# 126-TRC-07-004

SAFETY COMPLIANCE TESTING FOR FMVSS 126 (Indicant) **Electronic Stability Control Systems** 

> Toyota Motor Company 2008 Toyota Highlander NHTSÁ No. Č85104

TRANSPORTATION RESEARCH CENTER INC. 10820 State Route 347

East Liberty, Ohio 43319



December 13, 2007

#### **FINAL REPORT**

Prepared Under Contract No.: DTNH22-07-P-00332

**U. S. DEPARTMENT OF TRANSPORTATION** National Highway Traffic Safety Administration Enforcement Office of Vehicle Safety Compliance 1200 New Jersey Avenue, SE West Building, 4<sup>th</sup> Floor (NVS-221) Washington, DC 20590

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# **SECTION**

#### 1.0 PURPOSE OF COMPLIANCE TEST

The purpose of this test is to determine if the test vehicle, an MY 2008 Toyota Highlander meets the minimum equipment and performance requirements stated in Federal Motor Vehicle Safety Standard (FMVSS) 126, "Electronic Stability Control Systems."

This test is considered an "Indicant" Test because manufacturers are not required to certify vehicles to FMVSS 126 until on or after September 1, 2008.

This standard establishes performance and equipment requirements for Electronic Stability Control (ESC) Systems installed in passenger cars, multipurpose passenger vehicles, trucks and buses with a gross vehicle weight rating of 4,536 kilograms or less.

### 2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS

Testing of the MY 2008 Toyota Highlander was conducted at Transportation Research Center Inc. (TRC Inc.) in accordance with NHTSA TP-126-00, dated April 6, 2007.

The vehicle was inspected to ensure it was equipped with an ESC System that:

- Augments vehicle directional stability by applying and adjusting brake torques individually at each wheel to induce a correcting yaw moment to a vehicle;
- Is computer controlled with the computer using a closed-loop algorithm to limit vehicle oversteer and to limit vehicle understeer;
- Has a means to determine the vehicle's yaw rate and to estimate its side slip or side slip derivative with respect to time;
- Has a means to monitor driver steering inputs;
- Has an algorithm to determine the need, and a means to modify engine torque, as necessary, to assist the driver in maintaining control of the vehicle, and
- Is operational over the full speed range of the vehicle (except at vehicle speeds less than 15km/h (9.3mph) or when being driven in reverse).

The vehicle was subjected to a 0.7Hz sine with dwell steering maneuver to ensure that it would meet the stability and responsiveness requirements of the standard as follows:

- At 1.0 second after completion of a required sine with dwell steering input, the yaw rate of the vehicle must not exceed 35 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).
- At 1.75 seconds after completion of a required sine with dwell steering input, the yaw rate of the vehicle must not exceed 20 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between

first and second peaks during the same test run).

- The lateral displacement of the vehicle center of gravity with respect to its initial straight path must be at least 1.83 m (6 feet) (for vehicles with a GVWR of 3,500kg (7,716 lb) or less) when computed 1.07 seconds after the Beginning of Steer (BOS) at the specified steering wheel angles.

System malfunction simulations were executed to verify vehicle could identify and indicate a malfunction.

The vehicle's ESC System appears to meet the performance and equipment requirements as required by FMVSS 126. The test results are summarized on the following summary sheet.

# 2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS ... continued

# DATA SUMMARY SHEET (1 of 2)

VEHICLE MAKE/MODEL/BODY STYLE: Toyota / Highlander / MPV
VEHICLE NHTSA NO.: <u>C85104</u> VIN: <u>JTEES41A582004636</u>
VEHICLE TYPE: <u>MPV</u> DATE OF MANUFACTURE: <u>06/07</u>
LABORATORY: Transportation Research Center Inc.
REQUIREMENTSPASS/FAILESC Equipment and Operational Characteristics (Data Sheet 2)
The vehicle is be equipped with an ESC system that meets the equipment
ESC Malfunction Telltale – Location, Labeling and Bulb Check (Data Sheet 3)
Telltale meets the requirements for mounting, symbol or text, color <u>SEE REMARKS</u> and check of lamp function. (S126, S5.3.1*, S5.3.2*, S5.3.4* and S5.3.5, S5.3.6)
"ESC Off" and other System Controls and Telltale* (Data Sheet 3)
If provided, ESC OFF telltale meets the requirements for mounting, symbol or abbreviation, color and check of lamp function. (S126, S5.5.1, S5.5.2*, S5.5.3*, S5.5.6*, S5.5.7, and S5.5.8)
If provided, dedicated off control meets the label requirementsPASS
(S126, S5.4.2*)
If provided, off control and other system controls meets the operational PASS requirements (S126, S5.4, S5.4.1, S5.4.3*, S5.5.4, and S5.5.9)
Vehicle Lateral Stability (Data Sheet 7)
Yaw Rate Ratio at 1 second after COS is less than 35% of peak value. PASS (S126, S5.2.1)
Yaw Rate Ratio at 1.75 seconds after COS is less than 20% of peak value. PASS (S126, S5.2.2)

