126-DRI-11-009 **SAFETY COMPLIANCE TESTING FOR FMVSS 126 Electronic Stability Control Systems**

General Motors de Mexico, S. De R.L. DE C.V. 2011 GMC Sierra 1500 NHTSA No. CB0108

DYNAMIC RESEARCH, INC.

355 Van Ness Avenue, STE 200 Torrance, California 90501



1 December 2011

Final Report

Prepared Under Contract No.: DTNH22-08-D-00098

U. S. DEPARTMENT OF TRANSPORTATION **National Highway Traffic Safety Administration Enforcement** Office of Vehicle Safety Compliance 1200 New Jersey Avenue, SE West Building, 4th Floor (NVS-221) Washington, DC 20590

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		Sierra 1500 4WD Crew Cab, NHTSA No. CB		
	hicle Safety Compliance Test Proce eel drive and four wheel drive (high)	dure No. TP-126-02 for the determination of I modes.	FMVSS 126 compliance. The vehi	cle was tested in both two
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1.0 PURPOSE OF COMPLIANCE TEST

The purpose of this test is to determine if the test vehicle, a 2011 GMC Sierra 1500 4WD Crew Cab, meets the minimum equipment and performance requirements stated in Federal Motor Vehicle Safety Standard (FMVSS) 126, "Electronic Stability Control Systems." The vehicle was tested in both 2WD and 4WD (high) drive configurations.

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS

Testing of the 2011 GMC Sierra 1500 4WD Crew Cab was conducted at Dynamic Research, Inc (DRI) in accordance with NHTSA TP-126-02, dated November 19, 2008.

The vehicle was inspected to ensure it was equipped with an ESC system that:

- Augments vehicle directional stability by applying and adjusting brake torques individually at each wheel to induce a correcting yaw moment to a vehicle;
- Is computer controlled with the computer using a closed-loop algorithm to limit vehicle oversteer and to limit vehicle understeer;
- Has a means to determine the vehicle's yaw rate and to estimate its side slip or side slip derivative with respect to time;
- Has a means to monitor driver steering inputs;
- Has an algorithm to determine the need, and a means to modify engine torque, as necessary, to assist the driver in maintaining control of the vehicle; and
- Is operational over the full speed range of the vehicle (except at vehicle speeds less than 20 km/h (12.4 mph), when being driven in reverse, or during system initialization).

The vehicle was subjected to a 0.7 Hz Sine with Dwell steering maneuver to ensure that it would meet the stability and responsiveness requirements of the standard as follows:

 At 1.0 second after completion of a required Sine with Dwell steering input, the yaw rate of the vehicle must not exceed 35 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTINUED)

- At 1.75 seconds after completion of a required Sine with Dwell steering input, the yaw rate of the vehicle must not exceed 20 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).
- For steering inputs of scalar 5 and greater, the lateral displacement of the vehicle center of gravity with respect to its initial straight path must be at least 1.83 m (6 feet) (for vehicles with a GVWR of 3,500 kg (7,716 lb) or less) when computed 1.07 seconds after the Beginning of Steer (BOS) at the specified steering wheel angles.

System malfunction simulations were executed to verify vehicle could identify and indicate a malfunction.

The vehicle's ESC System appears to meet the performance and equipment requirements as required by FMVSS 126. The test results are summarized on the following summary sheet.

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTD)

Data Summary Sheet (Page 1 of 2)

Vehicle: 2011 GMC Sierra 1500 4WD (2WD and 4WD High Configurations)

NHTSA No. <u>CB0108</u> VIN: <u>3GTP2VE33BG386727</u>

Vehicle Type: *Truck* Manufacture Date: 7/11

Laboratory: Dynamic Research, Inc.

REQUIREMENTS: PASS/FAIL

ESC Equipment and Operational Characteristics (Data Sheet 2)

The vehicle is to be equipped with an ESC system that meets the equipment and operational characteristics requirements. (S126, S5.1, S5.6)

ESC Malfunction Telltale (Data Sheet 3)

Vehicle is equipped with a telltale that indicates one or more **PASS** ESC system malfunctions. (S126, S5.3)

"ESC Off" and other System Controls and Telltale (Data Sheet 3,4)

Vehicle is equipped with an ESC off telltale indicating the vehicle has been put into a mode that renders the ESC system unable to satisfy the performance requirements of the standard, if such a mode exists. (S5.5.1)

If provided, off control and other system controls as well as the ESC off telltale meets the operational requirements (S126, S5.4, S5.4.1,S5.4.2, S5.5.4, and S5.5.9)

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS (CONTD)

Data Summary Sheet (Page 2 of 2)

REQUIREMENTS:	PASS/FAIL
Vehicle Lateral Stability (Data Sheet 8) Yaw Rate Ratio at 1 second after COS is less than 35% of peak value. (S126, S5.2.1)	<u>PASS</u>
Yaw Rate Ratio at 1.75 seconds after COS is less than 20% of peak value. (S126, S5.2.2)	<u>PASS</u>
Vehicle Responsiveness (Data Sheet 8) Lateral displacement at 1.07 seconds after BOS is at least 1.83 m (6 feet) for vehicles with a GVWR of 3,500 kg (7,716 lb) or less, and 1.52 m (5 feet) for vehicles with a GVWR greater than 3,500 Kg (7,716 lb). (S126, S5.2.3)	<u>PASS</u>
ESC Malfunction Warning (Data Sheet 9)	
Warning is provided to driver after malfunction occurrence. (S126. S5.3)	<u>PASS</u>
Malfunction telltale stayed illuminated as long as malfunction existed and must extinguish after malfunction was corrected. (S126, S5.3.7)	<u>PASS</u>

3.0 TEST DATA

Data Sheet 1 (Page 1 of 2)
TEST VEHICLE INSPECTION AND TEST PREPARATION

Vehicle:	2011 GMC	Sierra 1500	0 4WD Crev	v Cab		
NHTSA N	lo. <i>CB01</i>	08	Data She	et Compl	etion Date:	<u>9/13/2011</u>
VIN <u>36</u>	GTP2VE33BG	386727	Manufactur	e Date:	<u>7/11</u>	
GVWR (k	g): <u>3175</u>	Front GA\	NR (kg): <u>1</u>	792	Rear GAW	R (kg): <u>1792</u>
_	ositions Fr	_			ar: <u>3</u>	
Odomete	r reading at ti	me of inspe	ction: <u>5</u>	miles (8	<u>km)</u>	
DESIGNA	TED TIRE SIZ	'E(S) FROM	VEHICLE L	ABELING:		
Fro	ont axle: <u><i>P275</i></u>	5/55R20	Rear ax	xle: <u><i>P275/</i></u>	<u>/55R20</u>	
INSTALLE	ED TIRE SIZE	(S) ON VEH	ICLE (from 1	tire sidewa	all)	
			Front	<u>Axle</u>	Re	ear Axle
	Tire Manufa	acturer:	Good	<u>year</u>	G	oodyear
	Tire	Model:	<u>Eagle</u>	<u>LS-2</u>	<u>Ea</u> ,	gle LS-2
	Ti	re Size:	P275/5	5R20	<u>P27</u>	75/55R20
TIN	Left Front:	M621 BCE	R 2611	Right Fr	ont: <u>M62</u> A	BCER 2611
	Left Rear:	M621 BCE	R 2611	Right R	Rear: <u>M62</u> A	BCER 2611
Are instal	led tire sizes	same as lab	eled tire siz	es? Yes	s	
lf no, con	tact COTR fo	or further gu	idance			
DRIVE CO	NFIGURATION	(S):(mark all	that apply)			
X Two \	Wheel Drive (2WD)	Front Who	eel Drive	X Rear V	Vheel Drive
All Wi	heel Drive (A\	WD)				
X Four Wheel Drive Automatic - differential no locked full time (4WD Automatic)						
Four Wheel Drive (High Gear Locked Differential 4WD HGLD)						
X Four \	Wheel Drive L	ow Gear (4)	WD Low)			
Other	(Describe)					

Data Sheet 1 (Page 2 of 2) TEST VEHICLE INSPECTION AND TEST PREPARATION

DRIVE CONFIGUR	ATIONS AND MODE	S: (ex. default, performa	ance, off)
(For each of the vehicle's drive configurations identify available operating modes)			e operating modes)
	Drive Configuration:	2WD	
	Modes:	ESC on (Default), ESC	<u>off</u>
	Drive Configuration:	<u>Auto</u>	
	Modes:	ESC on (Default), ESC	<u>off</u>
	Drive Configuration:	4WD High	
	Modes:	ESC on (Default), ESC	off
	Drive Configuration:	4WD Low	
	Mode:	ESC off	<u></u>
VEHICLE STABILIT	TY SYSTEMS (Check	applicable technologies):
List other systen	ns:		
X ESC	X Traction	n Control X	Roll Stability Control
Active Sus	pension X Electron	nic Throttle Control	Active Steering
X ABS			
REMARKS:			
RECORDED BY:	P Broen	DATE RECORDED:	9/13/2011
APPROVED BY:	B Kebschull	DATE APPROVED:	9/13/2011

Data Sheet 2 (Page 1 of 3) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab		
NHTSA No <u>CB0108</u> Data Sheet Completion Date: <u>8/31/2</u> 6	<u>011</u>	
ESC SYSTEM IDENTIFICATION Manufacturer/Model Robert Bosch LLC. / Bosch ESP Gen 8 ESC SYSTEM HARDWARE (Check applicable hardware) X Electronic Control Unit X Hydraulic Control Unit		
XWheel Speed SensorsXSteering Angle SensorXYaw Rate SensorXLateral Acceleration Sensor		
List other Components: Interface to engine management ECU		
ESC OPERATIONAL CHARACTERISTICS		
System is capable of generating brake torque at each wheel Brief explanation: To generate brake torque at each wheel, the ESC electronic control unit modulates electrical solenoids that open and close valves within the hydraulic control unit, which in turn controls brake fluid pressure to the foundation brake calipers located at the four wheels of the vehicle.	<u>X</u>	Yes (Pass) No (Fail)
System is capable of determining yaw rate Brief explanation: The component used to determine yaw rate is the yaw/lateral acceleration combination sensor, which is located under the passenger seat on the GMC Sierra. The yaw rate sensor is a gyroscopic device that measures the vehicle's angular velocity around its vertical axis. The signal from the yaw rate sensor is transmitted to the ESC electronic control unit for processing by the ESC control algorithm	<u>X</u>	Yes (Pass) No (Fail)
System is capable of monitoring driver steering input Brief explanation: Driver steering input is measured by a steering wheel angle sensor that is mounted on the steering column. The signal from the steering wheel angle sensor is transmitted to the ESC electronic control unit for processing by the ESC control algorithm.	X	Yes (Pass) No (Fail)

Data Sheet 2 (Page 2 of 3) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

ESC OPERATIONAL CHARACTERISTICS (continued)		
System is capable of estimating side slip or side slip derivative Brief explanation: Side slip and side slip derivative are calculated values within the ESC electronic control unit based on the following sensor inputs: four independent wheel speeds (from the wheel speed sensors mounted at each wheel), yaw rate (from the combination yaw/lateral acceleration sensor mounted underneath the front passenger seat), lateral acceleration (from the combination yaw/lateral acceleration sensor mounted underneath the front passenger seat), and steering wheel angle (from the steering wheel angle sensor mounted on the steering column).	X	Yes (Pass) No (Fail)
System is capable of modifying engine torque during ESC activation. Method used to modify torque: <u>During certain vehicle understeer</u> conditions vehicle speed may be reduced by reducing engine torque. In order to reduce engine torque, the ESC electronic control unit sends a signal to the powertrain control module requesting an appropriate percent reduction in engine torque. The powertrain control module provides the requested engine torque reduction using its own control algorithm with actuation that utilizes combinations of spark and throttle.	<u>X</u>	Yes (Pass) No (Fail)
System is capable of activation at speeds of 20 km/h (12.4 mph) and higher Speed system becomes active: 14.4 km/h	<u>x</u>	Yes (Pass) No (Fail)
System is capable of activation during the following driving phases: - acceleration - during activation of ABS or - braking traction control - coasting	<u>x</u>	Yes (Pass) No (Fail)

Data Sheet 2 (Page 3 of 3) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

ESC OPERATIONAL CHARACTERISTICS (continued)

Once the system is under driving phase during activation of being driven in revenue 14.4 km/h. Note that when the system is automate illuminated, and 'S Vehicle manufacture.	initializes after lives of accelerate of ABS or traction of ABS or traction of the following desired of the following the follow	is capable of activation: key-on, the ESC system is active ion, deceleration, coasting, and ion control, except if the vehicle is orward vehicle speed is less than 4-wheel drive low, the ESC f, the ESC off telltale is oFF' is displayed in the DIC. documentation explaining how the	_
ESC mitigates und	ersteer		— No (Fail)
		DATA INDICATES COMPLIANC	E: X Yes (Pass) No (Fail)
REMARKS:			
RECORDED BY:	J Lenkeit	DATE RECORDED: _ <i>8/</i>	/31/2011
APPROVED BY:	P Broen	DATE APPROVED: 8/	/31/2011

Data Sheet 3 (Page 1 of 2) ESC MALFUNCTION AND OFF TELLTALES

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab NHTSA No. CB0108 Data Sheet completion date: 9/13/2011 **ESC Malfunction Telltale** Vehicle is equipped with malfunction telltale? Yes Telltale Location: Left side of instrument cluster in the tachometer display Telltale Color: Yellow Telltale symbol or abbreviation used Vehicle uses this symbol or ESC Vehicle uses this abbreviation Neither symbol or abbreviation is used If different than identified above, make note of any message, symbol or abbreviation used. The ESC symbol above is enclosed in a triangle. The ESC symbol with triangle is illuminated and the message "SERVICE STABILITRAK" is displayed in the Driver Information Center (DIC) common display area located in the lower part of the tachometer. (see Figure 5.13) Is telltale part of a common space? No Is telltale also used to indicate activation of the ESC system? Yes If yes explain telltale operation during ESC activation: The "STABILITRAK" symbol (sliding car with triangle) flashes when ESC is activated

Data Sheet 3 (Page 2 of 2) ESC MALFUNCTION AND OFF TELLTALES

"ESC OFF" Telltale (if provided)

Vehicle is equipped with "ESC OFF" telltale? <u>Ye</u>	S
--	---

Is "ESC Off" telltale combined with "ESC Malfunction" telltale utilizing a two part telltale? Yes but the combined telltale is not a two part telltale utilizing the word "OFF" as shown in the symbol below.

Telltale Location	Left side of instrument cluster in the tachometer display
Telltale Color:	Yellow

Telltale symbol or abbreviation used

		Vehicle uses this symbol
33		Vehicle uses this abbreviation
	or ESC OFF	X Neither symbol or abbreviation is used
OFF		

If different than identified above, make note of any message, symbol or abbreviation used. <u>To identify an ESC off condition the ESC malfunction telltale is illuminated and the message "STABILITRAK OFF" is displayed in the Driver Information Center (DIC) common display area located in the lower part of the tachometer. (see Figure 5.13)</u>

Is telltale part of a common space? No

DATA INDICATES COMPLIANCE Yes

(Vehicle is compliant if equipped with a malfunction telltale)

Remarks:

The same sliding car symbol with triangle is used for ESC malfunction and ESC off. When the system is off the ESC malfunction illuminates and the message "Stabilitrak off" is displayed in the common space

RECORDED BY:	P Broen	DATE RECORDED:	9/13/2011
APPROVED BY:	B Kebschull	DATE APPROVED:	9/13/2011

Data Sheet 4 (Page 1 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

Vehicle: 2011 GMC Sierra 1:	500 4WD Crew Cab			
NHTSA No. <u>CB0108</u> Data Sheet completion date: <u>9/13/201</u>				
"ESC OFF" Controls Identific	ation and Operational Check:			
the ESC system or place the	a control or controls whose purpose is to deactivate ESC system in a mode or modes that may no ce requirements of the standard? X Yes No			
Type of control or controls provided? (mark all that apply)	Dedicated "ESC Off" Control X Multi-functional control with an "ESC Off" mode Other (describe)			
Identify each control location	n, labeling and selectable modes.			
First Control: Location	In the center of the dashboard (below the navigation display screen).			
Labeling	ESC symbol and an diagonal line through the symbol			
Modes	(Figure 5.14) 3 modes: 1. Traction Control and ESC on. 2. Traction control off. 3. Traction control and ESC off			
Identify standard or default of	Irive configuration RWD (2WD)			
Verify standard or default dri	ve configuration X Yes No			
	lluminate upon activation of the dedicated ESC off SC Off" mode on the multi-function control?			
	NA <u>X</u> Yes No (Fail)			
	extinguish when the ignition is cycled from "on" and then back again to the "On" ("Run") position?			
NAX Yes No (Fail) f no, describe how the "Off" control functions				

Data Sheet 4 (Page 2 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

If a multi-function control is provided, cycle through each mode setting on the control and record which modes illuminate the "ESC Off" telltale. Also, for those modes that illuminate the ESC Off" telltale identify if the telltale extinguishes upon cycling the ignition system.

