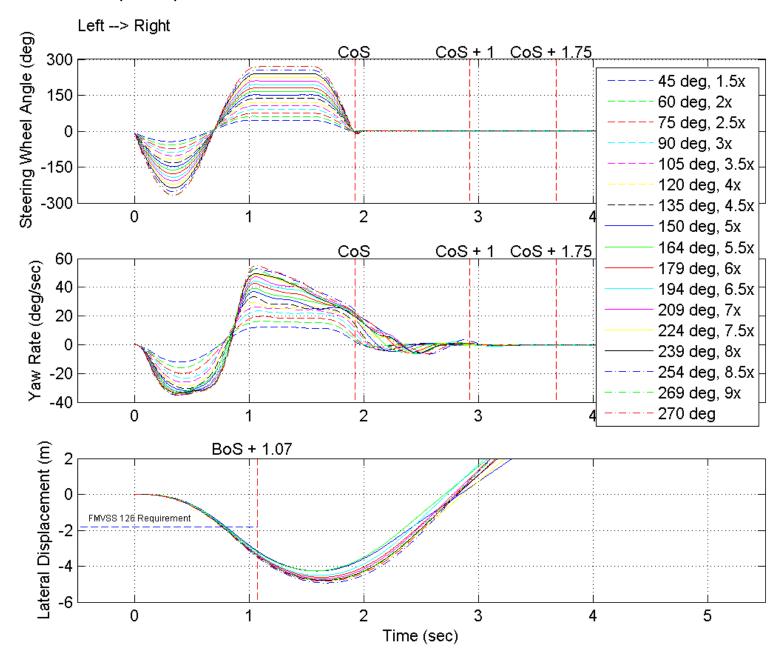


Figure 6.1. Steering Wheel Angle, Yaw Rate and Lateral Displacement for L-R Series

6.0 DATA PLOTS (2 of 4)

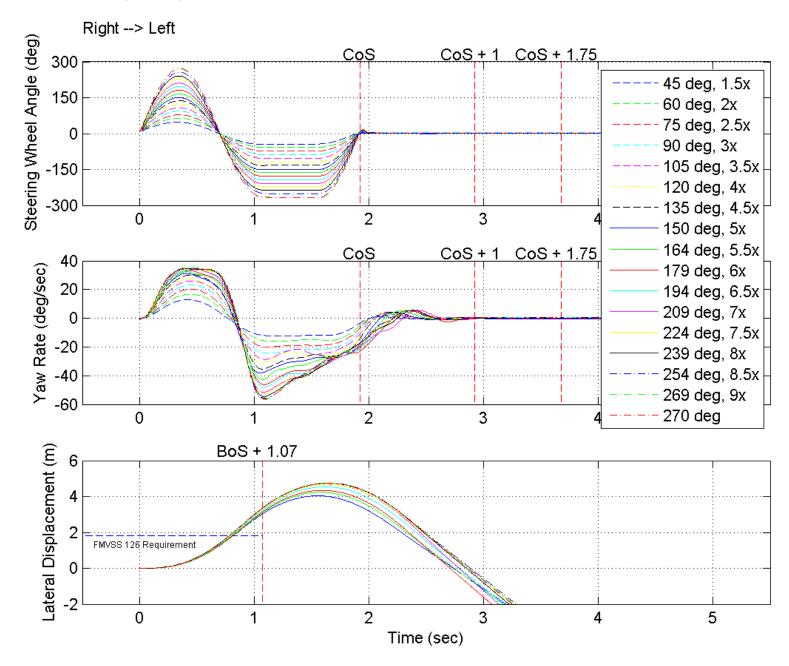


Figure 6.2. Steering Wheel Angle, Yaw Rate and Lateral Displacement for R-L Series

6.0 DATA PLOTS (3 of 4)

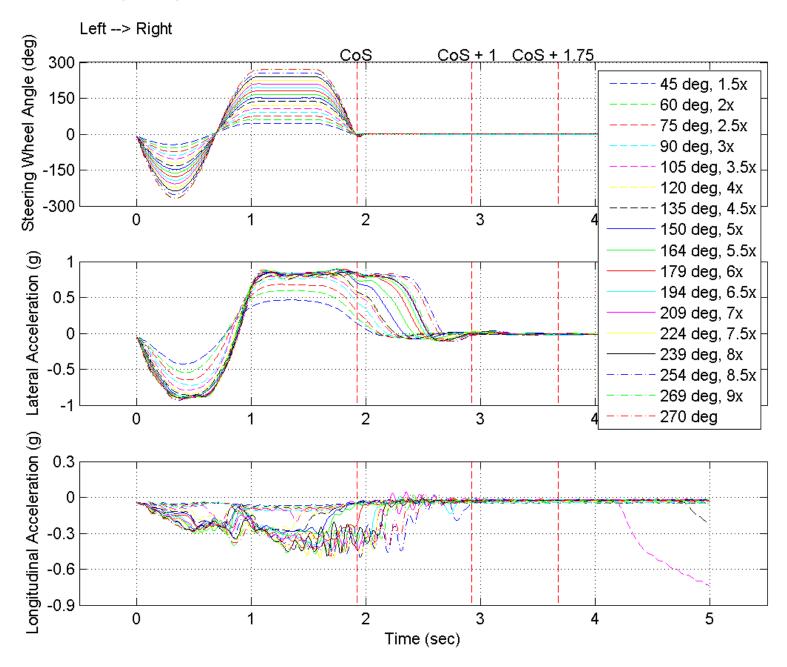


Figure 6.3. Steering Wheel Angle, Lateral Acceleration and Longitudinal Acceleration for L-R Series