### 2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS ... continued

#### DATA SUMMARY SHEET (2 of 2)

#### REQUIREMENTS

PASS/FAIL

#### Vehicle Responsiveness (Data Sheet 7)

Lateral displacement at 1.07 seconds after BOS is at least 1.83 m (6 feet) for vehicles with a GVWR of 3,500kg (7,716 lbs.) or less, and 1.52 m (5 feet) for vehicles with a GVWR greater than 3,500 kg (7,716 lbs.). (S126 S5.2.3)	PASS
ESC Malfunction Warning (Data Sheet 8)	
Warning is provided to driver after malfunction occurrence. (S126. S5.3.3*)	PASS
Malfunction telltale stayed illuminated as long as malfunction existed and must extinguished after malfunction was corrected. (S126, S5.3.3*, S5.3.7)	PASS

\*Requirements effective on and after September 1, 2011.

#### **REMARKS**:

ESC System malfunction and off telltales and controls do not have to meet the requirements of FMVSS No. 126 until on or after September 1, 2011.

# 3.0 TEST DATA

### DATA SHEET 1 TEST VEHICLE INSPECTION AND TEST PREPARATION

VEHICLE MAKE/MODEL/BODY STYLE: Toyota / Highlander / MPV				
NHTSA No.: <u>C85104</u> TEST DATE: <u>9-20-07</u>				
VIN: JTEES41A582004636 MANUFACTURE DATE: 06/07				
GVWR: <u>2,720</u> KG FRONT GAWR: <u>1,340</u> KG REAR GAWR <u>1,585</u> KG				
SEATING POSITIONS: FRONT 2 MID 3 REAR 2				
ODOMETER READING AT START OF TEST: <u>3,314 (5,333)</u> Miles (Kilometers)				
DESIGNATED TIRE SIZE(S) FROM VEHICLE LABELING: Front Axle P245 / 65R 17 Rear Axle P245 / 65R 17				
INSTALLED TIRE SIZE(S) ON VEHICLE:From Tire SidewallFront AxleRear Axle				
Manufacturer and Model Bridgestone Dueler H/L 400 Bridgestone Dueler H/L 400				
Tire Size Designation P245 / 65R 17 105S P245 / 65R 17 105S				
Are installed tire sizes same as labeled tire sizes? <u>X</u> Yes <u>No</u> If no, contact COTR for further guidance.				
DRIVETRAIN CONFIGURATION:         Front Wheel Drive (FWD)       Rear Wheel Drive (RWD)         Four Wheel Drive (4WD)       All Wheel Drive (AWD)				
X       ESC       X       Traction Control       Roll Stability Control        Active Suspension       X       Electronic Throttle Control       Active Steering        ABS      Ist other systems;       Steering torque assist (Enhanced VSC)				
REMARKS:				