	"ESC Off" telltale	"ESC Off" telltale
	illuminates upon	extinguishes
	activation of	upon cycling
Control Mode	control? (Yes/No)	ignition? (Yes/No)
Traction Control Off	Yes	Yes
Traction Control and ESC Off	Yes	Yes

For each mode that illuminates the "ESC Off" telltale, did to	:he tellta	le extinguis	h
when the ignition was cycled from "On" ("Run") to "Lock"	or "Off	" and then	back
again to the "On" ("Run") position?	NA	X Yes	No

Other System Controls that have an ancillary effect on ESC Operation:

Is the vehicle equipped with any ancillary controls that upon activation may deactivate the ESC system or place the ESC system in a mode or modes that may no longer satisfy the performance requirements of the standard? X Yes No

Ancillary Control: System <u>4WD Low transfer case selection</u>
Control Description <u>Transfer case selector</u>

Labeling <u>Selector-symbol with 2 axles, "4" with down arrow</u>
(see Figure 5.15)

Activate each ancillary control listed above and record whether the control illuminates the "ESC Off" telltale. Also, record warnings or messages provided regarding the ESC system.

	Control	
	Activates "ESC Off"	
Ancillary Control	Telltale? (Yes/No)	Warnings or Messages Provided
4WD Low transfer	Vaa	"STABILITRAK OFF" and "TRACTION
case selection	<u>Yes</u>	CONTROL OFF" in DIC

Data Sheet 4 (Page 3 of 3) ESC AND ANCILLARY SYSTEM CONTROLS

For those controls that illuminate the "ESC Off" telltale above identify if the "ESC Off" telltale extinguishes upon cycling the ignition system.

	"ESC Off" telltale extinguishes		
Ancillary Control	upon cycling ignition? (Yes/No)		
4WD Low transfer	A/-		
case selection	<u>No</u>		

For each ancillary control that illuminates the "ESC Off" telltale, did the telltale extinguish when the ignition is cycled from "On" ("Run") to "Lock" or "Off" and then back again to the "On" ("Run") position? If activating the control places the vehicle into a low-range four-wheel drive configuration designed for low-speed, off-road driving, the ESC system may remain turned off after the ignition has been cycled off and then back on and therefore the "ESC Off" telltale may not extinguish.

extinguish.						
		Yes	X	No (See rem	arks)	NA
	DAT	A INDIC	ATE	S COMPLIAN	CE: PA	SS
Remarks:						
Activating the 4W	D Low transfer cas	se select	tion c	control placed	the vehicle	into low-
range four-wheel d	Irive configuration	designe	d for	low-speed, o	ff-road driv	ing. The
ESC system remail	ned turned off afte	r the igi	nition	had been cy	cled off and	then
back on and therei	fore the "ESC Off"	telltale	did n	ot extinguish	. This condi	ition is
allowed by FMVSS	S No. 126 for the 4	WD Lo	w dri	ve configurati	on	
RECORDED BY:	B Kebschull	D	ATE	RECORDED:	9/13/201	1
APPROVED BV:	P Rroan		ΔTF	ΔPPR∩\/FD·	9/13/201	1

Data Sheet 5 (Page 1 of 3) TEST TRACK AND VEHICLE DATA

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab (2WD Drive Configuration) NHTSA No. CB0108 Data Sheet completion date: 9/13/2011 **Test Track Requirements:** Test surface slope (0-1%): 0.5% Peak Friction Coefficient (at least 0.9) 0.951 Test track data meets requirements: Yes If no, explain: **Full Fluid Levels:** Fuel Yes Other Fluids Yes (specify) Coolant Yes Oil, Washer Fluid, Brake Fluid **Tire Pressures:** Front Axle 210 kPa Rear Axle 210 kPa Required; Actual; LF *210* kPa RF *210* kPa LR 210 kPa RR 210 kPa Vehicle Dimensions: Front Track Width 172.2 cm Wheelbase 365.3 cm Rear Track Width 170.2 cm **Vehicle Weight Ratings:** GAWR Front 1792 GAWR Rear *1792* kg kg **Unloaded Vehicle Weight (UVW):** Front Axle 1451.5 kg Left Front *740.7* kg Right Front 710.8 kg *1021.0* kg Left Rear *510.3* kg Right Rear *510.7* Rear Axle kg Total UVW 2472.5 kg Baseline Weight and Outrigger Selection (only for MPVs, Trucks, Buses) Calculated baseline weight (UVW + 73kg) *2545.5* kg Outrigger size required ("Standard" or "Heavy") Standard Standard - Baseline weight under 2772 kg (6000 lb) Heavy - Baseline weight equal to or greater than 2772 kg (6000 lb)

Data Sheet 5 (Page 2 of 3) TEST TRACK AND VEHICLE DATA

UVW with Outriggers: (only for MPVs, Trucks, Buses)

Front axle 1476.0 kg Left front 759.3 kg Right front 716.7 kg

Rear axle 1059.5 kg Left rear 517.5 kg Right rear 542.0 kg

Total UVW with outriggers 2535.5 kg

Loaded Vehicle Weight w/Driver and Instrumentation (no Ballast)

Front axle <u>1557.2</u> kg Left front <u>812.4</u> kg Right front <u>744.8</u> kg

Rear axle <u>1109.1</u> kg Left rear <u>555.7</u> kg Right rear <u>553.4</u> kg

Vehicle Weight <u>2666.3</u> kg

Total Loaded Vehicle Weight w/Driver and Instrumentation and Ballast

Front axle <u>1578.1</u> kg Left front <u>814.7</u> kg Right front <u>763.4</u> kg

Rear axle <u>1125.4</u> kg Left rear <u>562.9</u> kg Right rear <u>562.5</u> kg

Total UVW <u>2703.5</u> kg

Data Sheet 5 (Page 3 of 3) TEST TRACK AND VEHICLE DATA

Center of Gravity and Inertial Sensing System Location at Loaded Vehicle Condition:

x-distance (longitudinal) Point of reference is the front axle centerline.

(Positive from front axle toward rear of vehicle.)

y-distance (lateral) Point of reference is the vehicle centerline.

(Positive from the center toward the right.)

z-distance (vertical) Point of reference is the ground plane.

(Positive from the ground up.)

Locations:

Center of Gravit	У	Inertial	Sensing S	<u>System</u>
x-distance	_ cm _	72.3	in <u>183</u>	<u>8.6</u> cm
y-distance0.6_ in1.6	_ cm	-1.8	in4	<u>1.5</u> cm
z-distance <u>28.1</u> in <u>71.3</u>	_ cm	28.2	in <i>71</i>	<u>'.5</u> cm
Roof H	leight 73.844	in	187.6	cm
Distance between ultrasonic senso	ors <u>85.8</u>	in	217.8	cm

Remarks:

RECORDED BY: B Kebschull DATE RECORDED: 9/13/2011
APPROVED BY: P Broen DATE APPROVED: 9/13/2011

Data Sheet 5 (Supplemental) (Page 1 of 1) TEST TRACK AND VEHICLE DATA

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab (4WD Drive Configuration)

NHTSA No. CB0108 Data Sheet completion date: 9/14/2011

Test Track Requirements: Test surface slope (0-1%): <u>0.5%</u>

Peak Friction Coefficient (at least 0.9) <u>0.928</u>

Test track data meets requirements: <u>Yes</u> If no, explain:

Full Fluid Levels: Fuel <u>Yes</u> Other Fluids <u>Yes</u> (specify)

Coolant Yes Oil, Washer Fluid, Brake Fluid

Tire Pressures:

Required; Front Axle 210 kPa Rear Axle 210 kPa

Actual; LF <u>210</u> kPa RF <u>210</u> kPa

LR <u>210</u> kPa RR <u>210</u> kPa

RECORDED BY: B Kebschull DATE RECORDED: 9/14/2011

APPROVED BY: <u>J Lenkeit</u> DATE APPROVED: <u>9/16/2011</u>

Data Sheet 6 (Page 1 of 6) BRAKE AND TIRE CONDITIONING

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab (2WD Drive Configuration)

NHTSA No. CB0108

Measured tire pressure: LF 218 kPa RF 215 kPa

LR <u>214</u> kPa RR <u>215</u> kPa

Wind Speed \underline{O} m/s (10 m/sec (22 mph) max for passenger cars; 5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 27 °C

Brake Conditioning Time: 8:50:00 AM Date: 9/13/2011

56 km/h (35 mph) Brake Stops

Number of stops executed (10 required) $\underline{10}$ Stops

Observed deceleration range (0.5g target) <u>0.45 - 0.55</u> g

72 km/h (45 mph) Brake Stops

Number of stops executed (3 required) 3 Stops

Number of stops ABS activated (3 required) 3 Stops

Observed deceleration range 0.85 - 0.95 g

72 km/h (45 mph) Brake Cool Down Period

Duration of cool down period (5 minutes min.) 5 Minutes

Data Sheet 6 (Page 2 of 6) BRAKE AND TIRE CONDITIONING

Tire Conditioning series No. 1 Time: 9:00:00 AM Date: 9/13/2011

Measured cold tire pressure LF 227 kPa RF 227 kPa

LR 223 kPa RR 225 kPa

Wind Speed ____1 __ m/s (10 m/sec (22 mph) max for passenger cars;

5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 28°C

30 meter (100 ft) Diameter Circle Maneuver					
Test Run	Steering Direction	Target Lateral Acceleration (g)	Observed Lateral Acceleration (g)	Observed Vehicle Speed (km/h)	
1-3	Clockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 30.4 - 32</u>	
4-6	Counterclockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 30.4 - 32</u>	

	5-1 Hz Cycle Sinusoidal Steering Maneuver to Determine Steering Wheel Angle for 0.5-0.6 g Lateral Acceleration					
Test Run	Data File	Vehicle Speed km/h(mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)	
1	2	56 ± 2 (35 ± 1)	<u>60</u>	0.5 - 0.6	<u>0.33</u>	
2	3	56 ± 2 (35 ± 1)	<u>100</u>	0.5 - 0.6	<u>0.55</u>	
3		56 ± 2 (35 ± 1)		0.5 - 0.6		
4		56 ± 2 (35 ± 1)		0.5 - 0.6		

Steering wheel angle that corresponds to a peak 0.5-0.6 g lateral acceleration: 100 degrees

	10-1 Hz Cycle Sinusoidal Steering Maneuver					
Test Run	Data File	Vehicle Speed km/h (mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)	
1-3	<u>4-6</u>	56 ± 2 (35 ± 1)	100 (cycles 1-10)	0.5 - 0.6	<u>0.55</u>	
4	7	FC + 2 (2F + 1)	<u>100</u> (cycles 1-9)	0.5 - 0.6	<u>0.55</u>	
4	<u>/</u>	56 ± 2 (35 ± 1)	<u>200</u> (cycle10) *	NA	<u>0.74</u>	

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9

Data Sheet 6 (Page 3 of 6) BRAKE AND TIRE CONDITIONING

Tire Conditioning series No. 2 Time: 10:11:00 AM Date: 9/13/2011

Measured cold tire pressure LF 236 kPa RF 236 kPa

LR <u>228</u> kPa RR <u>232</u> kPa

Wind Speed 0.5 m/s (10 m/sec (22 mph) max for passenger cars;

5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 29 °C

30 meter (100 ft) Diameter Circle Maneuver					
Test Run Steering Direction Target Lateral Acceleration (g) Observed Lateral Acceleration (g) Speed (km/h)					
1-3	Clockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 30.4 - 32</u>	
4-6	Counterclockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 30.4 - 32</u>	

Steering wheel angle that corresponds to a peak 0.5-0.6 g lateral acceleration: 100 degrees

10-1 Hz Cycle Sinusoidal Steering Maneuver							
Test Run	Data File	Vehicle Speed km/h (mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)		
1-3	<u>16-18</u>	56 ± 2 (35 ± 1)	100 (cycles 1-10)	0.5 - 0.6	<u>0.55</u>		
4	10 50 . 0 (05 . 1)	E6 + 2 /2E + 1)	100 (cycles 1-9)	0.5 - 0.6	<u>0.55</u>		
4 15	<u>19</u>	56 ± 2 (35 ± 1)	200 (cycle 10)*	NA	<u>0.74</u>		

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9

Remarks	:
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RECORDED BY: B Kebschull DATE RECORDED: 9/13/2011
APPROVED BY: J Lenkeit DATE APPROVED: 9/16/2011

Data Sheet 6 (Page 4 of 6) BRAKE AND TIRE CONDITIONING

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab (4WD Drive Configuration)

NHTSA No. CB0108

Measured tire pressure: LF 216 kPa RF 217 kPa

LR 214 kPa RR 215 kPa

Wind Speed $\underline{1}$ m/s (10 m/sec (22 mph) max for passenger cars; 5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 24 °C

Brake Conditioning Time: 8:43:00 AM Date: 9/14/2011

56 km/h (35 mph) Brake Stops

Number of stops executed (10 required) 10 Stops

Observed deceleration range (0.5g target) 0.45 - 0.55 g

72 km/h (45 mph) Brake Stops

Number of stops executed (3 required) 3 Stops

Number of stops ABS activated (3 required) <u>3</u> Stops

Observed deceleration range 0.85 - 0.95 g

72 km/h (45 mph) Brake Cool Down Period

Duration of cool down period (5 minutes min.) 5 Minutes

Data Sheet 6 (Page 5 of 6) BRAKE AND TIRE CONDITIONING

Tire Conditioning series No. 1 Time: 8:53:00 AM Date: 9/14/2011

Measured cold tire pressure LF 228 kPa RF 230 kPa

LR 223 kPa RR 226 kPa

Wind Speed ___1 _ m/s (10 m/sec (22 mph) max for passenger cars;

5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 26°C

30 meter (100 ft) Diameter Circle Maneuver							
Test Run	Test Run Steering Direction		Observed Lateral Acceleration (g)	Observed Vehicle Speed (km/h)			
1-3	Clockwise	0.5 - 0.6	<u> 0.5 - 0.6</u>	<u> 30.4 - 32</u>			
4-6	Counterclockwise	0.5 - 0.6	<u> 0.5 - 0.6</u>	<u> 30.4 - 32</u>			

	5-1 Hz Cycle Sinusoidal Steering Maneuver to Determine Steering Wheel Angle for 0.5-0.6 g Lateral Acceleration								
Test Run	Data File	Vehicle Speed km/h(mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)				
1	2	56 ± 2 (35 ± 1)	<u>60</u>	0.5 - 0.6	<u>0.33</u>				
2	3	56 ± 2 (35 ± 1)	<u>100</u>	0.5 - 0.6	<u>0.51</u>				
3		56 ± 2 (35 ± 1)		0.5 - 0.6					
4		56 ± 2 (35 ± 1)		0.5 - 0.6					

Steering wheel angle that corresponds to a peak 0.5-0.6 g lateral acceleration: 100 degrees