6.0 DATA PLOTS (4 of 4)

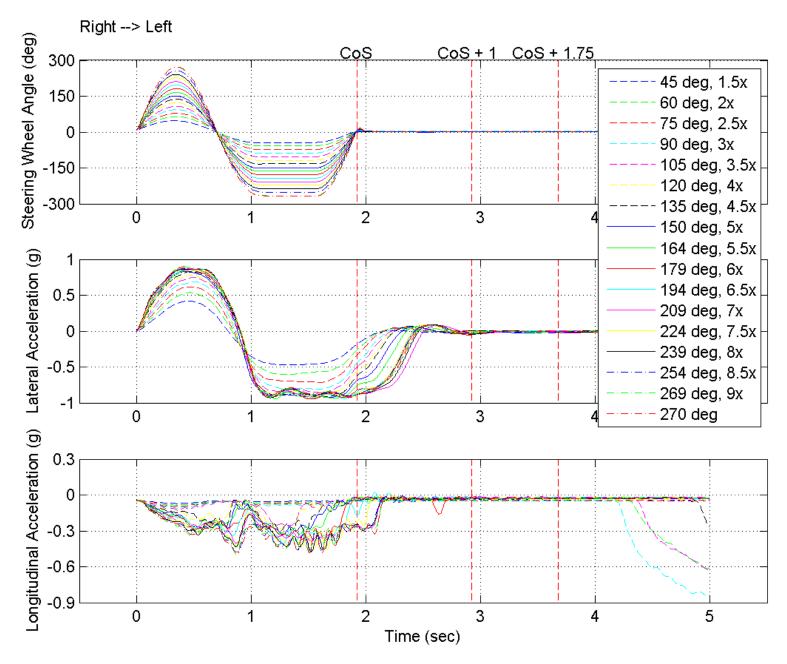


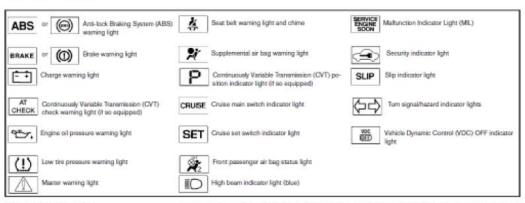
Figure 6.4. Steering Wheel Angle, Lateral Acceleration and Longitudinal Acceleration for R-L Series

7.0 OTHER DOCUMENTATION

- 7.1 OWNER'S MANUAL PAGES
- 7.2 VEHICLE ARRIVAL CONDITION REPORT
- 7.3 VEHICLE COMPLETION CONDITION REPORT
- 7.4 SINE WITH DWELL TEST RESULTS
- 7.5 SLOWLY INCREASING STEER TEST RESULTS
- 7.6 INERTIAL SENSING SYSTEM LOCATION COORDINATES

7.1 OWNER'S MANUAL PAGES

WARNING/INDICATOR LIGHTS AND AUDIBLE REMINDERS



CHECKING BULBS

With all doors closed, apply the parking brake and place the ignition switch in the ON position without starting the engine. The following lights will come on:



2-10 Instruments and controls

The following lights come on briefly and then go off:

ABS or (A) , A SEE SLIP , AND SHIP

If any light fails to come on, it may indicate a burned-out bulb or an open circuit in the electrical system. Have the system repaired promptly.



When the ignition switch is placed in the ON position, the Anti-lock Braking System (ABS) warning light illuminates and then turns off. This indicates the ABS is operational.

If the ABS warning light illuminates while the angine is running, or while driving, it may indicate the ABS is not functioning properly. Have the system checked by a NISSAN dealer.

If an ABS malfunction occurs, the anti-lock function is turned off. The brake system then operates normally, but without anti-lock assistance. See "Brake system" in the "Starting and driving" section.



This light functions for both the parking brake and the foot brake systems.

Parking brake indicator

When the ignition switch is placed in the ON position, the light comes on when the parking brake is applied.

Low brake fluid warning light.

When the ignition switch is placed in the ON position, the light warns of a low brake fluid level. If the light comes on while the engine is running with the parking brake not applied, stop the vehicle and perform the following:

- Check the brake fluid level. Add brake fluid as necessary. See "Brake fluid" in the "Maintenance and do-it-yoursel" section of this manual.
- If the brake fluid level is correct, have the warning system checked by a NISSAN dealer.