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

# DATA SHEET 2 (Sheet 1 of 2) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

VEHICLE MAKE/MODEL/BODY STYLE: Toyota / Highla	ander / MPV
NHTSA No.: C85104 TEST DA	TE: <u>10-19-07</u>
ESC SYSTEM IDENTIFICATION: Manufacturer/Model <u>Advics Company, Ltd. Mode</u>	l# 44540-48230
ESC SYSTEM HARDWARE (Check applicable hardwareXElectronic Control UnitXXWheel Speed SensorsXXYaw Rate SensorXXLateral Acceleration	e): Unit ensor on Sensor
List other components;	
ESC SYSTEM OPERATIONAL CHARACTERISTICS:	
System is capable of generating brake torques at each w	/heel <u>X</u> Yes (PASS) No (FAIL)
List and describe component(s):_Brake Actuator	、 ,
System is capable of determining yaw rate	<u>X</u> Yes (PASS) No (FAIL)
List and describe component(s): Yaw Rate Sensor	
System is capable of monitoring driver steering input List and describe component(s): <u>Steering Wheel Angle</u>	<u>X</u> Yes (PASS) No (FAIL)
System is capable of estimating side slip or side slip deri	vation <u>X</u> Yes (PASS) No (FAIL)
List and describe component(s): <u>Steering Wheel Angle</u> Yaw Rate Sensor Lateral Acceleration S	Sensor

# DATA SHEET 2 (Sheet 2 of 2) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

# ESC SYSTEM OPERATIONAL CHARACTERISTICS (continued):

System is capable of modifying engine torque during ESC activation. X Yes (PASS) No (FAIL)
Method used to modify engine torque: <u>ESC actuates Engine Control System</u>
System is capable of activation at speeds of 15 km/h (9.3 mph) X Yes (PASS) and higher.
Speed system becomes active. <u>15 km/h</u>
System is capable of activation during the following driving Yes (PASS) phases (acceleration, deceleration, coasting, and during No (FAIL) activation of ABS or traction control).
Driving phases system is capable of activation. <u>All phases listed above</u>
Vehicle manufacturer submitted documentation explaining how the <u>X</u> Yes (PASS) ESC system mitigates understeer? <u>No (FAIL)</u>
DATA INDICATES COMPLIANCE PASS/FAIL PASS
REMARKS:

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

#### DATA SHEET 3 (Sheet 1 of 5) ESC MALFUNCTION AND OFF TELLTALES AND CONTROLS – Location, Labeling and Bulb Check

VEHICLE MAKE/MODEL/BODY STYLE: <u>Toyota / Highlander / MPV</u>					
NHTSA No.: <u>C85104</u> TEST DATE: <u>9-25-07</u>					
<b>ESC Malfunction Telltale</b> Malfunction Telltale LocationInstrument Panel Cluster - Inside Tachometer Gauge					
Telltale is mounted inside the occupant compartment in front of and in clear view of the driver?					
No (fail) If no, explain: Telltale is part of a common space?YesX_No					
Malfunction Telltale symbol or abbreviation required by FMVSS No. 101.					
Or     ESC     X     Vehicle uses this symbol					
Note any words or additional symbols used.					

Also, "VSC Off" abbreviation located next to above symbol flashes

# "ESC OFF" Telltale (if provided)

"ESC OFF" Telltale Location <u>"VSC Off" telltale is combined with ESC malfunction</u> telltale located in the instrument panel cluster inside the tachometer gauge.

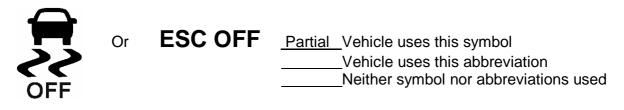
"ESC OFF" telltale is mounted inside the occupant compartment in front of and in clear view of the driver?

X	Yes	No (fail)	If no, explain:	

Telltale is part of a common space? Yes X No

#### DATA SHEET 3 (Sheet 2 of 5) ESC MALFUNCTION AND OFF TELLTALES AND CONTROLS

"ESC OFF" Telltale symbol or abbreviation required by FMVSS No. 101.



Note any words or additional symbols used.

 The ESC Symbol above is used without the word "OFF" below the symbol.	
In addition the "VSC OFF" abbreviation located next to the above symbol	
illuminates.	

#### Malfunction Telltale Lamp Function:

Identify position of ignition locking system when malfunction telltale illuminates.

OFF/LOCK	Between OFF/LOCK and ON/RUN
X ON/RUN	Between ON/RUN and Start
Is telltale yellow in color? <u>X</u> Yes	No (fail)
Time telltale remains illuminated 3	seconds
Note: If telltale is part of common sp check of lamp function.	ace, it is not required to illuminate during this
Starter Interlock:	
•	or other interlocks that affect operation of the
Mal-function telltale lamp check functions?	Yes X No

If yes, describe the interlock feature:

#### DATA SHEET 3 (Sheet 3 of 5) ESC MALFUNCTION AND OFF TELLTALES AND CONTROLS

#### "ESC OFF" Telltale Lamp Function:

Identify position of ignition locking system when "ESC OFF" telltale illuminates.