	10-1 Hz Cycle Sinusoidal Steering Maneuver							
Test Run	Data File	Vehicle Speed km/h (mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)			
1-3	<u>4-6</u>	56 ± 2 (35 ± 1)	100 (cycles 1-10)	0.5 - 0.6	<u>0.51</u>			
4	<u>7</u> 56 ± 2 (35 ± 1	FC + 2 (2F + 1)	<u>100</u> (cycles 1-9)	0.5 - 0.6	<u>0.51</u>			
4		56 ± 2 (35 ± 1)	<u>200</u> (cycle10) *	NA	<u>0.75</u>			

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9

Data Sheet 6 (Page 6 of 6) BRAKE AND TIRE CONDITIONING

Tire Conditioning series No. 2 Time: 10:23:00 AM Date: 9/14/2011

Measured cold tire pressure LF 234 kPa RF 235 kPa

LR <u>225</u> kPa RR <u>228</u> kPa

Wind Speed 1 m/s (10 m/sec (22 mph) max for passenger cars;

5m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 28 °C

30 meter (100 ft) Diameter Circle Maneuver							
Test Run	Steering Direction	Target Lateral Acceleration (g)	Observed Lateral Acceleration (g)	Observed Vehicle Speed (km/h)			
1-3	Clockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 30.4 - 32</u>			
4-6	Counterclockwise	0.5 - 0.6	<u>0.5 - 0.6</u>	<u> 30.4 - 32</u>			

Steering wheel angle that corresponds to a peak 0.5-0.6 g lateral acceleration: 100 degrees

10-1 Hz Cycle Sinusoidal Steering Maneuver							
Test Run	Data File	Vehicle Speed km/h (mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)		
1-3	<u>16-18</u>	56 ± 2 (35 ± 1)	100 (cycles 1-10)	0.5 - 0.6	<u>0.51</u>		
4	10 50	56 ± 2 (35 ± 1)	100 (cycles 1-9)	0.5 - 0.6	<u>0.51</u>		
4 <u>1</u>	<u>19</u>		200 (cycle 10)*	NA	<u>0.75</u>		

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9

Remarks:			

RECORDED BY: B Kebschull DATE RECORDED: 9/14/2011
APPROVED BY: J Lenkeit DATE APPROVED: 9/16/2011

Data Sheet 7 (Page 1 of 4) SLOWLY INCREASING STEER (SIS) MANEUVER (2WD)

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab (2WD Drive Configuration)

NHTSA No. <u>CB0108</u>

Measured tire pressure: LF 232 kPa RF 232 kPa

LR <u>225</u> kPa RR <u>229</u> kPa

Wind Speed 1 m/s

(10 m/sec (22 mph) max for passenger cars; 5 m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 28 °C

Selected drive configuration RWD

Selected Mode: Default

Preliminary Left Steer Maneuver:

Lateral Acceleration measured at 30 degrees steering wheel angle

 $a_{y,30 \text{deg}rees} =$ **0.25** g

Assuming a linear relationship the following ratio should be used to calculate the steering wheel angle at 0.55g:

$$\frac{30 \text{ degrees}}{a_{y,30 \text{ degrees}}} = \frac{\delta_{SIS}}{0.55 \text{ g}}$$

$$\frac{\delta_{sis} = 66.0 \text{ degrees (@.55g)}}{\delta_{sis} = 70 \text{ degrees (rounded)}}$$

Steering Wheel Angle at Corrected 0.3g Lateral Acceleration:

	J	Time Clock	Steering Wheel Angle		
	Initial Steer	(5 min max	to nearest	Data	
Maneuver	Direction	between runs)	0.1° (degrees)	Run	Good/NG
1	Left	<u>9:36</u>	<u>-41.2</u>	<u>10</u>	Good
2	Left	<u>9:39</u>	<u>-41.1</u>	<u>11</u>	<u>Good</u>
3	Left	<u>9:43</u>	<u>-41.8</u>	<u>12</u>	<u>Good</u>
4	Left				
5	Left				
1	Right	<u>9:47</u>	<u>39.5</u>	<u>13</u>	Good
2	Right	<u>9:50</u>	<u>39.8</u>	<u>14</u>	Good
3	Right	<u>9:54</u>	<u>40.1</u>	<u>15</u>	Good
4	Right				
5	Right				

Data Sheet 7 (Page 2 of 4) SLOWLY INCREASING STEER (SIS) MANEUVER (2WD)

Average Overall Steering Wheel Angle:

$$\delta_{0.3 \ g, \ overall} = (\mid \delta_{0.3 \ g, \ left \, (1)} \mid + \mid \delta_{0.3 \ g, \ left \, (2)} \mid + \mid \delta_{0.3 \ g, \ left \, (3)} \mid + \delta_{0.3 \ g, \ right \, (1)} + \delta_{0.3 \ g, \ right \, (2)} + \delta_{0.3 \ g, \ right \, (3)}) / 6$$

$$\delta_{0.3 \ g, \ overall} = \underline{\qquad 40.6 \qquad} \quad \text{degrees}$$
[to nearest 0.1 degree]

Rem	arks:		

RECORDED BY: B Kebschull DATE RECORDED: 9/13/2011
APPROVED BY: P Broen DATE APPROVED: 9/13/2011

Data Sheet 7 (Page 3 of 4) SLOWLY INCREASING STEER (SIS) MANEUVER (4WD)

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab (4WD Drive Configuration)

NHTSA No. CB0108

Measured tire pressure: LF 231 kPa RF 233 kPa

LR <u>224</u> kPa RR <u>227</u> kPa

Wind Speed 1 m/s

(10 m/sec (22 mph) max for passenger cars; 5 m/sec (11 mph) max for MPVs and trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 27 °C

Selected drive configuration 4WD High

Selected Mode: Nominal

Preliminary Left Steer Maneuver:

Lateral Acceleration measured at 30 degrees steering wheel angle

 $a_{y,30 \text{deg}rees} =$ **0.25** g

Assuming a linear relationship the following ratio should be used to calculate the steering wheel angle at 0.55g:

$$\frac{30 \text{ degrees}}{a_{y,30 \text{ degrees}}} = \frac{\delta_{SIS}}{0.55 \text{ g}}$$

$$\frac{\delta_{sis} = 66.0 \text{ degrees (@.55g)}}{\delta_{sis} = 70 \text{ degrees (rounded)}}$$

Steering Wheel Angle at Corrected 0.3g Lateral Acceleration:

			i		
		Time Clock	Steering Wheel Angle		
	Initial Steer	(5 min max	to nearest	Data	
Maneuver	Direction	between runs)	0.1° (degrees)	Run	Good/NG
1	Left	<u>9:56</u>	<u>-41.9</u>	<u>10</u>	<u>Good</u>
2	Left	<u>9:59</u>	<u>-42.3</u>	<u>11</u>	<u>Good</u>
3	Left	<u>10:02</u>	<u>-42.1</u>	<u>12</u>	Good
4	Left				
5	Left				
1	Right	<u>10:05</u>	<u>41.6</u>	<u>13</u>	Good
2	Right	<u>10:10</u>	<u>41.3</u>	<u>14</u>	Good
3	Right	<u>10:13</u>	<u>41.3</u>	<u>15</u>	Good
4	Right				
5	Right				

Data Sheet 7 (Page 4 of 4) SLOWLY INCREASING STEER (SIS) MANEUVER (4WD)

Average Overall Steering Wheel Angle:

$$\delta_{0.3 \ g, \ overall} = (\mid \delta_{0.3 \ g, \ left \, (1)} \mid + \mid \delta_{0.3 \ g, \ left \, (2)} \mid + \mid \delta_{0.3 \ g, \ left \, (3)} \mid + \delta_{0.3 \ g, \ right \, (1)} + \delta_{0.3 \ g, \ right \, (2)} + \delta_{0.3 \ g, \ right \, (3)}) / 6$$

$$\delta_{0.3 \ g, \ overall} = \underline{\qquad 41.7 \qquad} \text{degrees}$$
[to nearest 0.1 degree]

Remarks:			

RECORDED BY: B Kebschull DATE RECORDED: 9/14/2011
APPROVED BY: J Lenkeit DATE APPROVED: 9/16/2011

Data Sheet 8 (Page 1 of 6) VEHICLE LATERAL STABILITY AND RESPONSIVENESS (2WD)

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab (2WD Drive Configuration)								
NHTSA No. CB0108	ata sheet completio	n date: 9/13/2011						
Tire conditioning completed	X	X Yes No						
ESC system is enabled	Х	Yes No						
On track calibration checks have be	en completed	Yes No						
On track static data file for each se	nsor obtained	Yes No						
Selected Drive Configuration: 21	WD-RWD	<u> </u>						
Selected Mode: Default - ESC or	1	<u> </u>						
Overall steering wheel angle (δο.3 g, ον	verall) 40.6 degl	rees						

<u>Lateral Stability Test Series No. 1 – Counterclockwise Initial Steer Direction</u>

	Commanded		,	Yaw Rate	S	YRR		YRR		
	Clock	Steering	Wheel	(degrees/sec)		at 1.0 sec after		at 1.75 sec after		
Maneuver	Time	Ang	le¹				C	os	(cos
#							[<	35%]	[<	20%]
	(1.5 – 5.0 min max between runs)	Scalar (* δ _{0.3 g})	Angle (degrees)	$\dot{\psi}_{\it Peak}$	$\dot{\psi}_{1.0 \mathrm{sec}}$	$\dot{\psi}_{1.75 m sec}$	%	Pass/Fail	%	Pass/Fail
21	10:47	1.5	61	12.19	-0.29	-0.34	-2.34	<u>PASS</u>	-2.79	<u>PASS</u>
22	10:50	2.0	81	15.65	-0.27	-0.29	-1.76	<u>PASS</u>	-1.85	<u>PASS</u>
23	10:53	2.5	102	19.27	-0.25	-0.24	-1.31	<u>PASS</u>	-1.24	<u>PASS</u>
24	10:56	3.0	122	23.15	-0.19	-0.14	-0.81	<u>PASS</u>	-0.60	<u>PASS</u>
25	10:59	3.5	142	22.86	-0.16	-0.13	-0.68	<u>PASS</u>	-0.58	<u>PASS</u>
26	11:02	4.0	162	25.74	-0.35	-0.17	-1.38	<u>PASS</u>	-0.67	<u>PASS</u>
27	11:05	4.5	183	26.27	-0.19	-0.11	-0.73	PASS	-0.43	<u>PASS</u>
28	11:08	5.0	203	26.09	-0.39	-0.22	-1.50	PASS	-0.85	<u>PASS</u>
29	11:11	5.5	223	27.94	-0.39	-0.28	-1.38	<u>PASS</u>	-1.01	<u>PASS</u>
30	11:13	6.0	244	27.72	-0.49	-0.12	-1.78	PASS	-0.43	<u>PASS</u>
31	11:16	6.5	264	27.76	-0.43	-0.31	-1.54	<u>PASS</u>	-1.12	<u>PASS</u>
32	11:19	-	270	28.65	-0.12	-0.22	-0.42	<u>PASS</u>	-0.78	<u>PASS</u>

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5 *\delta_0.3 \, \text{o, overall} \ or 270 degrees is utilized, whichever is greater provided the calculated magnitude of 6.5 *\delta_0.3 \, \text{o, overall} \ is less than or equal to 300 degrees. If 6.5 *\delta_0.3 \, \text{g, overall} \ is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5 *\delta_0.3 \, \text{g, overall} \ without exceeding the 270 degree steering wheel angle.

Data Sheet 8 (2 of 6) VEHICLE LATERAL STABILITY AND RESPONSIVENESS (2WD)

LATERAL STABILITY TEST SERIES NO. 2 - Clockwise Initial Steer Direction

	LATERIAL STABLETT TEST SERVES NO. 2 - Clockwise lintal Steel Direction										
		Comm	anded	,	Yaw Rates			YRR		YRR	
	Clock Steering Wheel		(degrees/sec)			at 1.0 sec after		at 1.75 sec after			
Maneuver	Time	Ang	-		J	•	(cos	COS		
#			5				_	35%]	[< 20%]		
	(1.5 – 5.0 min max between runs)	Scalar (* δο.3 g)	Angle (degrees)	$\dot{\psi}_{\scriptscriptstyle Peak}$	$\dot{\psi}_{1.0 \mathrm{sec}}$	$\dot{\psi}_{1.75 m sec}$	%	Pass/Fail	%	Pass/Fail	
33	11:22	1.5	61	-12.25	0.08	0.10	-0.66	PASS	-0.85	PASS	
34	11:25	2.0	81	-16.04	0.14	0.12	-0.86	PASS	-0.78	PASS	
35	11:28	2.5	102	-19.57	0.20	0.03	-1.02	PASS	-0.16	PASS	
36	11:31	3.0	122	-23.21	0.15	0.00	-0.65	<u>PASS</u>	0.02	<u>PASS</u>	
37	11:34	3.5	142	-23.53	0.19	0.22	-0.82	<u>PASS</u>	-0.95	<u>PASS</u>	
38	11:37	4.0	162	-24.53	0.31	0.07	-1.25	<u>PASS</u>	-0.27	<u>PASS</u>	
39	11:40	4.5	183	-26.82	0.27	0.20	-1.01	<u>PASS</u>	-0.76	<u>PASS</u>	
40	11:43	5.0	203	-28.07	0.18	-0.07	-0.63	<u>PASS</u>	0.23	<u>PASS</u>	
41	11:46	5.5	223	-27.38	0.43	0.18	-1.58	<u>PASS</u>	-0.67	<u>PASS</u>	
42	11:50	6.0	244	-28.33	0.27	0.04	-0.97	<u>PASS</u>	-0.16	<u>PASS</u>	
43	11:53	6.5	264	-29.27	0.37	0.13	-1.26	<u>PASS</u>	-0.44	<u>PASS</u>	
44	11:56	-	270	-28.48	0.30	0.16	-1.06	<u>PASS</u>	-0.55	<u>PASS</u>	

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5*\delta_0.3 g, overall or 270 degrees is utilized, whichever is greater provided the calculated 6.5*\delta_0.3 g, overall is less than or equal to 300 degrees. If 6.5*\delta_0.3 g, overall is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5*\delta_0.3 g, overall without exceeding the 270 degree steering wheel angle.

During execution of the Sine with Dwell maneuvers were any of the

following events observed?		_		
Rim-to-pavement contact		Yes	X	No
Tire debeading		Yes	X	No
Loss of pavement contact of vehicle tires	X	Yes		No
Did the test driver experience any vehicle		Yes	X	No
loss of control or spinout?				
If "Yes" explain the event and consult with th	e C	OTR.		

Data Sheet 8 (3 of 6) VEHICLE LATERAL STABILITY AND RESPONSIVENESS (2WD)

Responsiveness – Lateral Displacement

DATA INDICATES COMPLIANCE:

		Commanded S	•	Calculated Lateral Displacement ¹		
Maneuver	Initial Steer	Ang (5.0*δο.3 g, overa	•			
# Direction		Scalar *80.3 g	Angle (degrees)	Distance (m)	Pass/Fail	
28	Counter Clockwise	5.0	203	-2.45	PASS	
29	Counter Clockwise	5.5	223	-2.58	PASS	
30	Counter Clockwise	6.0	244	-2.53	<u>PASS</u>	
31	Counter Clockwise	6.5	264	-2.44	<u>PASS</u>	
32	Counter Clockwise	-	270	-2.52	<u>PASS</u>	
40	Clockwise	5.0	203	2.41	<u>PASS</u>	
41	Clockwise	5.5	223	2.39	<u>PASS</u>	
42	Clockwise	6.0	244	2.40	<u>PASS</u>	
43	Clockwise	6.5	264	2.46	<u>PASS</u>	
44	Clockwise	-	270	2.40	<u>PASS</u>	

^{1.} Lateral displacement should be \geq 1.83 m (6 ft) for vehicle with a GVWR of 3,500 kg (7,716 lb) or less; and \geq 1.52 m (5 ft) for vehicles with GVWR greater than 3,500 kg (7,716 lb).

☑ PASS

☐ FAIL

Remarks: During F	Run 30 the	e right front	wheel lifted bi	riefly approx	imately 1 inch

from pavement on reversal as determined by visual observation.