AWARNING

- Your brake system may not be working properly if the warning light is on. Driving could be dangerous. If you judge it to be safe, drive carefully to the nearest service station for repairs. Otherwise, have your vehicle towed because driving it could be dangerous.
- Pressing the brake pedal with the engine stopped and/or a low brake fluid level may increase your stopping distance and braking will require greater pedal effort as well as pedal travel.

 If the brake fluid level is below the MINIMUM or MIN mark on the brake fluid reservoir, do not drive until the brake system has been checked at a NISSAN dealer.

Anti-lock Braking System (ABS) warning indicator

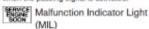
When the parking brake is released and the brake fluid level is sufficient, if both the brake warning light and the Anti-lock Braking System (ABS) warning light illuminate, it may indicate the ABS is not functioning properly. Have the brake system chacked, and if necessary repaired by a NISSAN dealer promptly. Avoid high-speed driving and abrupt braking. (See "Anti-lock Braking System (ABS) warning light" in this section.)

Charge warning light

If this light comes on while the engine is running, it may indicate the charging system is not functioning properly. Turn the angine off and check the generator belt. If the belt is loose, broken, missing, or if the light remains on, see a NISSAN dealer immediately.

Instruments and controls 2-11

The high beam indicator light also comes on when the passing signal is activated.



If this indicator light comes on steady or blinks while the engine is running, it may indicate a potential emission control malfunction.

The Malfunction Indicator Light may also come on steady if the fuel-filler cap is loose or missing, or if the vehicle runs out of fuel. Check to make sure the fuel-filler cap is installed and closed tightly, and that the vehicle has at least 3 gallons (11.4 liters) of fuel in the fuel tank.

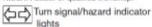
After a few driving trips, the ight should turn off if no other potential emission control system malfunction exists.

If this indicator light comes on steady for 20 seconds and then blinks for 10 seconds when the engine is not running, it indicates that the vehicle is not ready for an emission control system inspection/maintenance test. See "Readiness for inspection/maintenance (I/M) test" in the "Technical and consumer information" section of this manual.

You may feel or hear the system working; this is

The light will blink for a few seconds after the VDC system stops limiting wheel spin.

The SLIP indicator light also comes on when you place the ignition switch in the ON position. The light will turn off after approximately 2 seconds if the system is operational. If the light does not come on have the system checked by a NISSAN dealer or qualified workshop.



The appropriate light flashes when the turn signal switch is activated.

Both lights flash when the hazard switch is turned



Vehicle Dynamic Control (VDC) OFF indicator light

This indicator light comes on when the Vehicle Dynamic Control off switch is pushed to OFF. This indicates the Vehicle Dynamic Control has been turned off.

2-16 Instruments and controls

Operation

The Malfunction Indicator Light will come on in one of two ways:

- Malfunction Indicator Light on steady An emission control system malfunction has been detected. Check the fuel-filler cap. If the fuel-filler cap is loose or missing, tighten or install the cap and continue to drive the vehicle. The Will light should turn off after a few driving trips. If the ight does not turn off after a few driving trips, have the vehicle inspected by a NISSAN dealer. You do not need to have your vehicle towed to the dealer.
- · Malfunction Indicator Light blinking An engine misfire has been detected which may damage the emission control system. To reduce or avoid emission control system dam-
 - do not drive at speeds above 45 MPH (72 km/h).
 - avoid hard acceleration or deceleration.
 - avoid steep uphill grades.

tion of this manual.

- if possible, reduce the amount of cargo being hauled or towed.

Push the Vehicle Dynamic Control off switch

again or restart the engine and the system will

operate normally. See "Vehicle Dynamic Control

(VDC) system" in the "Starting and driving" sec-

The Vehicle Dynamic Control light also comes on

when you push the push-button ignition switch to

the ON position. The light will turn off after about

2 seconds if the system is operational. If the light

stays on or comes on along with the SLIP indica-

tor light while you are driving, have the Vehicle

Dynamic Control system checked by a NISSAN

While the Vehicle Dynamic Control system is

operating, you might feel slight vibration or hear

the system working when starting the vehicle or

The disc brake pads have audible wear warnings.

When a disc brake pad requires replacement, it

makes a high pitched scraping sound when the vehicle is in motion, whether or not the brake

pedal is depressed. Have the brakes checked as soon as possible if the warning sound is heard.

accelerating, but this is normal.

AUDIBLE REMINDERS

Brake pad wear warning

The Malfunction Indicator Light may stop blinking and come on steady. Have the vehicle inspected by a NISSAN dealer. You do not need to have your vehicle towed to the dealer.

A CAUTION

Continued vehicle operation without having the emission control system checked and repaired as necessary could lead to poor driveability, reduced fuel economy, and possible damage to the emission control system.



Security indicator light

This light blinks when the ignition switch is placed in the OFF, LOCK or ACC position.

The blinking security indicator light indicates that the security systems equipped on the vehicle are operational

For additional information, see "Security systems" later in this section.