OFF/LOCK	Between OFF/LOCK and ON/RUN
X ON/RUN	Between ON/RUN and Start
Is telltale yellow in color? X	Yes No (fail)
Time telltale remains illuminated	<u>3</u> seconds

Note: If telltale is part of common space, it is not required to illuminate during the check of lamp function.

#### Starter Interlock:

Does vehicle have any starter, transmission or other interlocks that affect operation of the "ESC OFF" telltale lamp check functions? Yes X No

If yes, describe the interlock feature:

#### **ESC OFF Control Operational Check:**

Is the vehicle equipped with a control whose sole purpose is to deactivate the ESC System? X Yes No

"ESC OFF" Control identification symbol or abbreviation required by FMVSS No. 101.



ESC OFF Or

<u>X</u> Vehicle uses this symbol

Vehicle uses this abbreviation

Note any words or additional symbols used.

#### DATA SHEET 3 (Sheet 4 of 5) ESC MALFUNCTION AND OFF TELLTALES AND CONTROLS

Does the "ESC Off" telltale illuminate upon activation of the ESC off control?

If no, describe off control function:

Does the "ESC Off" telltale extinguish when the	0		5	') to
"Lock" or "Off" and then back again to the "On" (	("Run"	) positio	on?	
	Х	Yes	No (fail)	
If no, describe the off control function:				

#### Other System Controls that have an ancillary effect on ESC Operation:

List other controls (i.e. low speed off-road axle/transfer case):

Does the "ESC OFF" telltale illuminate upon ac	tivation of each con	trol system lis	ted above?
	Yes	Ňo	
If no, describe off control function:			

For electrical controls, does the "ESC OFF" telltale extinguish and remain extinguished when the ignition is cycled from "On" ("Run") to "Lock" or "Off" and then back again to the "On" ("Run") position?

\_\_\_\_Yes \_\_\_\_No

none

If no, describe the off control function:

#### DATA SHEET 3 (Sheet 5 of 5) ESC MALFUNCTION AND OFF TELLTALES AND CONTROLS

For mechanical controls, does the "ESC OFF" telltale extinguish after de-activation of mechanical control?

If no, describe the off control function:

DATA INDICATES COMPLIANCE:

PASS/FAIL PASS

**REMARKS**:

The Highlander uses ESC malfunction and off telltales that differ from those required by FMVSS No. 126 and 101. However, the telltale symbols or abbreviations used are not required to meet the standard requirements until on or after September 1, 2011.

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

#### DATA SHEET 4 (Sheet 1 of 3) VEHICLE AND TEST TRACK DATA

VEHICLE MAKE/MODEL/	BODY STYLE: <u>Toy</u>	ota / Highlander /	MPV
NHTSA No.: C8510	04	TEST DATE:	9-25-07
Test Track Requirements	s: Test Surface	e Slope (0-1 %)	%
	Peak Frictio	n Coefficient (at le	ast 0.9) <u>0.96</u>
Full Fluid Levels: Fuel _	X Coolant	X Other Flu	ids <u>Washer</u> (specify)
Tire Pressures: Requi Actual: LF <u>210.0 K</u>			ar Axle <u>210.0</u> KPA PA RR <u>210.0</u> KPA
Vehicle Dimensions:	Track Width 162.5	<u>5</u> cm Wheelbas	e <u>279.0</u> cm
	Roof Height 169.8	<u>}_</u> cm	
Vehicle weight ratings:	GAWR Front 1	<u>,340 </u> KG GA	WR Rear <u>1,585</u> KG

# Unloaded Vehicle Weight (UVW)

Front Axle	1,097.0	_KG	Right Front <u>548.0</u> K0	G Left Front	549.0	_KG
Rear Axle	867.0	KG	Right Rear <u>427.0</u> K	G Left Rear	440.0	_KG
Total UVW	1,964.0	_KG				

#### Baseline Weight and Outrigger Selection (only for MPVs, Trucks, Buses)

Calculated Baseline Weight (UVW+ 73 kg) 2,037 KG

Outrigger size required ("Standard" or "Heavy") <u>Standard</u> Standard - Baseline weight under 2,722 kg (6,000 lbs) Heavy - Baseline weight equal to or greater than 2,722 kg (6,000 lbs)