RECORDED BY: $P \ Broen$ DATE RECORDED: 9/13/2011 APPROVED BY: $B \ Kebschull$ DATE APPROVED: 9/13/2011

Data Sheet 8 (Page 4 of 6) VEHICLE LATERAL STABILITY AND RESPONSIVENESS (4WD)

Vehicle: 2011 GMC Sierra 1500 4WD C	Crew Cab	(4WD Drive	e Config	uration)
NHTSA No. CB0108	Oata sheet o	completion	date:	9/14/2011
Tire conditioning completed		X	Yes	No
ESC system is enabled		X	Yes	No
On track calibration checks have be	een comple	ted X	Yes	No
On track static data file for each se	ensor obtain	ned X	Yes	No
Selected Drive Configuration: 4	WD High			
Selected Mode: Default - ESC o	n			
Overall steering wheel angle (δ0.3 g, o	overall) 41	.7 degre	es	

Lateral Stability Test Series No. 1 - Counterclockwise Initial Steer Direction

Commanded		anded	Yaw Rates			YRR		YRR		
	Clock	Clock Steering Wheel		(degrees/sec)			at 1.0 sec after		at 1.75 sec after	
Maneuver	Time	Ang	Jle¹				C	cos	cos	
#		_					[<	35%]	[< 20%]	
	(1.5 – 5.0 min max between runs)	Scalar (* δ _{0.3 g})	Angle (degrees)	$\dot{\psi}_{\it Peak}$	$\dot{\psi}_{1.0\mathrm{sec}}$	$\dot{\psi}_{1.75 \mathrm{sec}}$	%	Pass/Fail	%	Pass/Fail
22	10:49	1.5	63	12.53	-0.04	-0.05	-0.34	<u>PASS</u>	-0.39	<u>PASS</u>
23	10:52	2.0	83	16.06	-0.10	-0.18	-0.61	<u>PASS</u>	-1.11	<u>PASS</u>
24	10:55	2.5	104	19.29	-0.26	-0.16	-1.32	<u>PASS</u>	-0.83	<u>PASS</u>
25	10:59	3.0	125	23.09	-0.30	-0.28	-1.28	<u>PASS</u>	-1.21	<u>PASS</u>
26	11:02	3.5	146	22.67	-0.43	-0.42	-1.88	PASS	-1.86	<u>PASS</u>
27	11:06	4.0	167	25.36	-0.38	-0.15	-1.51	<u>PASS</u>	-0.58	<u>PASS</u>
28	11:09	4.5	188	26.48	-0.31	-0.20	-1.16	PASS	-0.77	<u>PASS</u>
29	11:12	5.0	208	26.43	-0.39	-0.18	-1.48	PASS	-0.68	<u>PASS</u>
30	11:15	5.5	229	27.52	-0.62	-0.39	-2.26	<u>PASS</u>	-1.41	<u>PASS</u>
31	11:18	6.0	250	27.69	-0.27	-0.07	-0.96	PASS	-0.25	<u>PASS</u>
32	11:22	6.5	271	27.46	-0.38	-0.03	-1.38	<u>PASS</u>	-0.11	<u>PASS</u>

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5 *\delta_0.3 \, \text{o, overall} \) or 270 degrees is utilized, whichever is greater provided the calculated magnitude of 6.5 *\delta_0.3 \, \text{g, overall} \) is less than or equal to 300 degrees. If 6.5 *\delta_0.3 \, \text{g, overall} \) is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5 *\delta_0.3 \, \text{g, overall} \) without exceeding the 270 degree steering wheel angle.

Data Sheet 8 (5 of 6) VEHICLE LATERAL STABILITY AND RESPONSIVENESS (4WD)

LATERAL STABILITY TEST SERIES NO. 2 - Clockwise Initial Steer Direction

LATERAL STABILITY TEST SERIES NO. 2 - Clockwise Illitial Steer Direction										
	Commanded Clock Steering Wheel		anded	Yaw Rates			YRR at 1.0 sec after		YRR at 1.75 sec after	
			(c	(degrees/sec)						
Maneuver	Time	Ang	gle¹		_		cos		COS	
#							[<	35%]	[< 20%]	
	(1.5 – 5.0 min max between runs)	Scalar (* δ _{0.3 g})	Angle (degrees)	$\dot{\psi}_{\it Peak}$	$\dot{\psi}_{1.0 m sec}$	$\dot{\psi}_{1.75 m sec}$	%	Pass/Fail	%	Pass/Fail
33	11:26	1.5	63	-12.29	0.25	0.13	-2.02	PASS	-1.02	<u>PASS</u>
34	11:30	2.0	83	-16.24	0.24	0.19	-1.45	<u>PASS</u>	-1.17	<u>PASS</u>
35	11:33	2.5	104	-19.82	0.15	0.28	-0.76	<u>PASS</u>	-1.41	<u>PASS</u>
36	11:36	3.0	125	-23.09	0.41	0.27	-1.76	<u>PASS</u>	-1.18	<u>PASS</u>
37	11:39	3.5	146	-24.19	0.41	0.31	-1.71	<u>PASS</u>	-1.29	<u>PASS</u>
38	11:42	4.0	167	-25.26	0.41	0.23	-1.63	<u>PASS</u>	-0.89	<u>PASS</u>
39	11:45	4.5	188	-25.81	0.20	0.15	-0.79	<u>PASS</u>	-0.59	<u>PASS</u>
40	11:48	5.0	208	-27.76	0.34	0.23	-1.22	<u>PASS</u>	-0.82	<u>PASS</u>
41	11:50	5.5	229	-27.44	0.37	0.18	-1.34	<u>PASS</u>	-0.64	<u>PASS</u>
42	11:53	6.0	250	-28.74	0.07	-0.14	-0.24	<u>PASS</u>	0.48	<u>PASS</u>
43	11:56	6.5	271	-28.80	0.05	-0.05	-0.17	<u>PASS</u>	0.18	PASS

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5*\delta_0.3 g, overall or 270 degrees is utilized, whichever is greater provided the calculated 6.5*\delta_0.3 g, overall is less than or equal to 300 degrees. If 6.5*\delta_0.3 g, overall is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5*\delta_0.3 g, overall without exceeding the 270 degree steering wheel angle.

During execution of the Sine with Dwell maneuvers	wer	e any	of th	ne
following events observed?				
Rim-to-pavement contact		Yes	X	No
Tire debeading		Yes	X	No
Loss of pavement contact of vehicle tires		Yes	X	No
Did the test driver experience any vehicle loss of control or spinout?		Yes	X	No
If "Yes" explain the event and consult with th	e CO	OTR.		

Data Sheet 8 (6 of 6) **VEHICLE LATERAL STABILITY AND RESPONSIVENESS (4WD)**

Responsiveness – Lateral Displacement

Maneuver	Initial Steer	Commanded S Ang	gle	Calculated Lateral Displacement ¹		
#	Direction	(5.0*δο.3 g, overa Scalar *δο.3 g	Angle (degrees)	Distance (m)	Pass/Fail	
29	Counter Clockwise	5.0	208	-2.42	PASS	
30	Counter Clockwise	5.5	229	-2.47	PASS	
31	Counter Clockwise	6.0	250	-2.43	<u>PASS</u>	
32	Counter Clockwise	6.5	271	-2.45	<u>PASS</u>	
40	Clockwise	5.0	208	2.42	<u>PASS</u>	
41	Clockwise	5.5	229	2.43	PASS	
42	Clockwise	6.0	250	2.46	<u>PASS</u>	
43	Clockwise	6.5	271	2.54	<u>PASS</u>	

(5 ft) for vehicles with GVWR	greater than 3,500 kg (7,7)	16 lb).	FAIL		
Remarks:					
RECORDED BY: APPROVED BY:	B Kebschull J Lenkeit	DATE RECORDED: DATE APPROVED:	<u>9/14/2011</u> 9/16/2011		

Data Sheet 9 (Page 1 of 2) MALFUNCTION WARNING TESTS

Vehicle: 2011 GMC Sierra 1500	0 4WD Crew Cab
NHTSA No. <u>CB0108</u>	Data Sheet Completion Date: 9/13/2011
	TEST 1
MALFUNCTION SIMULATION	ON: Describe method of malfunction simulation
Disconnected left front whe	eel speed sensor
MALFUNCTION TELLTALE	ILLUMINATION:
	illuminated after ignition locking system is rehicle is driven at least 2 minutes.
	Yes No
of 48 \pm 8 km/h (30 \pm 5 mph) is	
O Seconds (must be wit	hin 2 minutes) X Pass Fail
ESC SYSTEM RESTORATION	ON
Telltale extinguishes after ignition the vehicle is driven at least 2 r	on locking system is activated and if necessary ninutes.
	<u>X</u> Yes No
Time for telltale to extinguish at speed of 48 \pm 8 km/h (30 \pm 5 n	fter ignition system is activated and vehicle nph) is reached.
O Seconds (must be wit	hin 2 minutes) X Pass Fail
TEST 1 D	ATA INDICATES COMPLIANCE: PASS
disconnected. In addition, the a "Service Traction Control" appears part of the tachometer. The tele	nmediately upon ignition, after sensor was alternating messages "Service Stabilitrak" and eared in the common display area in the lower litale and messages extinguished immediately the sensor was reconnected. No driving was
RECORDED BY: B Kebschull	DATE RECORDED: <u>9/13/2011</u>
APPROVED BY: P Broen	DATE APPROVED 9/13/2011

Data Sheet 9 (Page 2 of 2) MALFUNCTION WARNING TESTS

Vehicle: 2011 GMC Sierra 1500 4	4WD Crew Cab					
NHTSA No. CB0108 Data Sheet Completion Date: 9/13/2011						
	TEST 2					
MALFUNCTION SIMULATION	ON: Describe method of malfunction simulation					
Removed ABS Controller fuse	<u>e.</u>					
MALFUNCTION TELLTALE	ILLUMINATION:					
	illuminated after ignition locking system is rehicle is driven at least 2 minutes.					
	Yes No					
Time for telltale to illuminate aft of 48 ± 8 km/h (30 ± 5 mph) is Seconds (must be with						
ESC SYSTEM RESTORATION	ON					
Telltale extinguishes after ignition the vehicle is driven at least 2 m	on locking system is activated and if necessary ninutes.					
	<u>X</u> Yes No					
Time for telltale to extinguish af speed of 48 \pm 8 km/h (30 \pm 5 m	ter ignition system is activated and vehicle nph) is reached.					
O Seconds (must be with	hin 2 minutes) X Pass Fail					
TEST 2 D	ATA INDICATES COMPLIANCE: PASS					
disconnected. In addition, the r	nmediately upon ignition, after sensor was red "BRAKE" and ABS telltales also illuminated. diately upon cycling the ignition, after the fuse s required.					
RECORDED BY: B Kebschull	DATE RECORDED: 9/13/2011					
APPROVED BY: P Broen	DATE APPROVED <u>9/13/2011</u>					

4.0 TEST EQUIPMENT LIST AND CALIBRATION INFORMATION (1 OF 2)

TABLE 1. TEST INSTRUMENTATION

Туре	Output	Range	Resolution	Accuracy	Specifics	Serial Number	Calibration
Tire Pressure Gauge	Vehicle Tire Pressure	0-100 psi 0-690 kPa	1 psi 6.89 kPa	0.5 psi 3.45 kPa	Ashcroft D1005PS	1039350	By: DRI Date:2/22/11 Due: 2/22/12
Platform Scales	Vehicle Total, Wheel, and Axle Load	8000 lb 35.6 kN	0.5 lb 2.2 N	±1.0% of applied load	Intercomp Model SWII	24032361	By: DRI Date: 2/23/11 Due: 2/23/12
Automated Steering Machine with Steering Angle Encoder	Handwheel Angle	±800 deg	0.25 deg	±0.25 deg	Heitz Automotive Testing Model: Sprint 3	60304	By: DRI Date: 3/30/11 Due: 3/30/12
Multi-Axis Inertial Sensing System	Longitudinal, Lateral, and Vertical Acceleration Roll, Yaw, and Pitch Rate	Accelerometer s: ±2 g Angular Rate Sensors: ±100 deg/s	Accelerometers: ≤10 ug Angular Rate Sensors: ≤0.004 deg/s	Acceleromete rs: ≤0.05% of full range Angular Rate Sensors: 0.05% of full range	BEI Technologies Model: MotionPAK MP-1	0767	By: Systron Donner Date: 3/8/11 Due: 3/8/12
Radar Speed Sensor and Dashboard Display	Vehicle Speed	0-125 mph 0-200 km/h	0.009 mph .014 km/h	±0.25% of full scale	A-DAT Corp. Radar Model: DRS-6 Display Model: RD-2	1400.604	By: DRI Date: 5/3/11 Due: 5/3/12
Ultrasonic Distance	Left and Right Side 5-24 inches Vehicle Height 127-610 mm	5-24 inches	0.01 inches	±0.25% of	Massa Products Corporation	DOT-NHTSA D2646	By: DRI Date: 2/22/11 Due: 2/21/12
Measuring System		.254 mm	distance	Model: M- 5000/220	DOT-NHTSA D3272	By: DRI Date: 2/22/11 Due: 2/22/12	

4.0 TEST EQUIPMENT LIST AND CALIBRATION INFORMATION (2 OF 2)

TABLE 1. TEST INSTRUMENTATION (CONTD)

Туре	Output	Range	Resolution	Accuracy	Specifics	Serial Number	Calibration
Data Acquisition System [Includes amplification, anti-	Record Time; Velocity; Distance; Lateral, Longitudinal, and Vertical Accelerations; Roll, Yaw, and Pitch Rates; Steering Wheel Angle.	Sufficient to meet or exceed individual sensors	200 Hz	Sufficient to meet or exceed individual sensors	SoMat eDaq ECPU processor	MSHLB.03- 2476	By: DRI Date: 3/29/11 Due: 3/29/12
aliasing, and analog to digital conversion.]					SoMat High level Board EHLS	MSHLS.03- 3182	By: DRI Date: 3/29/11 Due: 3/29/12
Load Cell	Vehicle Brake Pedal Force	0-300 lb 0-1.33 kN	1 lb 4.44 N	±0.05% of full scale	Lebow 3663-300	767	Operationally verified by DRI prior to test
Coordinate Measurement Machine	Inertial Sensing System Coordinates	0-8 ft 0-2.4 m	±.0020 in. ±.051 mm	±.0020 in. ±.051 mm (Single point articulation accuracy)	Faro Arm Fusion	UO8-05-08- 06636	By; DRI Date: 11/7/10 Due: 11/7/11
Outriggers	No output. Safety Item.	NA	NA	NA	DRI manufactured Aluminum meeting the weight and MOI specifications of Docket 2007- 27662-11	NA	NA