SLIP Slip indicator light

This indicator will blink when the VDC system is operating, thus alerting the driver to the fact that the road surface is slippery and the vehicle is nearing its traction limits

Instruments and controls 2-15

Key reminder chime

A chime sounds if the driver's door is opened while the ignition switch is placed in the ACC or OFF position or placed in the OFF or LOCK position with the Intelligent Key left in the Intelligent Key port. Make sure the ignition switch is placed in the LOCK position, and take the Intelligent Key with you when leaving the vehicle.

Light reminder chime

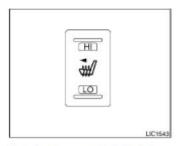
With the ignition switch placed in the OFF position, a chime sounds when the driver's door is opened if the headlights or parking lights are on.

Turn the headlight control switch off before leaving the vehicle.

NISSAN Intelligent Key™ door buzzer

The Intelligent Key door buzzer sounds if the Intelligent Key is left inside the vehicle when locking the doors. When the buzzer sounds, be sure to check both the vehicle and the Intelligent Key. See "NISSAN Intelligent Key" " in the "Predriving checks and adjustments" section.

HEATED SEAT (if so equipped)



The front seats are warmed by built-in heaters.

- 1. Start the engine.
- Push the low or high position of the switch, as desired, depending on the temperature. The indicator light in the switch will illuminate.

The heater is controlled by a thermostat, automatically turning the heater on and off. The indicator light will remain on as long as the switch is on.

When the seat is warmed or before you leave the vehicle, be sure to turn the switch

2-34 Instruments and controls

To dry the brakes, drive the vehicle at a safe speed while lightly pressing the brake pedal to heat up the brakes. Do this until the brakes return to normal. Avoid driving the vehicle at high speeds until the brakes function correctly.

ANTI-LOCK BRAKING SYSTEM (ABS)

A WARNING

- The Anti-lock Braking System (ABS) is a sophisticated device, but it cannot prevent accidents resulting from careless or dangerous driving techniques. It can help maintain wehicle control during braking on slippery surfaces. Remember that stopping distances on slippery surfaces will be longer than on normal surfaces even with ABS. Stopping distances may also be longer on rough, gravel or snow covered roads, or if you are using tire chains. Always maintain a safe distance from the vehicle in front of you. Ultimately, the driver is responsible for safety.
- Tire type and condition may also affect braking effectiveness.

A CAUTION

- Do not use the seat heater for extended periods or when no one is using the seat.
- Do not put anything on the seat which insulates heat, such as a blanket, cushion, seat cover, etc. Otherwise, the seat may become overheated.
- Do not place anything hard or heavy on the seat or pierce it with a pin or similar object. This may result in damage to the heater.
- Any liquid spilled on the heated seat should be removed immediately with a dry cloth.
- When cleaning the seat, never use gasoline, benzine, thinner, or any similar materials.
- If any abnormalities are found or the heated seat does not operate, turn the switch off and have the system checked by your NISSAN dealer.
- The battery could run down if the seat heater is operated while the engine is not running.

VEHICLE DYNAMIC CONTROL (VDC) OFF SWITCH



The vehicle should be driven with the Vehicle Dynamic Control (VDC) system on for most driving conditions.

If the vehicle is stuck in mud or snow, the VDC system reduces the engine output to reduce wheal spin. The engine spead will be reduced even if the accelerator is depressed to the floor. If maximum engine power is needed to free a stuck whicle, turn the VDC system off.

To turn off the VDC system, push the VDC OFF switch. The indicator will come on.

Push the VDC OFF switch again or restart the engine to turn on the system. See "Vehicle Dynamic Control (VDC) system" in the "Starting and driving" section.

 When replacing tires, install the specified size of tires on all four wheels.

- When installing a spare tire, make sure that it is the proper size and type as specified on the Tire and Loading Information label. See "Tire and Loading Information label" in the "Technical and consumer information" section of this manual.
- For detailed information, see "Wheels and tires" in the Maintenance and do-it-yourself" section of this manual.

The Anti-lock Braking System (ABS) controls the brakes so the wheels do not lock during hard braking or when braking on slippery surfaces. The system detects the rotation speed at each wheel and varies the brake fluid pressure to prevent each wheel from locking and sliding. By preventing each wheel from locking, the system helps the driver maintain steering control and helps to minimize awarving and spinning on slippery surfaces.

Using the system

Depress the brake pedal and hold it down. Depress the brake pedal with firm steady pressure, but do not pump the brakes. The ABS will operate to prevent the wheels from locking up. Steer the vehicle to avoid obstacles.

A WARNING

Do not pump the brake pedal. Doing so may result in increased stopping distances.

Self-test feature

The ABS includes electronic sensors, electric pumps, hydraulic solenoids and a computer. The computer has a built-in diagnostic feature that tests the system each time you start the engine and move the vehicle at a low speed in forward or reverse. When the self-test occurs, you may hear a "clunk" noise and/or feel a pulsation in the brake pedal. This is normal and does not indicate a malfunction. If the computer senses a malfunction, it switches the ABS off and illuminates the ABS warning light on the instrument panel. The brake system then operates normally, but without anti-lock assistance.