#### DATA SHEET 4 (Sheet 2 of 3) VEHICLE AND TEST TRACK DATA

UVW with Outriggers (only for MPVs, Trucks, Buses)

Rear Axle	911.0	_KG	Right Rear 449	<u>.0 K</u> G	Left Rear	462.0	_KG
Front Axle	1,143.0	_KG	Right Front 570	<u>.0   </u> KG	Left Front	573.0	_KG

Total UVW w/ Outriggers 2,054.0 KG

Loaded Vehicle Weight w/ Driver and Instrumentation (No Ballast)

Front Axle	1,222.0	_KG	Right Front <u>599.0</u> KG	Left Front 623.0	_KG
Rear Axle	980.0	_KG	Right Rear <u>477.0</u> KG	Left Rear <u>503.0</u>	_KG

Total Loaded weight w/ Driver 2,202.0 KG

Ballast Required = [UVW w/ Outriggers + 168 KG] - Total Loaded Weight w/ Driver and Instrumentation

= [<u>2,054.0</u> KG + 168 KG] - <u>2,202.0</u> KG

= <u>20.0 K</u>G

#### **Total Loaded Vehicle Weight**

Total Loade	d Vehicle \	Neight_	2,221.0	KG				
Rear Axle	993.0	_KG	Right Rear_	485.0	_KG	Left Rear	508.0	_KG
Front Axle	1,228.0	_KG	Right Front	607.0	_KG	Left Front	621.0	_KG

#### DATA SHEET 4 (Sheet 3 of 3) VEHICLE AND TEST TRACK DATA

### Center of Gravity and Inertial Sensing System Location at Loaded Vehicle Condition

x-distance (longitudinal)	Point of reference is the front axle centerline. (Positive from front axle toward rear of vehicle.)
y-distance (lateral)	Point of reference is the vehicle centerline. (Positive from the center toward the right.)
z-distance (vertical)	Point of reference is the ground plane. (Positive from the ground up.)

#### Locations:

	Center of Gravity	Inertial Sensing System
x-distance	<u>    124.7 </u> cm	<u>    176.8 </u> cm
y-distance	<u>-1.32</u> cm	<u>-1.63</u> cm
z-distance	<u>    64.5  </u> cm	<u> </u>

Distance Between Ultrasonic Sensors: 196.2 cm

TEST TRACK DATA MEETS REQUIREMENTS:	YES/NO	YES	
If no, explain:			

#### **REMARKS**:

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

# DATA SHEET 5 (Sheet 1 of 3) BRAKE AND TIRE CONDITIONING

VEHICLE MAKE/MODEL/BODY STYLE: Toyota / Highlander / MPV				
VEHICLE NHTSA No.: C851	04			
Measured Cold Tire Pressures:	LF <u>210</u> KPA	LR <u>210</u> KPA		
	RF <u>210</u> KPA	RR <u>210</u> KPA		
Wind Speed <u>1.3</u> (10m/sec (22mph) max for pass		nax. for MPVs and Trucks)		
Ambient Temperature (7°C (45°l	F) - 40°C (104°F))	<u>19.4</u> °C		
Brake Conditioning	Time; <u>3:30 PM</u>	Date; <u>9-27-07</u>		
56 km/h (35 mph) Brake S	Stops			
Number of stops e	xecuted (10 required)	<u> </u>		
Observed decelera	tion rate range (.5g target)	<u>0.45 – 0.55</u> g		
72 km/h (45 mph) Brake S	Stops			
Number of stops ex	xecuted (3 required)	<u> </u>		
Number of stops A	<u> </u>			
Observed decelera	<u>0.9 – 1.0</u> g			
72 km/h (45 mph) Brake (	Cool Down Period			
Duration of cool do	wn period (5 minutes min.)	5.5 minutes		

#### DATA SHEET 5 (Sheet 2 of 3) BRAKE AND TIRE CONDITIONING

Tire Conditioning Series No. 1	Time:	<u>9:00 a</u>	m	Date:	9-28-07
Measured Tire Pressures:	LF	210	_KPA	LR	<u>210   </u> KPA
	RF	210	_KPA	RR	<u>210</u> KPA