5.0 PHOTOGRAPHS (1 of 15)



Figure 5.1. Front View of Test Vehicle

5.0 PHOTOGRAPHS (2 of 15)



Figure 5.2. Rear View of Test Vehicle

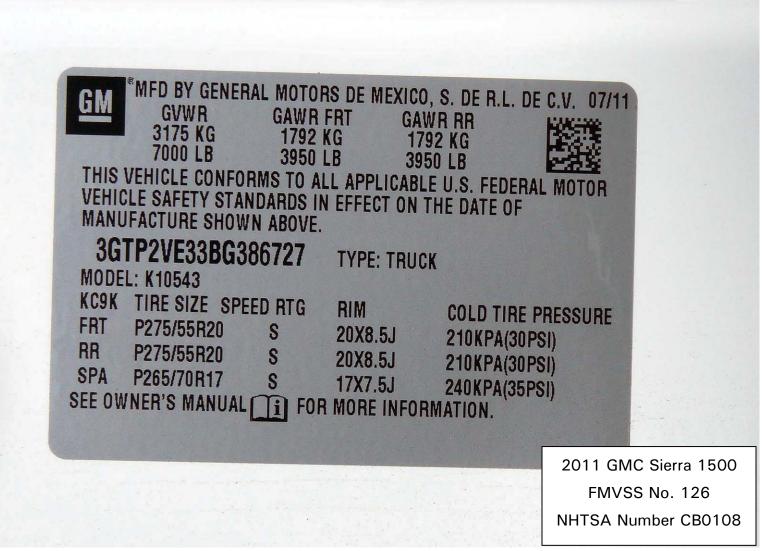


Figure 5.3. Vehicle Certification Label

5.0 PHOTOGRAPHS (4 of 15)

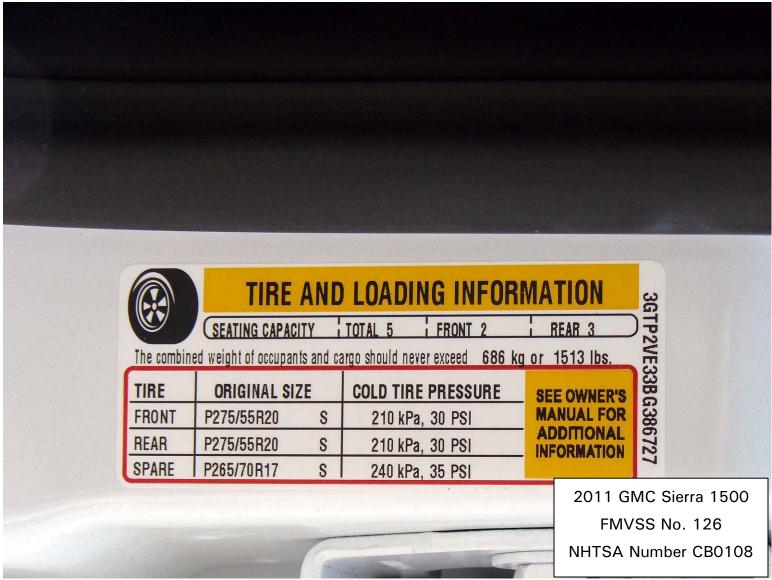


Figure 5.4. Vehicle Placard

5.0 PHOTOGRAPHS (5 of 15)

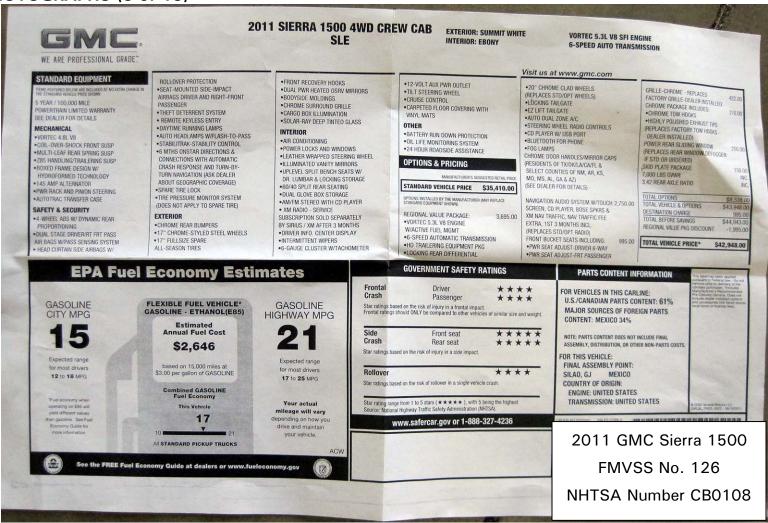


Figure 5.5. Window Sticker (Monroney Label)

5.0 PHOTOGRAPHS (6 of 15)



Figure 5.6. Front View of Vehicle as Tested

5.0 PHOTOGRAPHS (7 of 15)



Figure 5.7. Rear View of Vehicle as Tested

5.0 PHOTOGRAPHS (8 of 15)



Figure 5.8. Ultrasonic Height Sensor Mounted on Side of Vehicle for Determining Body Roll Angle

5.0 PHOTOGRAPHS (9 of 15)



Figure 5.9. Rear Mounted Speed Sensor

5.0 PHOTOGRAPHS (10 of 15) 2011 GMC Sierra 1500 FMVSS No. 126 NHTSA Number CB0108

Figure 5.10. Steering Controller and Data Acquisition Computer

5.0 PHOTOGRAPHS (11 of 15)



Figure 5.11. Inertial Measurement Unit Mounted in Vehicle

5.0 PHOTOGRAPHS (12 of 15)



Figure 5.12. Brake Pedal Load Cell

5.0 PHOTOGRAPHS (13 of 15)



Figure 5.13. Telltale and Messages for ESC Malfunction and ESC Off

5.0 PHOTOGRAPHS (14 of 15)



Figure 5.14. ESC Off Control Switch

5.0 PHOTOGRAPHS(15 of 15)

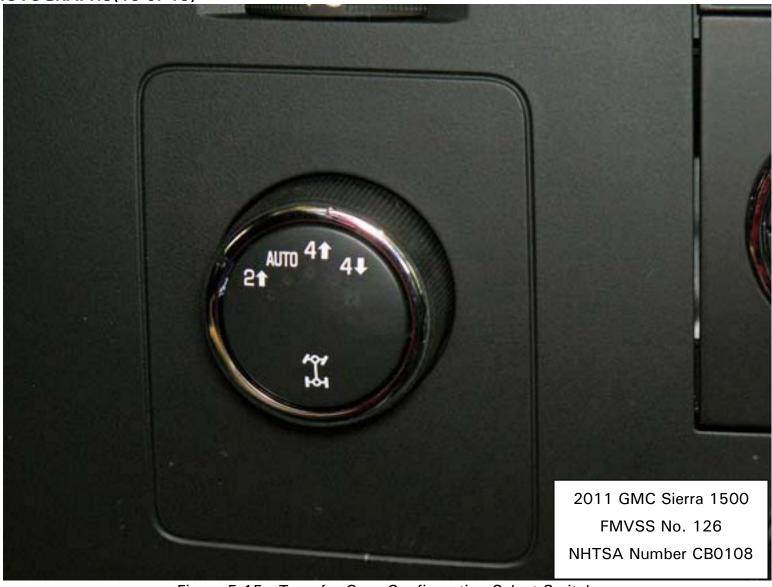


Figure 5.15. Transfer Case Configuration Select Switch

6.0 DATA PLOTS (1 of 8)

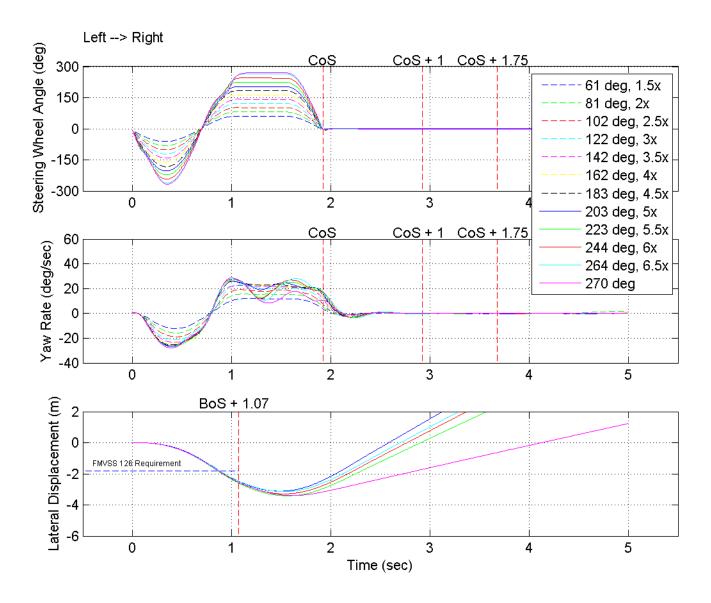


Figure 6.1. Steering Wheel Angle, Yaw Rate and Lateral Displacement for L-R Series (2WD Configuration)

6.0 DATA PLOTS (2 of 8)

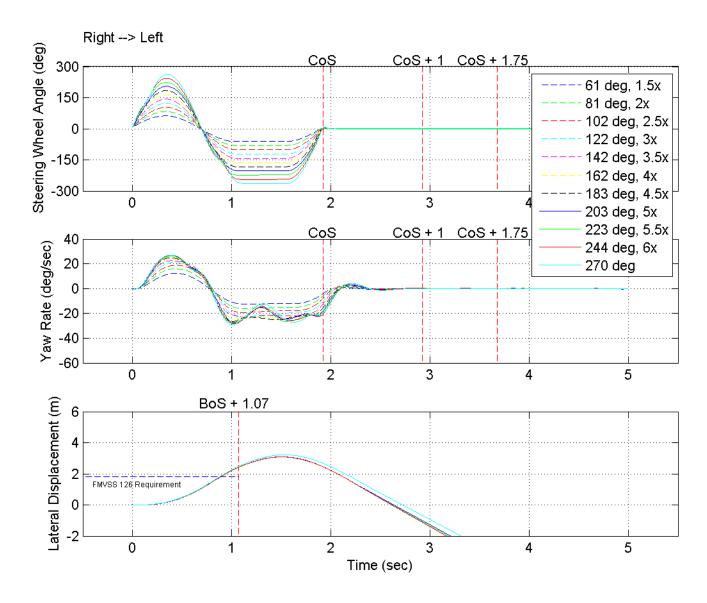


Figure 6.2. Steering Wheel Angle, Yaw Rate and Lateral Displacement for R-L Series (2WD Configuration)

6.0 DATA PLOTS (3 of 8)

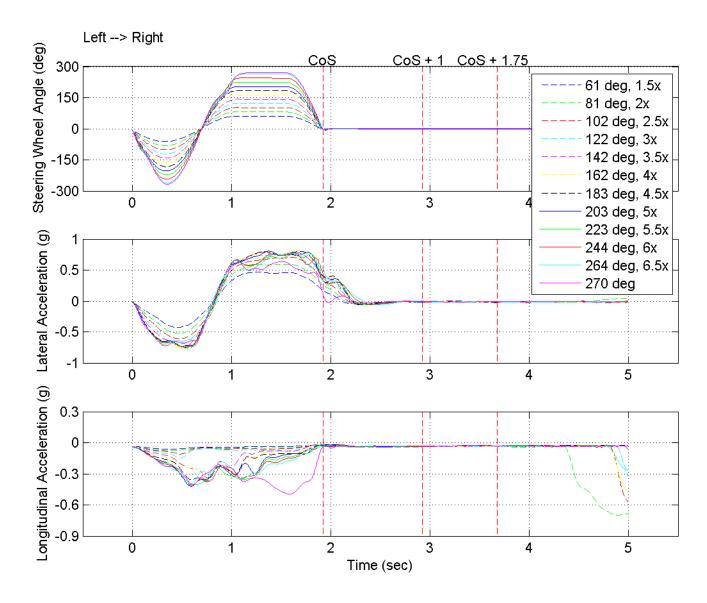


Figure 6.3. Steering Wheel Angle, Lateral Acceleration and Longitudinal Acceleration for L-R Series (2WD Configuration)

6.0 DATA PLOTS (4 of 8)

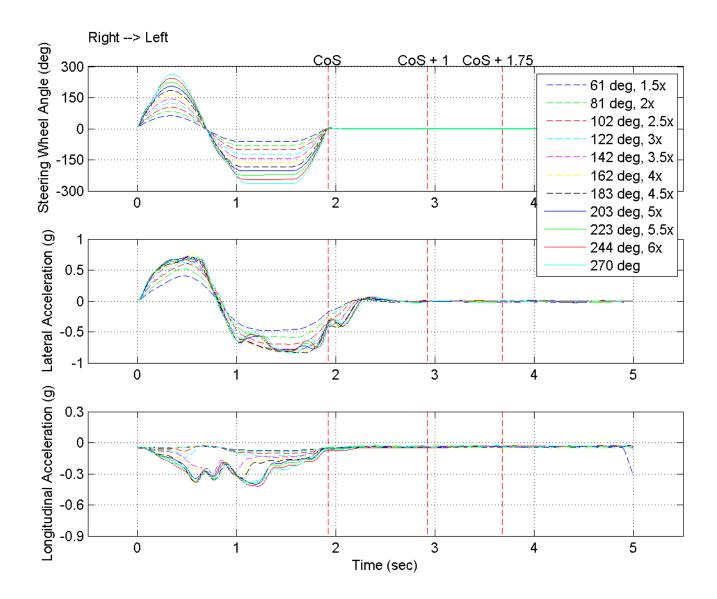


Figure 6.4. Steering Wheel Angle, Lateral Acceleration and Longitudinal Acceleration for R-L Series (2WD Configuration)

6.0 DATA PLOTS (5 of 8)

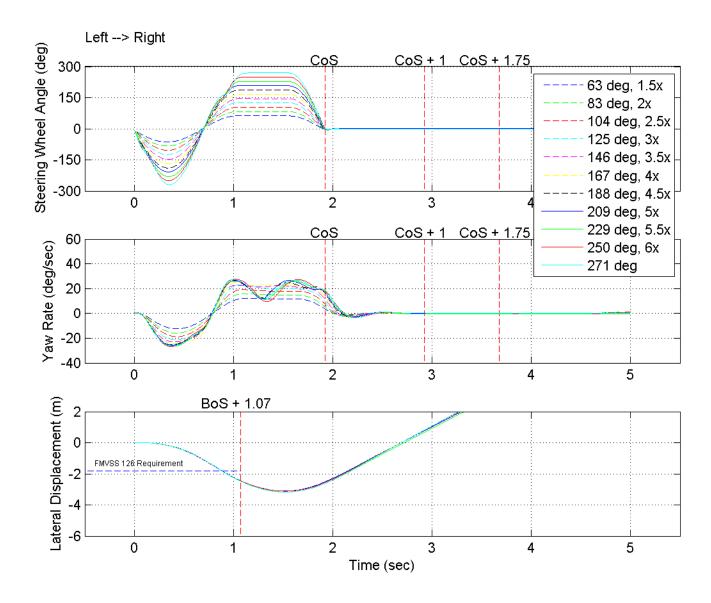


Figure 6.5. Steering Wheel Angle, Yaw Rate and Lateral Displacement for L-R Series (4WD Configuration)

6.0 DATA PLOTS (6 of 8)

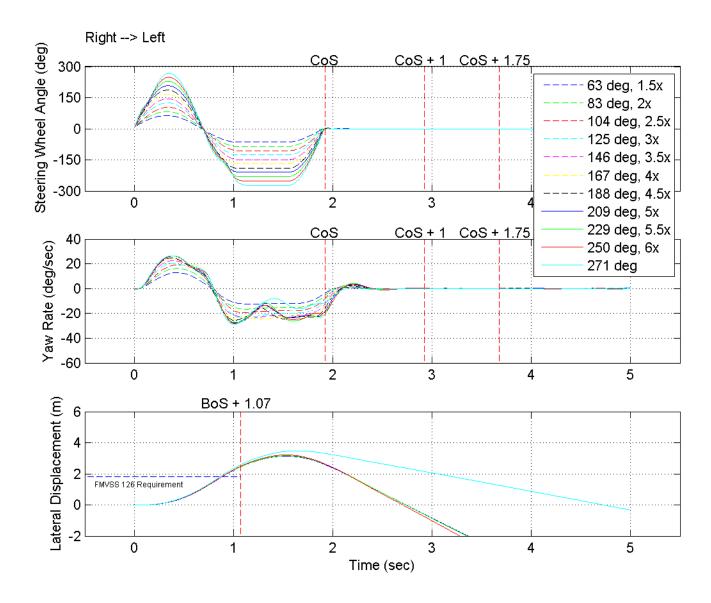


Figure 6.6. Steering Wheel Angle, Yaw Rate and Lateral Displacement for R-L Series (4WD Configuration)