If the ABS warning light illuminates during the self-test or while driving, have the vehicle checked by a NISSAN dealer.

5-24 Starting and driving

VEHICLE DYNAMIC CONTROL (VDC) SYSTEM

Normal operation

The ABS operates at speeds above 3 - 6 MPH (5 - 10 km/h). The speed varies according to road conditions.

When the ABS senses that 1 or more wheels are close to locking up, the actuator rapidly applies and releases hydrautic pressure. This action is similar to pumping the brakes very quickly. You may feel a pulsation in the brake pedal and hear a noise from under the hood or feel a vibration from the actuator when it is operating. This is normal and indicates that the ABS is operating properly. However, the pulsation may indicate that road conditions are hazerdous and extra care is required while dinking.

The Vehicle Dynamic Control (VDC) system uses various sensors to monitor driver inputs and vehicle motion. Under certain driving situations, the system will control braking and engine output to help keep the vehicle on its steered path.

- When the Vehicle Dynamic Control (VDC) system is operating, the SLIP indicator in the instrument panel blinks.
- If the SLIP indicator blinks, the road conditions may be slippery. Be sure to adjust your speed and driving to these conditions. See "Slip indicator light", and "Vehicle Dynamic Control (VDC) off indicator light" in the "Instruments and controls" section.
- Indicator light.

If a malfunction occurs in the system, the SLIP and indicator lights come on in the instrument panel.

As long as these indicator lights are on, the traction control function is canceled.

If the vehicle is operated with the Vehicle Dynamic Control system off using the VDC OFF switch, VDC and the Traction Control System (TCS) functions will be turned off. The SLIP indicator will flash if whost spin is distracted. The ABS will still operate with the VDC system off. When the VDC system is operating, you may feel a pulsation in the brake pedal and hear a noise or vibration from under the hood. This is normal and indicates that the VDC system is working property.

The computer has a built in diagnostic feature that tests the system each time you start the engine and move the vehicle forward or in reverse at a slow speed. When the self-test occurs, you may hear a clunk noise and/or feel a pulsation in the brake pedal. This is normal and is not an indication of a maffunction.

AWARNING

 The Vehicle Dynamic Control system is designed to help improve driving stability but does not prevent accidents due to abrupt steering operation at high speeds or by careless or dangerous driving techniques. Reduce vehicle speed and be especially careful when driving and cornering on slippery surfaces and always drive carefully.

Starting and driving 5-25

- Do not modify the vehicle's suspension. If suspension parts such as shock absorbers, struts, springs, stabilizer bars, bushings and wheels are not NISSAN approved for your vehicle or are extremely deteriorated the Vehicle Dynamic Control system may not operate properly. This could adversely affect vehicle handling performance, and the VDC OFF indicator light may come on.
- If brake related parts such as brake pads, rotors and calipers are not standard equipment or are extremely deteriorated, the Vehicle Dynamic Control system may not operate properly and the Vehicle Dynamic Control off indicator light may come on.
- When driving on extremely inclined surfaces such as higher banked corners, the Vehicle Dynamic Control system may not operate properly and the VDC OFF indicator light may come on. Do not drive on these types of roads.
- When driving on an unstable surface such as a turnitable, ferry, elevator or ramp, the Vehicle Dynamic Control off indicator light may illuminate. This is not a mallunction. Restart the engine after driving onto a stable surface.
- 5-26 Starting and driving

- If wheels or tires other than the recommended ones are used, the Vehicle Dynamic Control system may not operate properly and the Vehicle Dynamic Control off Indicator light may come on.
- The Vehicle Dynamic Control system is not a substitute for winter tires or tire chains on a snow covered road.

COLD WEATHER DRIVING FREEING A FROZEN DOOR LOCK

To prevent a door lock from freezing, apply delose through the key hole. If the lock becomes frozen, hear the key before insorting it into the key hole or use the remote keyless entry function on the intelligent key.

ANTI-FREEZE

In the winter when it is anticipated that the temparature will drop below 32°F (0°C), chack the anti-freeze to assure proper winter protection. For dotals, see "Engine cooling system" in the "Maintenance and do-it-yourself" section of this manual.

BATTERY

If the battery is not fully charged during extremely cold weather conditions, the battery fluid may freeze and damage the battery. To maintain maxmum efficiency, the battery should be chacked regularly. For details, see "Battery" in the "Maintenance and do-it-yourself" section of this manual.