Wind Speed <u>3.1</u> m/sec (10m/sec (22mph) max for passenger cars; 5m/s (11mph) max. for MPVs and Trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) <u>15.0</u> °C

30 meter (100 ft) Diameter Circle Maneuver					
Test Runs         Steering Direction         Target Lateral         Observed Lateral         Observed Vehi           Acceleration (g)         Acceleration (g)         Speed (km/h)					
1-3	Clockwise	0.5-0.6	0.55	44	
4-6	Counterclockwise	0.5-0.6	0.55	44	

1 Hz 3 Cycle Sinusoidal Steering Maneuver to Determine Steering Wheel Angle For 0.5-0.6g Lateral Acceleration						
Test Runs	Vehicle Speed Km/h(mph)	Steering Wheel Angle (degrees)	Target Peak Lateral Acceleration (g)	Observed Peak Lateral Acceleration (g)		
1	56 <u>+</u> 2 (35 <u>+</u> 1)	30	0.5-0.6	0.20		
2	56 <u>+</u> 2 (35 <u>+</u> 1)	90	0.5-0.6	0.52		
3	56 <u>+</u> 2 (35 <u>+</u> 1)		0.5-0.6			
4	56 <u>+</u> 2 (35 <u>+</u> 1)		0.5-0.6			

Steering wheel angle that corresponds to a peak 0.5–0.6g lateral acceleration; <u>90</u> degrees

1 Hz 10 Cycle Sinusoidal Steering Maneuver						
Test Runs	Vehicle Speed Km/h (mph)	Steering Wheel Angle (degrees)	Target Peak Lateral	Observed Peak Lateral		
			Acceleration (g)	Acceleration (g)		
1 - 3	56 <u>+</u> 2 (35 <u>+</u> 1)	90 (cycles 1-10)	0.5-0.6	0.52		
4	56 <u>+</u> 2 (35 <u>+</u> 1)	90 (cycles 1-9)	0.5-0.6	0.52		
		180 (cycle 10)*	N/A	N/A		

\* The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9.

#### DATA SHEET 5 (Sheet 3 of 3) BRAKE AND TIRE CONDITIONING

Tire Conditioning Series No. 2		Time:	10:40 AM		Date:	9-28-07
Measured Tire Pressures:	LF	221	_ KPA	LR	<u>221</u>	_KPA
	RF	221	_ KPA	RR	221	_KPA

Wind Speed <u>5.8</u> m/sec (10m/sec (22mph) max for passenger cars; 5m/s (11mph) max. for MPVs and Trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) <u>17.2</u> °C

30 meter (100 ft) Diameter Circle Maneuver					
Test Runs	Steering Direction	Target Lateral	Observed Lateral	Observed Vehicle	
		Acceleration (g)	Acceleration (g)	Speed (km/h)	
1-3	clockwise	0.5-0.6	0.55	44	
4-6	counterclockwise	0.5-0.6	0.55	44	

1 Hz 3 Cycle Sinusoidal Steering Maneuver to Determine Steering Wheel Angle For 0.5-0.6g Lateral Acceleration					
Test Runs	Vehicle Speed	Steering Wheel	Target Peak	Observed Peak	
	Km/h (mph)	Angle (degrees)	Lateral	Lateral	
			Acceleration (g)	Acceleration (g)	
1	56 <u>+</u> 2 (35 <u>+</u> 1)	30	0.5-0.6	N/A	
2	56 <u>+</u> 2 (35 <u>+</u> 1)	90	0.5-0.6	0.52	
3	56 <u>+</u> 2 (35 <u>+</u> 1)		0.5-0.6		
4	56 <u>+</u> 2 (35 <u>+</u> 1)		0.5-0.6		

Steering wheel angle that corresponds to a peak 0.5–0.6g lateral acceleration; <u>90</u> degrees

1 Hz 10 Cycle Sinusoidal Steering Maneuver						
Test Runs	Vehicle Speed	Steering Wheel	Target Peak	Observed Peak		
	(mph)	Angle (degrees)	Lateral	Lateral		
			Acceleration (g)	Acceleration (g)		
1 - 3	56 <u>+</u> 2 (35 <u>+</u> 1)	90 (cycles 1-10)	0.5-0.6	0.52		
4	56 <u>+</u> 2 (35 <u>+</u> 1)	90 (cycles 1-9)	0.5-0.6	0.52		
		180 (cycle 10)*	N/A	N/A		

\* The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9.