6.0 DATA PLOTS (7 of 8)

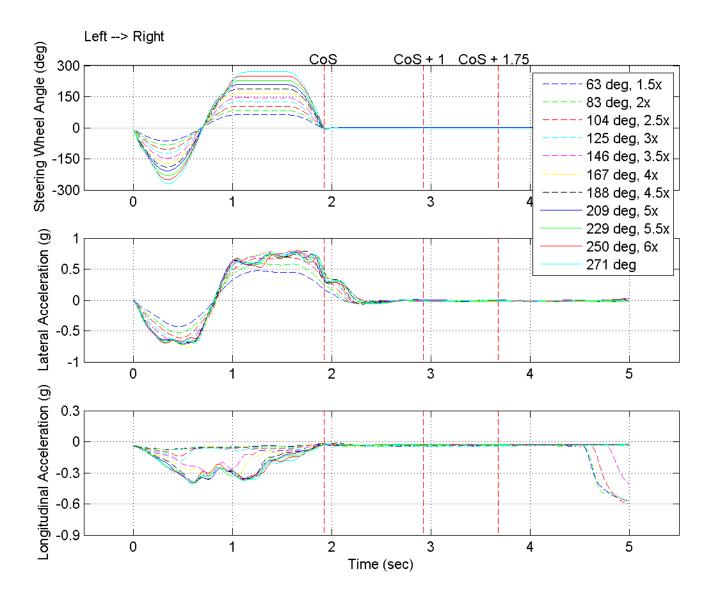


Figure 6.7. Steering Wheel Angle, Lateral Acceleration and Longitudinal Acceleration for L-R Series (4WD Configuration)

6.0 DATA PLOTS (8 of 8)

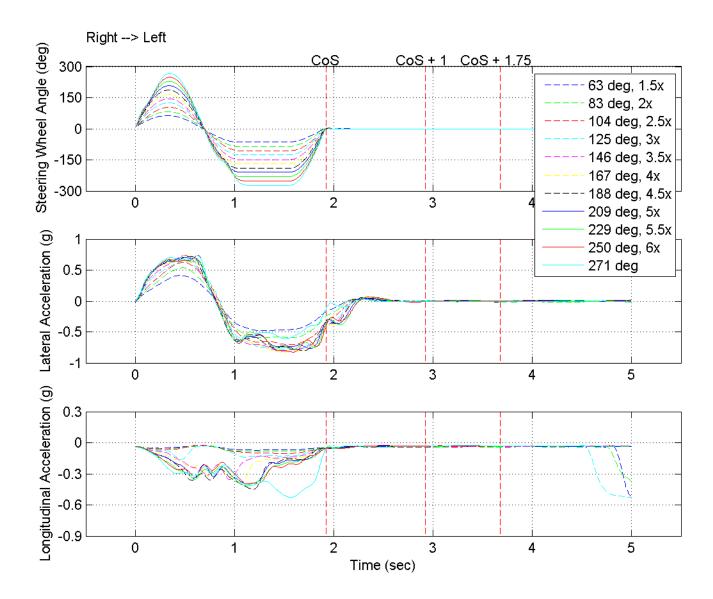


Figure 6.8. Steering Wheel Angle, Lateral Acceleration and Longitudinal Acceleration for R-L Series (4WD Configuration)

7.0 OTHER DOCUMENTATION

- 7.1 OWNER'S MANUAL PAGES
- 7.2 VEHICLE ARRIVAL CONDITION REPORT
- 7.3 VEHICLE COMPLETION CONDITION REPORT
- 7.4 SINE WITH DWELL TEST RESULTS
- 7.5 SLOWLY INCREASING STEER TEST RESULTS
- 7.6 INERTIAL SENSING SYSTEM LOCATION COORDINATES

7.1 OWNER'S MANUAL PAGES

Introduction v

Vehicle Symbol Chart

Here are some additional symbols that may be found on the vehicle and what they mean. For more information on the symbol, refer to the Index.

: Adjustable Pedals

☆: Airbag Readiness Light

☆: Air Conditioning

(ABS): Antilock Brake System (ABS)

િર્દ : Audio Steering Wheel Controls or OnStar®

①: Brake System Warning Light

: Charging System

: Cruise Control

♣: Engine Coolant Temperature

- Exterior Lamps

₽: Fog Lamps

: Fuel Gauge

#: Fuses

ED: Headlamp High/Low-Beam Changer

②: LATCH System Child Restraints

: Malfunction Indicator Lamp

: Outside Power Foldaway Mirrors

①: Power

\Omega: Remote Vehicle Start

#: Safety Belt Reminders

①: Tire Pressure Monitor

: Tow/Haul Mode

★: Traction Control

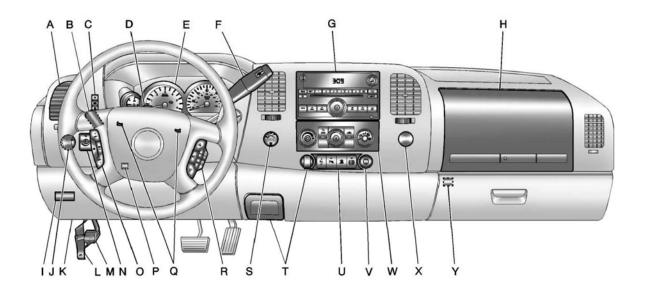
: Windshield Washer Fluid

7.1 OWNER'S MANUAL PAGES

1-2 In Brief

Instrument Panel

Instrument Panel (Base/Uplevel Version)



- A. Air Vents on page 8-11.
- B. Turn and Lane-Change Signals on page 6-6.
 Windshield Wiper/Washer on page 5-5.
- C. Driver Information Center (DIC) Buttons. See *Driver Information* Center (DIC) on page 5-33.
- D. Hazard Warning Flashers on page 6-5.
- E. Instrument Cluster on page 5-13.
- F. Shift Lever. See Automatic Transmission on page 9-46.

Tow/Haul Selector Button (If Equipped). See *Tow/Haul Mode on page 9-51*.

Range Selection Mode (Allison Transmission and Hydra-Matic[®] 6-Speed Button (If Equipped). See *Manual Mode on page 9-50*.

- G. Infotainment on page 7-1.
- H. Instrument Panel Storage on page 4-1.
- Integrated Trailer Brake Controller (If Equipped). See Trailer Towing on page 9-95.
- J. Exterior Lamp Controls on page 6-1.
- K. Data Link Connector (DLC) (Out of View). See Malfunction Indicator Lamp on page 5-25.
- L. Hood on page 10-5.
- M. Parking Brake on page 9-69.
- N. Dome Lamps on page 6-8.

 Fog Lamps on page 6-6
 (If Equipped).
- O. Cruise Control on page 9-73.
- P. Steering Wheel Adjustment on page 5-2.

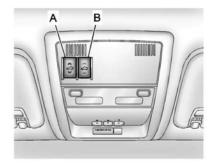
- Q. Horn on page 5-5.
- R. Steering Wheel Controls on page 5-3 (If Equipped).
- S. Automatic Transfer Case Control (If Equipped). See Four-Wheel Drive on page 10-34.
- T. Ashtray (If Equipped). See Ashtrays on page 5-12 and Cigarette Lighter on page 5-11.
- U. StabiliTrak® System on page 9-70 (If Equipped).

Ultrasonic Parking Assist on page 9-76 (If Equipped).

Pedal Adjust Button (If Equipped). See Adjustable Throttle and Brake Pedal on page 9-35.

Exhaust Brake (If Equipped). See "Brakes" in the Duramax Diesel Supplement. The sunroof also has a roller sunshade that can be used to block the rays of the sun. To open the sunshade, press and unlatch it, and roll it back. To close, pull it forward and latch it into the closed position.

Crew Cab



A. Open or Close

B. Vent

There are two sunroof switches located in the overhead console above the rearview mirror.

Vent: From the closed position, press the rear of the passenger side switch (B) to vent the sunroof.

Manual-Open/Manual-Close:

To open the sunroof, press and hold the rear of the driver side switch (A) until the sunroof reaches the desired position. Press and hold the front of the driver side switch to close it.

Express-Open/Express-Close:

To express-open the sunroof, fully press and release the rear of the driver side switch (B) until the sunroof reaches the desired position. To express-close the sunroof, fully press and release the front of the driver side switch. Press the switch again to stop it.

The sunroof also has a sunshade that you can pull forward to block the rays of the sun. The sunshade must be opened and closed manually.

See Sunroof (Extended Cab) on page 2-21 or Sunroof (Crew Cab) on page 2-22.

Performance and Maintenance

StabiliTrak® System

If equipped, the vehicle has a traction control system that limits wheel spin and the StabiliTrak system that assists with directional control of the vehicle in difficult driving conditions. Both systems turn on automatically every time the vehicle is started.

7.1 OWNER'S MANUAL PAGES

1-34 In Brief

- Press and release again to turn on both systems.

For more information, see StabiliTrak® System on page 9-70.

Tire Pressure Monitor

This vehicle may have a Tire Pressure Monitor System (TPMS).



The TPMS warning light alerts you to a significant loss in pressure of one of the vehicle's tires.

If the warning light comes on, stop as soon as possible and inflate the tires to the recommended pressure shown on the Tire and Loading Information label. See *Vehicle Load Limits on page 9-25*. The warning light will remain on until the tire pressure is corrected.

During cooler conditions, the low tire pressure warning light may appear when the vehicle is first started and then turn off. This may be an early indicator that the tire pressures are getting low and the tires need to be inflated to the proper pressure.

The TPMS does not replace normal monthly tire maintenance. It is the driver's responsibility to maintain correct tire pressures.

See Tire Pressure Monitor System on page 10-68.

Engine Oil Life System

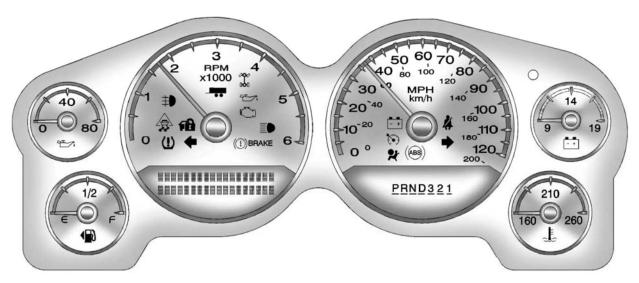
The engine oil life system calculates engine oil life based on vehicle use and, on most vehicles, displays a DIC message when it is necessary to change the engine oil and filter. The oil life system should be reset to 100% only following an oil change.

Resetting the Oil Life System

To reset the Engine Oil Life System on most vehicles:

- Display OIL LIFE REMAINING on the DIC. If the vehicle does not have DIC buttons, the vehicle must be in P (Park) to access this display.
- Press and hold the SET/RESET button on the DIC, or the trip odometer reset stem if the vehicle does not have DIC buttons, for more than five seconds. The oil life will change to 100%.

Instrument Cluster



English Light Duty Premium Shown. Metric, Uplevel, Base, Heavy Duty Similar.

5-30 Instruments and Controls

StabiliTrak[®] Indicator Light



For vehicles with the StabiliTrak system, this light comes on briefly while starting the engine.

If it does not, have the vehicle serviced by your dealer. If the system is working normally the indicator light then goes off.

If the light comes on and stays on while driving, there could be a problem with the StabiliTrak system and the vehicle might need service. When this warning light is on, the StabiliTrak system is off and does not limit wheel spin.

The light flashes if the system is active and is working to assist the driver with directional control of the vehicle in difficult driving conditions.

See StabiliTrak® System on page 9-70 for more information.

If the vehicle is a hybrid, see the hybrid supplement for more information.

Tire Pressure Light



For vehicles with the Tire Pressure Monitor System (TPMS), this light comes on briefly when the engine is started. It provides information about tire pressures and the TPMS.

When the Light is On Steady

This indicates that one or more of the tires are significantly underinflated.

A tire pressure message can accompany the light. See *Tire Messages on page 5-49* for more information. Stop as soon as possible, and inflate the tires to the pressure value shown on the Tire and Loading Information label. See *Tire Pressure on page 10-66* for more information.

When the Light Flashes First and Then is On Steady

This indicates that there may be a problem with the Tire Pressure Monitor System. The light flashes for about a minute and stays on steady for the remainder of the ignition cycle. This sequence repeats with every ignition cycle. See *Tire Pressure Monitor Operation on page 10-69* for more information.

SERVICE PARK ASSIST

If the vehicle has the Ultrasonic Rear Parking Assist (URPA) system, this message displays if there is a problem with the URPA system. Do not use this system to help you park. See *Ultrasonic Parking Assist on page 9-76* for more information. See your dealer for service.

Ride Control System Messages

SERVICE STABILITRAK

If the vehicle has StabiliTrak and this message displays, it means there may be a problem with the StabiliTrak system. If you see this message, try to reset the system.

Stop; turn off the engine for at least 15 seconds; then start the engine again. If this message still comes on, it means there is a problem. You should see your dealer for service. The vehicle is safe to drive; however, you do not have the benefit of StabiliTrak, so reduce your speed and drive accordingly.

SERVICE TRACTION CONTROL

If the vehicle has StabiliTrak, this message displays when there is a problem with the Traction Control System (TCS). When this message displays, the system will not limit wheel spin. Adjust your driving accordingly. See your dealer for service. See StabiliTrak® System on page 9-70 for more information.

STABILITRAK OFF

If the vehicle has StabiliTrak, this message displays when you turn off StabiliTrak, or when the stability control has been automatically disabled. To limit wheel spin and realize the full benefits of the stability enhancement system, you should normally leave StabiliTrak on. However, you should turn StabiliTrak off if your vehicle gets stuck in sand, mud, ice, or snow and you want to rock your vehicle to attempt to free it, or if you are driving in extreme off-road conditions and require more wheel spin. See If the Vehicle is Stuck on page 9-23. To turn the StabiliTrak system on or off, see StabiliTrak® System on page 9-70.

5-48 Instruments and Controls

There are several conditions that can cause this message to appear.

- If the vehicle is overheating, which could occur if StabiliTrak activates continuously for an extended period of time.
- If the brake system warning light is on. See Brake System Warning Light on page 5-27.
- If the stability system takes longer than usual to complete its diagnostic checks due to driving conditions.
- If an engine or vehicle related problem has been detected and the vehicle needs service.
 See your dealer.
- If the vehicle is shifted into 4LO.

The message turns off as soon as the conditions that caused the message to be displayed are no longer present.

TRACTION CONTROL OFF

If the vehicle has StabiliTrak, this message displays when the Traction Control System (TCS) is turned off. Adjust your driving accordingly. See StabiliTrak® System on page 9-70 for more information.

Airbag System Messages SERVICE AIR BAG

This message displays if there is a problem with the airbag system. Have your dealer inspect the system for problems. See *Airbag Readiness Light on page 5-20* and *Airbag System on page 3-29* for more information.

Anti-Theft Alarm System Messages

SERVICE THEFT DETERRENT SYSTEM

This message displays when there is a problem with the theft-deterrent system. The vehicle may or may not restart so you may want to take the vehicle to your dealer before turning off the engine. See *Immobilizer Operation on page 2-13* for more information.

Starting the Vehicle Messages

FAST IDLE ON

If your vehicle has this feature, this message displays when the fast idle feature is on. See Fast Idle System on page 9-39 for more information.

9-54 Driving and Operating

Drive Systems

Four-Wheel Drive

If the vehicle has Four-Wheel Drive, you can send the engine's driving power to all four wheels for extra traction. To get the most satisfaction out of Four-Wheel Drive, you must be familiar with its operation. Read the following before using Four-Wheel Drive. See the appropriate text for the transfer case in the vehicle.

Notice: Driving on clean, dry pavement in Four-Wheel Drive High or Four-Wheel Drive Low for an extended period of time may cause premature wear on the vehicle's powertrain. Do not drive on clean, dry pavement in Four-Wheel Drive High or Four-Wheel Drive Low for extended periods of time.

While driving on clean dry pavement and during tight turns, you may experience vibration in the steering system.

If the vehicle has StabiliTrak[®], shifting into Four-Wheel Drive Low will turn Traction Control and StabiliTrak off. See *StabiliTrak*[®] *System on page 9-70*.

Front Axle

The front axle engages and disengages automatically when you shift the transfer case. Some delay for the axle to engage or disengage is normal.

Manual Transfer Case

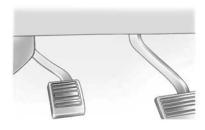


The transfer case shift lever is on the floor to the right of the driver. Use this lever to shift into and out of Four-Wheel Drive.