7.2 VEHICLE ARRIVAL CONDITION REPORT

CONTRACT NO.: DTNH22-08-D-00098

DATE: 12/7/2009

From: Competitive Vehicle Services Purpose I Initial Receipt

Received via Transfer

To: Dynamic Research, Inc Present Vehicle

Vehicle VIN: 1N4AL2AP3AN403449 NHTSA NO.: CA5206

Model Year: <u>2010</u> Odometer Reading: <u>13</u> Miles Make <u>Nissan</u> Body Style: <u>Passenger Car</u>

Model: <u>Altima</u> Body Color: <u>Black</u>

Manufacture 9/09 Dealer: Competitive Vehicle

Date: Services

GVWR (kg/lb) <u>1941/4279</u> Price: <u>Leased</u>

X All options listed on the "Window Sticker" are present on the test vehicle

X Tires and wheel rims are new and the same as listed

There are no dents or other interior or exterior flaws

The vehicle has been properly prepared and is in running condition

▼ The glove box contains an owner's manual, warranty document, consumer information, and extra set of keys

X Proper fuel filler cap is supplied on the test vehicle

▼ Place vehicle in storage area

Inspect the vehicle's interior and exterior, including all windows, seats, doors, etc., to confirm that each system is complete and functional per the manufacturer's specifications. Any damage, misadjustment, or other unusual condition that could influence the test program or test results shall be recorded. Report any abnormal condition to the NHTSA COTR before beginning any test. NOTES:

RECORDED BY: <u>J Lenkeit</u> DATE RECORDED: <u>12/7/2009</u>

APPROVED BY: <u>P Broen</u> DATE APPROVED: <u>12/7/2009</u>

7.3 VEHICLE COMPLETION CONDITION REPORT

CONTRACT NO.: DTNH22-08-D-00098 DATE: 1/14/2010 Vehicle VIN: 1N4AL2AP3AN403449 NHTSA NO.: CA5206 Model Year: 2010 Odometer Reading: Miles 66 Make: Nissan Body Style: Passenger Car Body Color: Black Model: *Altima* Manufacture Date: 9/09 Dealer: Competitive Vehicle Services 1941 (4279) GVWR (kg/lb) Price: Leased LIST OF FMVSS TESTS PERFORMED BY THIS LAB: 126 ▼ THERE ARE NO DENTS OR OTHER INTERIOR OR EXTERIOR FLAWS ☑ THE VEHICLE HAS BEEN PROPERLY MAINTAINED AND IS IN RUNNING. CONDITION DOCUMENT, CONSUMER INFORMATION, AND EXTRA SET OF KEYS □ PROPER FUEL FILLER CAP IS SUPPLIED ON THE TEST VEHICLE **REMARKS:** Equipment that is no longer on the test vehicle as noted on Vehicle Arrival **Condition Report:** None Explanation for equipment removal: NA Test Vehicle Condition: Like New RECORDED BY: J Lenkeit DATE RECORDED: 1/14/2010

DATE APPROVED: 1/14/2010

APPROVED BY: B Kebschull

7.4 SINE WITH DWELL TEST RESULTS

2010 Nissan Altima Passenger Car

NHTSA No.: <u>CA5206</u>
Date of Test: <u>1/6/2010</u>
Date Created: <u>1/6/2010</u>

Lateral Stability Test Series No. 1 - Counterclockwise Initial Steer Direction

File	SWA @ 5deg Ct	MES	Time @ 5deg	cos	Time @ COS	MOS	Time @ MOS	YRR1	YR1	YRR 1 Ct	YRR 175	YR 175	YRR 175 Ct	2nd Yaw Peak	2nd Yaw Peak Ct	Lat Disp	Lat. Acc. 1.07	1st SWA Peak	1st SWA Peak Ct	2nd SWA Mean
	(deg)	(mph)	(s)		(s)		(sec)	(%)	(deg/s)		(%)	(deg/s)		(deg/s)		(ft)	(g)	(deg)		(deg)
22	710	49.9	3.5	1091	5.4	847	4.2	-1.3	-0.2	1291	-1.0	-0.1	1441	12.6	953	-3.9	0.4	45.0	775	44.9
23	709	50.0	3.5	1091	5.4	847	4.2	-1.2	-0.2	1291	-0.3	0.0	1441	16.2	939	-5.3	0.5	60.1	775	59.8
24	708	49.7	3.5	1090	5.4	847	4.2	-1.2	-0.2	1290	-1.1	-0.2	1440	19.8	932	-6.4	0.6	75.0	776	74.8
25	707	49.9	3.5	1090	5.4	846	4.2	-1.0	-0.2	1290	-0.8	-0.2	1440	23.6	926	-7.5	0.7	89.9	775	89.7
26	707	49.8	3.5	1090	5.4	847	4.2	-0.8	-0.2	1290	0.1	0.0	1440	26.5	923	-8.4	0.7	104.8	775	104.6
27	707	49.9	3.5	1090	5.4	846	4.2	-1.2	-0.3	1290	-0.4	-0.1	1440	29.6	917	-9.2	0.7	119.9	775	119.5
28	706	49.9	3.5	1090	5.4	846	4.2	-0.6	-0.2	1290	0.1	0.0	1440	33.4	916	-9.6	0.7	134.9	775	134.4
29	706	49.9	3.5	1090	5.4	846	4.2	-0.7	-0.3	1290	0.0	0.0	1440	37.0	916	-10.2	0.8	149.8	775	149.4
30	706	49.9	3.5	1090	5.4	846	4.2	-0.1	-0.1	1290	-0.1	0.0	1440	39.3	916	-10.3	8.0	163.9	775	163.4
31	706	49.8	3.5	1090	5.4	846	4.2	0.9	0.4	1290	-0.1	-0.1	1440	42.6	917	-10.7	0.8	178.9	775	178.4
32	706	50.0	3.5	1090	5.4	847	4.2	0.8	0.4	1290	-1.3	-0.6	1440	44.4	918	-10.7	0.8	193.8	775	193.5
33	706	50.0	3.5	1090	5.4	847	4.2	1.6	0.8	1290	0.0	0.0	1440	47.3	920	-10.9	0.8	208.7	775	208.5
34	706	50.0	3.5	1090	5.4	847	4.2	0.7	0.4	1290	-0.3	-0.2	1440	48.6	922	-11.1	8.0	223.8	775	223.6
35	706	50.0	3.5	1090	5.4	847	4.2	1.5	0.7	1290	-0.6	-0.3	1440	49.3	920	-11.1	0.8	238.8	775	238.6
36	706	50.1	3.5	1090	5.4	846	4.2	5.7	3.0	1290	-0.2	-0.1	1440	52.8	921	-11.3	0.8	253.8	776	253.6
37	706	49.8	3.5	1090	5.4	847	4.2	1.8	1.0	1290	-0.3	-0.1	1440	52.7	918	-11.1	0.9	268.9	776	268.6
38	706	50.1	3.5	1090	5.4	847	4.2	1.8	1.0	1290	-0.5	-0.3	1440	55.2	921	-11.3	0.9	269.9	776	269.6