#### **REMARKS**:

The tire pressures for Tire Conditioning Series No. 1 were the cold settings, which were recorded prior.

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

#### DATA SHEET 6 (1 of 2) SLOWLY INCREASING STEER (SIS) MANEUVER

VEHICLE MAKE/MODEL/BODY STYLE: <u>Toyota / Highlander / MPV</u>

VEHICLE NHTSA No.: C85104 TEST DATE: 9-28-07

Wind Speed <u>3.6</u> m/sec (10m/sec (22mph) max for passenger cars; 5m/s (11mph) max. for MPVs and Trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) <u>15.6</u> °C

#### Preliminary Left Steer Maneuver:

Lateral Acceleration measured at 30 degrees steering wheel angle ( $a_{y,30 \text{ degrees}}$ )  $a_{y,30 \text{ degrees}} = \underbrace{0.26 \text{ g}}$ 

Assuming a linear relationship the following ratio should be used to calculate the steering wheel angle at .55g.

 $\frac{30 \text{ degrees}}{a_{\text{y},30 \text{ degrees}}} = \frac{\delta_{SIS}}{0.55 \text{ g}}$ 

 $\delta_{S/S} = ____70$  degrees

#### **Steering Wheel Angle at Corrected 0.3 g Lateral Acceleration:**

Maneuver #	Initial Steer Direction	Time Clock (5 min max between runs)	Steering Wheel Angle to nearest 0.1 degree (degrees)	All Conditions Met?
1	Left	9:32 am	-37.1	Yes
2	Left	9:47 am	-36.4	Yes
3	Left	9:50 am	-36.7	Yes
4	Right	9:52 am	37.7	Yes
5	Right	9:56 am	36.8	Yes
6	Right	9:58 am	36.2	Yes

### DATA SHEET 6 (2 of 2) SLOWLY INCREASING STEER (SIS) MANEUVER

# Average Overall Steering Wheel Angle:

$$\begin{split} \delta_{0.3 \text{ g, overall}} &= \left( \left| \delta_{0.3 \text{ g, left (1)}} \right| + \left| \delta_{0.3 \text{ g, left (2)}} \right| + \left| \delta_{0.3 \text{ g, left (3)}} \right| + \delta_{0.3 \text{ g, right (1)}} + \delta_{0.3 \text{ g, right (2)}} + \delta_{0.3 \text{ g, right (3)}} \right) / \\ 6 \end{split}$$

 $\delta_{0.3 \text{ g, overall}} = 36.8 \text{ degrees}$ [to nearest 0.1 degree]

**REMARKS**:

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

#### DATA SHEET 7 (1 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

VEHICLE MAKE/MODEL/BODY STYLE:	/ Highlander / MPV
VEHICLE NHTSA No.: C85104 TEST	DATE: <u>9-28-07</u>
Tire conditioning completed ESC System is enabled On track calibration checks have been completed On track static data file for each sensor obtained	X         Yes         No           X         Yes         No
Overall steering wheel angle ( $\delta_{0.3 \text{ g, overall}}$ ) 36.8	degrees