Braking in Emergencies

ABS allows the driver to steer and brake at the same time. In many emergencies, steering can help more than even the very best braking.

Parking Brake



Set the parking brake by holding the regular brake pedal down, then pushing down the parking brake pedal. If the ignition is on, the brake system warning light will come on. See *Brake System Warning Light on page 5-27*.

Notice: Driving with the parking brake on can overheat the brake system and cause premature wear or damage to brake system parts. Make sure that the parking brake is fully released and the brake warning light is off before driving.

To release the parking brake, hold the regular brake pedal down, then push down momentarily on the parking brake pedal until you feel the pedal release. Slowly pull your foot up off the parking brake pedal. If the parking brake is not released when you begin to drive, the brake system warning light will flash and a chime will sound warning you that the parking brake is still on.

If you are towing a trailer and are parking on a hill, see *Driving Characteristics and Towing Tips on page 9-91*.

Brake Assist (Except With 4.3L V6 Engine)

If this vehicle has StabiliTrak®, it also has a Brake Assist feature designed to assist the driver in stopping or decreasing vehicle speed in emergency driving conditions. This feature uses the stability system hydraulic brake control module to supplement the power brake system under conditions where the driver has quickly and forcefully applied the brake pedal in an attempt to guickly stop or slow down the vehicle. The stability system hydraulic brake control module increases brake pressure at each corner of the vehicle until the ABS activates.

9-70 Driving and Operating

Minor brake pedal pulsation or pedal movement during this time is normal and the driver should continue to apply the brake pedal as the driving situation dictates. The Brake Assist feature will automatically disengage when the brake pedal is released or brake pedal pressure is quickly decreased.

Hill Start Assist (HSA)

2500 and 3500 series vehicles with StabiliTrak have a Hill Start Assist (HSA) feature, which may be useful when the vehicle is stopped on a grade. This feature is designed to prevent the vehicle from rolling, either forward or rearward, during vehicle drive off. After the driver completely stops and holds the vehicle in a complete standstill on a grade, HSA will be automatically

activated. During the transition period between when the driver releases the brake pedal and starts to accelerate to drive off on a grade, HSA holds the braking pressure for a maximum of two seconds to ensure that there is no rolling. The brakes will automatically release when the accelerator pedal is applied within the two-second window. If the vehicle is equipped with the Integrated Trailer Brake Control (ITBC) system, HSA may also apply the trailer brakes. It will not activate if the vehicle is in a drive gear and facing downhill or if the vehicle is facing uphill and in R (Reverse). There may be situations on minor hills (less than 5% grade) with a loaded vehicle or while pulling a trailer where HSA will not activate.

Ride Control Systems

StabiliTrak® System

The vehicle may have a vehicle stability enhancement system called StabiliTrak[®]. It is an advanced computer-controlled system that assists the driver with directional control of the vehicle in difficult driving conditions.

StabiliTrak activates when the computer senses a discrepancy between the intended path and the direction the vehicle is actually traveling. StabiliTrak selectively applies braking pressure at any one of the vehicle's brakes to assist the driver with keeping the vehicle on the intended path.

When the vehicle is started and begins to move, the system performs several diagnostic checks to insure there are no problems. The system may be heard or felt while it is working. This is normal and does not mean there is a problem with the vehicle. The system should initialize before the vehicle reaches 32 km/h (20 mph). In some cases, it may take approximately 3.2 km (2 mi) of driving before the system initializes.

If cruise control is being used when StabiliTrak activates, the cruise control automatically disengages. The cruise control can be re-engaged when road conditions allow. See *Cruise Control on page 9-73* for more information.

If the system fails to turn on or activate, the StabiliTrak light along with one of the following messages will be displayed on the Driver Information Center (DIC): TRACTION

CONTROL OFF, SERVICE TRACTION CONTROL, STABILITRAK OFF, SERVICE STABILITRAK. If these DIC messages appear, make sure the StabiliTrak system has not been turned off using the StabiliTrak on/off button. Then turn the vehicle off, wait 15 seconds, and turn it back on again to reset the system. If any of these messages still appear on the DIC, the vehicle should be taken in for service. For more information on the DIC messages, see Ride Control System Messages on page 5-47.



The StabiliTrak light will flash on the instrument panel cluster when the system is both on and activated.

The system may be heard or felt while it is working; this is normal.



The traction control disable button is located on the instrument panel below the climate controls.

The Traction Control System (TCS) part of StabiliTrak can be turned off by pressing and releasing the StabiliTrak button. To disable both TCS and StabiliTrak, press and hold a until illuminates and the appropriate DIC message displays.

TCS and StabiliTrak can be turned on by pressing and releasing the StabiliTrak button if they are not automatically shut off for any other reason.

9-72 Driving and Operating

When TCS or StabiliTrak is turned off, the StabiliTrak light and the appropriate message will be displayed on the DIC to warn the driver. The vehicle will still have brake-traction control when traction control is off, but will not be able to use the engine speed management system. See "Traction Control Operation" next for more information.

When the traction control system has been turned off, system noises may still be heard as a result of the brake-traction control coming on.

It is recommended to leave the system on for normal driving conditions, but it may be necessary to turn the system off if the vehicle is stuck in sand, mud, ice or snow, and you want to "rock" the vehicle to attempt to free it. It may also be necessary to turn off the system when driving in extreme off-road conditions where high wheel spin is required. See *If the Vehicle is Stuck on page 9-23*.

When the transfer case is in 4LO, the stability system is automatically disabled, the StabiliTrak light comes on, and the STABILITRAK OFF message will appear on the DIC. Both traction control and StabiliTrak are automatically disabled in this condition.

Traction Control Operation

The traction control system is part of the StabiliTrak system. Traction control limits wheel spin by reducing engine power to the wheels (engine speed management) and by applying brakes to each individual wheel (brake-traction control) as necessary.

The traction control system is enabled automatically when the vehicle is started. It will activate and the StabiliTrak light will flash if it senses that any of the wheels are spinning or beginning to lose traction while driving. If traction control is turned off, only the brake-traction control portion of traction control will work. The engine speed management will be disabled. In this mode, engine power is not reduced automatically and the driven wheels can spin more freely. This can cause the brake-traction control to activate constantly.

Notice: If the wheel(s) of one axle is allowed to spin excessively while the StabiliTrak®, ABS, brake warning lights, and any relevant DIC messages are displayed, the transfer case could be damaged. The repairs would not be covered by the vehicle warranty. Reduce engine power and do not spin the wheel(s) excessively while these lights and messages are displayed.

The traction control system may activate on dry or rough roads or under conditions such as heavy acceleration while turning or abrupt upshifts/downshifts of the transmission. When this happens, a reduction in acceleration may be noticed, or a noise or vibration may be heard. This is normal.

If cruise control is being used when the system activates, the StabiliTrak light will flash and cruise control will automatically disengage. Cruise control may be reengaged when road conditions allow. See *Cruise Control on page 9-73*.

StabiliTrak may also turn off automatically if it determines that a problem exists with the system. If the problem does not clear itself after restarting the vehicle, see your dealer for service.

2500 and 3500 series vehicles with StabiliTrak have a Trailer Sway Control (TSC) feature. See *Trailer Sway Control (TSC) on page 9-124*.

2500 and 3500 series vehicles with StabiliTrak have a Hill Start Assist (HSA) feature. See *Hill Start Assist (HSA) on page 9-70*.

Adding non-dealer accessories can affect the vehicle's performance. See Accessories and Modifications on page 10-3.

Locking Rear Axle

Vehicles with a locking rear axle can give more traction on snow, mud, ice, sand, or gravel. It works like a standard axle most of the time, but when traction is low, this feature will allow the rear wheel with the most traction to move the vehicle.

Cruise Control

⚠ WARNING

Cruise control can be dangerous where you cannot drive safely at a steady speed. So, do not use the cruise control on winding roads or in heavy traffic.

Cruise control can be dangerous on slippery roads. On such roads, fast changes in tire traction can cause excessive wheel slip, and you could lose control. Do not use cruise control on slippery roads.

For vehicles with cruise control, a speed of about 40 km/h (25 mph) or more can be maintained without keeping your foot on the accelerator. Cruise control does not work at speeds below about 40 km/h (25 mph).

9-118 Driving and Operating

Integrated Trailer Brake Control System



The vehicle may have an Integrated Trailer Brake Control (ITBC) system for electric trailer brakes.

This symbol is located on the Trailer Brake Control Panel on vehicles with an Integrated Trailer Brake Control system. The power output to the trailer brakes is based on the amount of brake pressure being applied by the vehicle's brake system. This available power output to the trailer brakes can be adjusted to a wide range of trailering situations.

The ITBC system is integrated with the vehicle's brake, antilock brake, and StabiliTrak (if equipped) systems. In trailering conditions that

cause the vehicle's antilock brake or StabiliTrak systems to activate, power sent to the trailer's brakes will be automatically adjusted to minimize trailer wheel lock-up. This does not imply that the trailer has StabiliTrak.

2500 and 3500 series vehicles with StabiliTrak have a Trailer Sway Control (TSC) feature. See *Trailer Sway Control (TSC) on page 9-124*.

2500 and 3500 series vehicles with StabiliTrak have a Hill Start Assist (HSA) feature. See *Hill Start Assist (HSA) on page 9-70*.

If the vehicle's brake, antilock brake, or StabiliTrak systems are not functioning properly, the ITBC system may not be fully functional or may not function at all. Make sure all of these systems are fully operational to ensure full functionality of the ITBC system.

The ITBC system is powered through the vehicle's electrical system. Turning the ignition off will also turn off the ITBC system.

The ITBC system is fully functional only when the ignition is in ON or in RUN.

The ITBC system can only be used with trailers with electric brakes.

↑ WARNING

Connecting a trailer that is not compatible with the ITBC system may result in reduced or complete loss of trailer braking. There may be an increase in stopping distance or trailer instability which could result in personal injury or damage to the vehicle, trailer, or other property. An aftermarket controller may be available for use with trailers with surge, air. or electric-over-hydraulic trailer brake systems. To determine the type of brakes on the trailer and the availability of controllers, check with your trailer manufacturer or dealer.

9-124 Driving and Operating

SERVICE TRAILER BRAKE SYSTEM: This message will be displayed when there is a problem with the ITBC system. If this message persists over multiple ignition cycles, there is a problem with the ITBC system. Take the vehicle to an authorized GM dealer to have the ITBC system diagnosed and repaired.

If either the CHECK TRAILER WIRING or SERVICE TRAILER BRAKE SYSTEM message is displayed while driving the vehicle, power is no longer available to the trailer brakes. When traffic conditions allow, carefully pull the vehicle over to the side of the road and turn the ignition off. Check the wiring connection to the trailer and turn the ignition back on. If either of these messages continues, either the vehicle or trailer needs service.

An authorized GM dealer may be able to diagnose and repair problems with the trailer. However, any diagnosis and repair of the trailer is not covered under the vehicle warranty. Please contact your trailer dealer for assistance with trailer repairs and trailer warranty information.

Trailer Sway Control (TSC)

Trailer Sway Control (TSC)

2500 and 3500 series vehicles with StabiliTrak have a Trailer Sway Control (TSC) feature. If the vehicle is towing a trailer and the system detects that the trailer is swaying, the vehicle's brakes are applied

without the driver pressing the brake pedal. If the vehicle is equipped with the Integrated Trailer Brake Control (ITBC) system, StabiliTrak may also apply the trailer brakes. The TCS/ StabiliTrak warning light will flash on the instrument panel cluster to notify the driver to reduce speed. If the trailer continues to sway, StabiliTrak will reduce engine torque to help slow the vehicle.

Adding non-dealer accessories can affect the vehicle's performance. See *Accessories and Modifications* on page 10-3 for more information.

7.2 VEHICLE ARRIVAL CONDITION REPORT

CONTRACT NO.: DTNH22-08-D-00098 DATE: 8/26/2011 Purpose Initial Receipt From: Automotive Allies Received via Transfer Present Vehicle Condition To: Dynamic Research, Inc. Vehicle VIN: *3GTP2VE33BG386727* NHTSA NO.: CB0108 Model Year: 2011 Odometer Reading: 5 Miles Make **GMC** Body Style: Truck Model: Sierra 1500 Body Color: White Manufacture Date: Dealer: Automotive Allies 7/11 3175/7000 GVWR (kg/lb) Price: Leased X All options listed on the "Window Sticker" are present on the test vehicle Tires and wheel rims are new and the same as listed There are no dents or other interior or exterior flaws The vehicle has been properly prepared and is in running condition The glove box contains an owner's manual, warranty document, consumer information, and extra set of keys Representation Proper fuel filler cap is supplied on the test vehicle ▼ Place vehicle in storage area Inspect the vehicle's interior and exterior, including all windows, seats, doors, etc., to confirm that each system is complete and functional per the manufacturer's specifications. Any damage, misadjustment, or other unusual condition that could influence the test program or test results shall be recorded. Report any abnormal condition to the NHTSA COTR before beginning any test. NOTES: RECORDED BY: J Lenkeit DATE RECORDED: 8/26/2011

DATE APPROVED: 8/26/2011

APPROVED BY: P Broen

7.3 VEHICLE COMPLETION CONDITION REPORT

CONTRACT NO.: <u>DTNH22-08-D-00098</u>

DATE: <u>9/27/2011</u>	
Vehicle VIN: <u>3GTP2VE33BG386727</u>	NHTSA NO.: <u>CB0108</u>
Model Year: 2011	Odometer Reading: 79 Miles
Make: <u>GMC</u>	Body Style: Truck
Model: Sierra 1500	Body Color: White
Manufacture Date: 7/11	Dealer: <u>Automotive Allies</u>
GVWR (kg/lb) <u>3175 (7000)</u>	Price: <u>Leased</u>
LIST OF FMVSS TESTS PERFORMED BY	THIS LAB: <u>126</u>
☑ THERE ARE NO DENTS OR OTHER	R INTERIOR OR EXTERIOR FLAWS
	LY MAINTAINED AND IS IN RUNNING
☑ THE GLOVE BOX CONTAINS AN DOCUMENT, CONSUMER INFORM	OWNER'S MANUAL, WARRANTY MATION, AND EXTRA SET OF KEYS
☑ PROPER FUEL FILLER CAP IS SUF REMARKS:	PPLIED ON THE TEST VEHICLE
Equipment that is no longer on the test ve Condition Report:	chicle as noted on Vehicle Arrival
<u>None</u>	
Explanation for equipment removal:	
Explanation for equipment formevall	
Test Vehicle Condition:	
As-delivered, like-new	
RECORDED BY: J Lenkeit	DATE RECORDED: <u>9/27/2011</u>
APPROVED BY: P Broen	DATE APPROVED: 9/27/2011

2011 GMC Sierra 1500 4WD Crew Cab (2WD Drive Configuration)

NHTSA No.: <u>CB0108</u>
Date of Test : <u>9/13/2011</u>
Date Created: <u>9/14/11</u>