7.4 SINE WITH DWELL TEST RESULTS

2010 Nissan Altima Passenger Car

NHTSA No.: <u>CA5206</u>
Date of Test : <u>1/6/2010</u>
Date Created: <u>1/6/2010</u>

Lateral Stability Test Series No. 2 - Clockwise Initial Steer Direction

File	SWA @ 5deg Ct	MES	Time @ 5deg	cos	Time @ COS	MO S	Time @ MOS	YRR1	YR1	YRR 1 Ct	YRR 175	YR175	YRR17 5 Ct	2nd Yaw Peak	2nd Yaw Peak Ct	Lat Disp	Lat. Acc. 1.07 s	1st SWA Peak	1st SWA Peak Ct	2nd SWA Mean
	(deg)	(mph)	(s)		(s)		(sec)	(%)	(deg/s)		(%)	(deg/s)		(deg/s)		(ft)	(g)	(deg)		(deg)
39	710	49.9	3.5	1091	5.4	847	4.2	-1.0	0.1	1291	0.7	-0.1	1441	-12.2	941	4.3	-0.4	45.7	776	45.5
40	709	49.9	3.5	1090	5.4	847	4.2	-0.3	0.0	1290	-0.1	0.0	1440	-16.4	939	5.4	-0.5	60.5	776	60.5
41	708	49.9	3.5	1090	5.4	847	4.2	-0.8	0.2	1290	-0.5	0.1	1440	-20.3	929	6.5	-0.6	75.4	776	75.4
42	707	50.0	3.5	1090	5.4	847	4.2	-0.6	0.2	1290	-0.3	0.1	1440	-24.6	932	7.4	-0.7	90.3	775	90.5
43	707	49.6	3.5	1090	5.4	846	4.2	-0.7	0.2	1290	-0.5	0.1	1440	-28.8	926	8.3	-0.7	105.2	775	105.3
44	706	50.1	3.5	1090	5.4	847	4.2	-0.8	0.2	1290	-0.6	0.2	1440	-30.9	921	8.7	-0.8	120.2	776	120.4
45	706	49.9	3.5	1090	5.4	847	4.2	-0.7	0.2	1290	-0.4	0.2	1440	-35.6	920	9.5	-0.8	135.2	776	135.4
46	706	50.0	3.5	1090	5.4	847	4.2	-0.3	0.1	1290	0.2	-0.1	1440	-38.0	917	9.8	-0.8	150.3	775	150.3
47	706	49.9	3.5	1090	5.4	846	4.2	-0.4	0.2	1290	-0.3	0.1	1440	-42.7	921	10.1	-0.8	164.4	775	164.4
48	706	49.9	3.5	1090	5.4	847	4.2	-0.8	0.4	1290	-0.3	0.1	1440	-46.4	923	10.3	-0.8	179.6	775	179.3
49	706	50.0	3.5	1090	5.4	846	4.2	-0.1	0.0	1290	-0.2	0.1	1440	-48.1	923	10.6	-0.8	194.7	775	194.1
50	706	50.0	3.5	1090	5.4	847	4.2	0.7	-0.4	1290	0.0	0.0	1440	-51.5	923	10.8	-0.8	209.7	775	209.0
51	706	49.7	3.5	1090	5.4	847	4.2	-0.2	0.1	1290	-0.1	0.1	1440	-52.6	924	10.8	-0.8	224.8	775	224.1
52	706	49.9	3.5	1090	5.4	847	4.2	0.1	-0.1	1290	0.0	0.0	1440	-54.6	924	10.9	-0.8	239.7	775	239.2
53	706	50.0	3.5	1090	5.4	847	4.2	-0.2	0.1	1290	0.0	0.0	1440	-55.9	925	11.0	-0.8	254.6	776	254.2
54	706	49.6	3.5	1090	5.4	846	4.2	-0.3	0.1	1290	-0.2	0.1	1440	-57.0	924	11.0	-0.8	269.6	776	269.2
55	706	50.0	3.5	1090	5.4	847	4.2	0.0	0.0	1290	0.1	-0.1	1440	-56.3	924	11.0	-0.8	270.5	776	270.2

7.5 SLOWLY INCREASING STEER TEST RESULTS

2010 Nissan Altima Passenger Car

NHTSA No.: <u>CA5206</u>
Date of Test : <u>1/6/2010</u>
Date Created: <u>1/6/2010</u>

THETAENCF 3 AYCG CD2 3 r squared ZeroBegin ZeroEnd MES Mean SPD File EventPt DOS AYcount 3 (mph) (mph) (deg) (g) 10 700 50.87 50.15 1151 -30.13 -0.2947 0.9914 500 700 1 11 700 1 49.44 50.70 1137 -29.22 -0.2980 0.9973 500 700 12 29.96 700 0 50.27 50.19 1147 0.2981 0.9970 500 700 13 700 0 50.03 50.01 1139 29.61 0.2964 0.9954 500 700 16 700 0 50.16 49.78 1143 29.86 0.3002 0.9978 500 700 9 700 1 50.36 50.26 1163 -30.91 -0.3005 0.9834 500 700

Averages 29.9 0.2980

Scalars	Steering Angles (deg)
1.5	45
2.0	60
2.5	75
3.0	90
3.5	105
4.0	120
4.5	135
5.0	150

Scalars Steering Angles (deg) 5.5 164 6.0 179
5.5 164
6.0 179
•.•
6.5 194
7.0 209
7.5 224
8.0 239
8.5 254
9.0 269
270

7.6 INERTIAL SENSING SYSTEM LOCATION COORDINATES

Vehicle: **2010 Nissan Altima Passenger Car**Wheelbase: 105.3 Inches

NHTSA No.: CA5206

Faro Arm S/N: U08-05-08-06636

Measurement date: 1/5/2010 Certification date: 8/18/2009

CMM Measurements

Coordinate system: SAE (X,Y,Z positive forward, to the right, and downward, respectively)

Origin defined at 48" point on lateral arm of measurement fixture, projected onto the ground plane

	Ref X	Ref Y	Ref Z
M_PLANE001_Ground_Plane	-	-	0.000
M_Line_Y_Axis	2.393	-3.795	0.000
M_Point_48_Ref	0.000	0.000	-
M_CIRCLE001_I_Left_Rear_Wheel_Axle	-34.581	13.036	-12.474
M Point IMU side	3.784	45.888	-16.967
M_Point_ROOF	-	-	-57.516
Motion Pak reference point taken from mid height of unit left side			
Motion Pak Width = 3.05" ==> 1/2 W = 1.525			
Motion_PAK_Location	3.784	47.413	-16.967

Measurment Notes

- 1. The Faro arm is positioned just to the left of the vehicle, near the rear door.
- 2. A "centerline jig" is used in the Faro arm measurement. The jig consists of a long beam with a 4 ft lateral arm that is perpendicular to the beam. The jig is placed on the ground underneath the vehicle with the long beam positioned along the centerline of the vehicle, such that the lateral arm extends to the left, slightly forward of the left rear tire. The lateral arm has a marked indentation point which is located 48.00" from the edge of the centerline beam.
- 3. The Faro arm is used to make the following meaurements:
 - Three points on the ground, which establishes the ground plane.
 - Two points along the lateral arm, and projected onto the ground plane. This establishes the y axis.
 - One point at the 48 inch reference point on the lateral arm. This establishes the origin.
 - Three points on the left rear wheel or wheel cover. The Faro arm then computes the center point of the wheel.
 - One point to establish the height of the highest point on the roof of the vehicle.

Coordinate Measurements Calculated for S7D (Matlab Program)

Coordinate system: X,Y,Z positive rearward, to the right, and upward, respectively

Origin defined as follows: X axis: front axle, Y axis: vehicle centerline, Z axis: ground plane

	Ref X	Ref Y	Ref Z
Motion_PAK_Location in S7D (Matlab program) coordinate system	66.935	-0.587	16.967

Calculation Notes:

- 1. X axis value is the difference between the wheelbase and the calculated distance from the rear axle centerline to the IMU (the value must be positive and less than the wheelbase).
- 2. Y axis value is -48.00 (the Y axis offset of the measurement origin in the S7D coordinate system) plus the measured Y axis value (a negative value indicates the IMU is to the left of the vehicle centerline, and a positive value indicates it is to the right)
- 3. Z axis value is from the ground plane up to the center of the IMU (value must be positive).