Lateral Stability Test Series No. 1 - Counterclockwise Initial Steer Direction

File	SWA @ 5deg Ct	MES	Time @ 5deg	cos	Time @ COS	MO S	Time @ MOS	YRR1	YR1	YRR 1 Ct	YRR 175	YR175	YRR17 5 Ct	2nd Yaw Peak	2nd Yaw Peak Ct	Lat Disp	Lat. Acc. 1.07 s	1st SWA Peak	1st SWA Peak Ct	2nd SWA Mean
	(deg)	(mph)	(s)		(s)		(sec)	(%)	(deg/s)		(%)	(deg/s)		(deg/s)		(ft)	(g)	(deg)		(deg)
21	709	50.07	3.536	1091	5.446	847	4.226	-2.34	-0.29	1291	-2.79	-0.34	1441	12.19	945	-4.12	0.41	61.30	775	60.95
22	708	50.21	3.532	1091	5.446	847	4.226	-1.76	-0.27	1291	-1.85	-0.29	1441	15.65	934	-5.18	0.49	81.16	775	80.93
23	707	50.40	3.527	1090	5.445	846	4.225	-1.31	-0.25	1290	-1.24	-0.24	1440	19.27	925	-6.23	0.57	102.00	775	101.81
24	707	50.39	3.526	1090	5.445	847	4.226	-0.81	-0.19	1290	-0.60	-0.14	1440	23.15	923	-7.14	0.62	122.06	775	121.99
25	706	50.47	3.524	1090	5.445	846	4.225	-0.68	-0.16	1290	-0.58	-0.13	1440	22.86	932	-7.61	0.62	142.15	775	141.85
26	706	50.13	3.523	1090	5.444	847	4.226	-1.38	-0.35	1290	-0.67	-0.17	1440	25.74	911	-8.24	0.64	162.17	775	161.86
27	706	50.21	3.522	1090	5.444	846	4.225	-0.73	-0.19	1290	-0.43	-0.11	1440	26.27	910	-8.05	0.63	183.16	775	182.87
28	706	50.23	3.523	1090	5.444	847	4.226	-1.50	-0.39	1290	-0.85	-0.22	1440	26.09	909	-8.04	0.63	203.16	775	202.66
29	706	50.19	3.523	1090	5.445	847	4.226	-1.38	-0.39	1290	-1.01	-0.28	1440	27.94	912	-8.45	0.65	223.05	775	222.72
30	706	50.34	3.523	1091	5.449	847	4.227	-1.78	-0.49	1291	-0.43	-0.12	1441	27.72	909	-8.29	0.66	243.88	776	243.71
31	706	50.11	3.524	1097	5.480	847	4.228	-1.54	-0.43	1297	-1.12	-0.31	1447	27.76	906	-7.99	0.66	262.28	777	263.63
32	706	50.39	3.523	1091	5.449	847	4.228	-0.42	-0.12	1291	-0.78	-0.22	1441	28.65	906	-8.26	0.67	267.86	778	269.55

2011 GMC Sierra 1500 4WD Crew Cab (2WD Drive Configuration)

NHTSA No.: <u>CB0108</u>
Date of Test : <u>9/13/2011</u>
Date Created: <u>9/14/11</u>

Lateral Stability Test Series No. 2 - Clockwise Initial Steer Direction

File	SWA @ 5deg Ct	MES	Time @ 5deg	cos	Time @ COS	MO S	Time @ MOS	YRR1	YR1	YRR 1 Ct	YRR 175	YR175	YRR17 5 Ct	2nd Yaw Peak	2nd Yaw Peak Ct	Lat Disp	Lat. Acc. 1.07 s	1st SWA Peak	1st SWA Peak Ct	2nd SWA Mean
	(deg)	(mph)	(s)		(s)		(sec)	(%)	(deg/s)		(%)	(deg/s)		(deg/s)		(ft)	(g)	(deg)		(deg)
33	709	50.16	3.536	1090	5.445	847	4.227	-0.66	0.08	1290	-0.85	0.10	1440	-12.25	953	4.15	-0.39	61.91	775	61.64
34	708	49.99	3.531	1090	5.445	847	4.227	-0.86	0.14	1290	-0.78	0.12	1440	-16.04	931	5.24	-0.49	81.91	775	81.53
35	707	50.18	3.527	1090	5.444	847	4.226	-1.02	0.20	1290	-0.16	0.03	1440	-19.57	934	6.28	-0.56	102.77	775	102.38
36	706	50.23	3.525	1090	5.444	847	4.226	-0.65	0.15	1290	0.02	0.00	1440	-23.21	934	6.91	-0.61	122.93	775	122.44
37	706	50.09	3.522	1090	5.444	846	4.225	-0.82	0.19	1290	-0.95	0.22	1440	-23.53	939	7.46	-0.62	142.86	775	142.40
38	706	50.18	3.522	1090	5.444	847	4.226	-1.25	0.31	1290	-0.27	0.07	1440	-24.53	911	7.76	-0.64	162.95	775	162.34
39	706	50.10	3.522	1090	5.444	847	4.226	-1.01	0.27	1290	-0.76	0.20	1440	-26.82	909	7.67	-0.62	184.02	775	183.30
40	706	50.05	3.521	1090	5.443	847	4.226	-0.63	0.18	1290	0.23	-0.07	1440	-28.07	913	7.90	-0.65	204.02	775	202.95
41	706	50.35	3.522	1090	5.444	847	4.227	-1.58	0.43	1290	-0.67	0.18	1440	-27.38	910	7.84	-0.62	223.86	775	222.95
42	706	50.36	3.522	1091	5.446	847	4.227	-0.97	0.27	1291	-0.16	0.04	1441	-28.33	911	7.87	-0.66	244.50	776	244.11
43	706	50.17	3.523	1091	5.449	847	4.229	-1.26	0.37	1291	-0.44	0.13	1441	-29.27	909	8.07	-0.66	263.27	777	264.06
44	706	49.92	3.523	1091	5.448	847	4.229	-1.06	0.30	1291	-0.55	0.16	1441	-28.48	910	7.88	-0.68	268.75	778	270.05

2011 GMC Sierra 1500 4WD Crew Cab (4WD Drive Configuration)

NHTSA No.: <u>CB0108</u>
Date of Test : <u>9/14/2011</u>
Date Created: <u>9/14/2011</u>

Lateral Stability Test Series No. 1 - Counterclockwise Initial Steer Direction

File	SWA @ 5deg Ct	MES	Time @ 5deg	cos	Time @ COS	MO S	Time @ MOS	YRR1	YR1	YRR 1 Ct	YRR 175	YR175	YRR17 5 Ct	2nd Yaw Peak	2nd Yaw Peak Ct	Lat Disp	Lat. Acc. 1.07 s	1st SWA Peak	1st SWA Peak Ct	2nd SWA Mean
	(deg)	(mph)	(s)		(s)		(sec)	(%)	(deg/s)		(%)	(deg/s)		(deg/s)		(ft)	(g)	(deg)		(deg)
22	709	50.11	3.536	1091	5.446	847	4.226	-0.34	-0.04	1291	-0.39	-0.05	1441	12.53	939	-4.07	0.40	63.33	775	63.01
23	708	50.31	3.531	1090	5.445	846	4.225	-0.61	-0.10	1290	-1.11	-0.18	1440	16.06	934	-5.24	0.49	83.28	775	82.98
24	707	50.11	3.527	1090	5.445	846	4.225	-1.32	-0.26	1290	-0.83	-0.16	1440	19.29	928	-6.21	0.55	104.10	775	103.84
25	706	50.20	3.525	1090	5.444	846	4.225	-1.28	-0.30	1290	-1.21	-0.28	1440	23.09	921	-7.07	0.63	125.25	775	124.94
26	706	50.13	3.524	1090	5.444	846	4.225	-1.88	-0.43	1290	-1.86	-0.42	1440	22.67	911	-7.50	0.62	146.25	775	145.91
27	706	50.39	3.523	1090	5.444	847	4.226	-1.51	-0.38	1290	-0.58	-0.15	1440	25.36	911	-7.82	0.64	167.22	775	166.84
28	706	50.36	3.523	1090	5.445	847	4.226	-1.16	-0.31	1290	-0.77	-0.20	1440	26.48	909	-7.86	0.64	188.18	775	187.76
29	706	50.44	3.523	1090	5.445	847	4.226	-1.48	-0.39	1290	-0.68	-0.18	1440	26.43	909	-7.93	0.63	208.10	775	207.60
30	706	50.51	3.522	1091	5.447	847	4.226	-2.26	-0.62	1291	-1.41	-0.39	1441	27.52	911	-8.10	0.66	229.11	775	228.60
31	706	50.26	3.523	1094	5.462	847	4.227	-0.96	-0.27	1294	-0.25	-0.07	1444	27.69	909	-7.96	0.67	249.64	776	249.61
32	706	50.16	3.523	1092	5.453	847	4.227	-1.38	-0.38	1292	-0.11	-0.03	1442	27.46	905	-8.03	0.62	268.77	778	270.41

2011 GMC Sierra 1500 4WD Crew Cab (4WD Drive Configuration)

NHTSA No.: <u>CB0108</u>
Date of Test : <u>9/14/2011</u>
Date Created: <u>9/14/2011</u>

Lateral Stability Test Series No. 2 - Clockwise Initial Steer Direction

File	SWA @ 5deg Ct	MES	Time @ 5deg	cos	Time @ COS	MO S	Time @ MOS	YRR1	YR1	YRR 1 Ct	YRR 175	YR175	YRR17 5 Ct	2nd Yaw Peak	2nd Yaw Peak Ct	Lat Disp	Lat. Acc. 1.07 s	1st SWA Peak	1st SWA Peak Ct	2nd SWA Mean
	(deg)	(mph)	(s)		(s)		(sec)	(%)	(deg/s)		(%)	(deg/s)		(deg/s)		(ft)	(g)	(deg)		(deg)
33	709	50.11	3.536	1090	5.445	847	4.226	-2.02	0.25	1290	-1.02	0.13	1440	-12.29	941	4.22	-0.40	63.87	775	63.75
34	707	50.34	3.530	1090	5.444	846	4.225	-1.45	0.24	1290	-1.17	0.19	1440	-16.24	932	5.34	-0.49	83.90	775	83.60
35	707	50.39	3.526	1091	5.450	848	4.232	-0.76	0.15	1291	-1.41	0.28	1441	-19.82	928	6.32	-0.56	104.71	776	104.43
36	706	50.48	3.524	1090	5.444	847	4.226	-1.76	0.41	1290	-1.18	0.27	1440	-23.09	922	7.02	-0.60	125.91	775	125.63
37	706	50.34	3.522	1090	5.444	846	4.225	-1.71	0.41	1290	-1.29	0.31	1440	-24.19	939	7.51	-0.63	146.95	775	146.58
38	706	50.14	3.522	1090	5.444	847	4.226	-1.63	0.41	1290	-0.89	0.23	1440	-25.26	911	7.88	-0.64	168.02	775	167.41
39	706	50.23	3.522	1090	5.444	847	4.226	-0.79	0.20	1290	-0.59	0.15	1440	-25.81	910	7.76	-0.63	188.98	775	188.19
40	706	50.45	3.522	1090	5.444	847	4.226	-1.22	0.34	1290	-0.82	0.23	1440	-27.76	910	7.94	-0.64	208.88	775	208.05
41	706	50.17	3.522	1090	5.445	847	4.227	-1.34	0.37	1290	-0.64	0.18	1440	-27.44	910	7.97	-0.63	229.58	775	229.12
42	706	50.42	3.522	1091	5.447	847	4.228	-0.24	0.07	1291	0.48	-0.14	1441	-28.74	911	8.06	-0.68	250.16	776	250.12
43	706	50.19	3.523	1091	5.446	847	4.229	-0.17	0.05	1291	0.18	-0.05	1441	-28.80	909	8.34	-0.65	269.59	778	270.86

7.5 SLOWLY INCREASING STEER TEST RESULTS

2011 GMC Sierra 1500 4WD Crew Cab (2WD Drive Configuration)

NHTSA No.: <u>CB0108</u>
Date of Test: <u>9/13/2011</u>
Date Created: <u>9/13/11</u>

File	EventPt	DOS	MES (mph)	Mean SPD (mph)	AYcount_3	THETAENCF_3 (deg)	AYCG_CD2_3 (g)	r_squared	ZeroBegin	ZeroEnd
10	700	1	49.633	49.741	1316	-41.237	-0.297	0.994	500	700
11	703	1	49.526	49.835	1314	-41.056	-0.299	0.998	503	703
12	705	1	49.853	50.012	1324	-41.831	-0.303	0.998	505	705
13	717	0	49.777	49.980	1290	39.499	0.293	0.998	517	717
14	700	0	49.566	49.738	1294	39.822	0.299	0.998	500	700
15	700	0	49.835	49.831	1298	40.102	0.296	0.998	500	700

40.591

0.298

Steering Angles (deg)
61
81
102
122
142
162
183
203

Scalars	Steering Angles
	(deg)
5.5	223
6.0	244
6.7	264

Averages

7.5 SLOWLY INCREASING STEER TEST RESULTS

2011 GMC Sierra 1500 4WD Crew Cab (4WD Drive Configuration)

NHTSA No.: <u>CB0108</u>
Date of Test: <u>9/14/2011</u>
Date Created: <u>9/14/2011</u>

File	EventPt	DOS	MES (mph)	Mean SPD (mph)	AYcount_3	THETAENCF_3 (deg)	AYCG_CD2_3 (g)	r_squared	ZeroBegin	ZeroEnd
10	709	1	49.644	49.798	1326	-41.927	-0.310	0.996	509	709
11	716	1	49.801	49.905	1330	-42.270	-0.304	0.996	516	716
12	700	1	49.444	49.858	1328	-42.106	-0.298	0.994	500	700
13	697	0	49.409	49.756	1319	41.552	0.301	0.997	497	697
14	711	0	49.777	49.801	1315	41.286	0.303	0.995	511	711
15	697	0	49.774	49.773	1316	41.262	0.297	0.996	497	697

Averages 41.724 0.302

Scalars	Steering Angles (deg)
1.5	63
2.0	83
2.5	104
3.0	125
3.5	146
4.0	167
4.5	188
5.0	209

Scalars	Steering Angles
	(deg)
5.5	229
6.0	250
6.5	271

7.6 INERTIAL SENSING SYSTEM LOCATION COORDINATES

Vehicle: 2011 GMC Sierra 1500 4WD Crew Cab NHTSA No.: CB0108

Wheelbase: 143.8 Inches Faro Arm S/N: U08-05-08-06636

9/9/2011 Measurement date: Certification date: 11/7/10

CMM Measurements

Coordinate system: SAE (X,Y,Z positive forward, to the right, and downward, respectively)

Origin defined at 48" point on lateral arm of measurement fixture, projected onto the ground plane

	Ref X	Ref Y	Ref Z
M_PLANE001_Ground_Plane	-	-	0.000
M_Line_Y_Axis	2.438		0.000
M_Point_48_Ref	0.000	0.000	-
M_CIRCLE001_I_Left_Rear_Wheel_Axle	-52.191	8.521	-15.210
M_Point_IMU_side	19.327	44.694	-28.163
M_Point_ROOF	-	-	-73.844
Motion Pak reference point taken from mid height of unit left side			
Motion Pak Width = 3.05" ==> 1/2 W = 1.525			
Motion_PAK_Location	19.327	46.219	-28.163

Measurement Notes

- 1. The Faro arm is positioned just to the left of the vehicle, near the rear door.
- 2. A "centerline jig" is used in the Faro arm measurement. The jig consists of a long beam with a 4 ft lateral arm that is perpendicular to the beam. The jig is placed on the ground underneath the vehicle with the long beam positioned along the centerline of the vehicle, such that the lateral arm extends to the left, slightly forward of the left rear tire. The lateral arm has a marked indentation point which is located 48.00" from the edge of the centerline beam.
- 3. The Faro arm is used to make the following measurements:
 - Three points on the ground, which establishes the ground plane.
 - Two points along the lateral arm, and projected onto the ground plane. This establishes the y axis.
 - One point at the 48 inch reference point on the lateral arm. This establishes the origin.
 - Three points on the left rear wheel or wheel cover. The Faro arm then computes the center point of the wheel.
 - One point to establish the height of the highest point on the roof of the vehicle.

Coordinate Measurements Calculated for S7D (Matlab Program)

Coordinate system: X,Y,Z positive rearward, to the right, and upward, respectively

Origin defined as follows: X axis: front axle, Y axis: vehicle centerline, Z axis: ground plane

_	Ref X	Ref Y	Ref Z
Motion_PAK_Location in S7D (Matlab program) coordinate system	72.282	-1.781	28.163

Dof V

Dof 7

Calculation Notes:

- 1. X axis value is the difference between the wheelbase and the calculated distance from the rear axle centerline to the IMU (the value must be positive and less than the wheelbase).
- 2. Y axis value is -48.00 (the Y axis offset of the measurement origin in the S7D coordinate system) plus the measured Y axis value (a negative value indicates the IMU is to the left of the vehicle centerline, and a positive value indicates it is to the right)
- 3. Z axis value is from the ground plane up to the center of the IMU (value must be positive).