#### Lateral Stability Test Series No. 1 – Counterclockwise Initial Steer Direction

	ability 100									
		Comma			Yaw Rate		Y	RR		RR
	Clock	Steering		(0	degrees/s	ec)		sec after		sec after
Maneuver	Time	Angle						OS		OS
#	(1.5 – 5 min	(degre	,		1			35%]		20%]
	between	Scalar	Angle	$\dot{\psi}_{\scriptscriptstyle Peak}$	ŵ.	<i>w</i>	%	Pass/	%	Pass/
	each test			Ψ Peak	$\psi_{1.0  m sec}$	$\Psi_{1.75 m sec}$		Fail		Fail
	run)									_
1	10:57 am	1.5* δ <sub>0.3 g</sub>	55	12.52	-0.42	-0.26	-3.34	Pass	-2.05	Pass
2	11:00 am	2.0* δ <sub>0.3 g</sub>	74	16.17	-0.17	-0.03	-1.07	Pass	-0.16	Pass
3	11:04 am	2.5* δ <sub>0.3 g</sub>	92	20.46	-0.04	-0.02	-0.22	Pass	-0.11	Pass
4	11:07 am	<b>3.0*</b> δ <sub>0.3 g</sub>	110	25.49	-0.15	-0.01	-0.60	Pass	-0.02	Pass
5	11:10 am	3.5* δ <sub>0.3 q</sub>	129	31.28	-0.25	-0.18	-0.80	Pass	-0.56	Pass
6	11:13 am	4.0* δ <sub>0.3 g</sub>	147	38.28	0.19	0.05	0.50	Pass	0.14	Pass
7	11:16 am	4.5* δ <sub>0.3 g</sub>	166	44.68	1.16	0.09	2.59	Pass	0.21	Pass
8	11:19 am	5.0* δ <sub>0.3 g</sub>	184	49.66	1.22	-0.08	2.45	Pass	-0.16	Pass
9	11:22 am	5.5* δ <sub>0.3 q</sub>	202	53.10	2.71	0.14	5.10	Pass	0.26	Pass
10	11:25 am	6.0* δ <sub>0.3 g</sub>	221	53.04	0.94	-0.06	1.78	Pass	-0.11	Pass
11	11:28 am	<b>6.5</b> * δ <sub>0.3 g</sub>	239	54.62	0.44	0.08	0.81	Pass	0.14	Pass
12	11:31 am	<b>7.0*</b> δ <sub>0.3 g</sub>	258	54.67	1.57	0.10	2.86	Pass	0.18	Pass
13	11:34 am	<b>7.3*</b> δ <sub>0.3 g</sub>	270	53.28	-0.84	-0.09	-1.57	Pass	-0.17	Pass

1. Maneuver execution should continue until a steering wheel angle magnitude factor of  $6.5^* \delta_{0.3 \text{ g, overall}}$  or 270 degrees is utilized, whichever is greater provided the calculated magnitude of  $6.5^* \delta_{0.3 \text{ g, overall}}$  is less than or equal to 300 degrees. If  $6.5^* \delta_{0.3 \text{ g, overall}}$  is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of  $0.5^* \delta_{0.3 \text{ g, overall}}$  without exceeding the 270 degree steering wheel angle.

#### DATA SHEET 7 (2 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

Lateral Sta	whity res	L Selles IN	0.2 - 0	JIUCKWI			mech			
		Comma	nded		Yaw Rate	es	Y	RR	Y	RR
	Clock	Steering	Wheel	(c	legrees/s	ec)	at 1.0 s	sec after	at 1.75	sec after
Maneuver	Time	Angl						OS		OS
#	(1 E E main	(degre					[< 3	35%]	[< 2	20%]
	(1.5 – 5 min between	Scalar	Angle	$\dot{\psi}_{\scriptscriptstyle Peak}$	nic	nic	%	Pass/	%	Pass/
	each test			$\Psi$ Peak	$\psi_{1.0  ext{sec}}$	$\psi_{1.75 m sec}$		Fail		Fail
	run)									
1	11:37 am	1.5* δ <sub>0.3 g</sub>	55	-12.86	-0.02	-0.04	0.17	Pass	0.28	Pass
2	11:40 am	2.0* δ <sub>0.3 q</sub>	74	-16.93	0.01	-0.11	-0.04	Pass	0.68	Pass
3	11:43 am	<b>2.5*</b> δ <sub>0.3 g</sub>	92	-20.85	0.17	0.11	-0.80	Pass	-0.53	Pass
4	11:46 am	<b>3.0*</b> δ <sub>0.3 g</sub>	110	-25.48	0.06	-0.06	-0.25	Pass	0.23	Pass
5	11:49 am	<b>3.5</b> * δ <sub>0.3 g</sub>	129	-31.82	-0.21	-0.04	0.65	Pass	0.14	Pass
6	11:51 am	4.0* δ <sub>0.3 g</sub>	147	-37.00	-0.43	-0.09	1.15	Pass	0.25	Pass
7	11:54 am	4.5* δ <sub>0.3 g</sub>	166	-43.39	-0.97	-0.18	2.23	Pass	0.41	Pass
8	11:57 am	5.0* δ <sub>0.3 g</sub>	184	-48.75	-1.64	0.09	3.36	Pass	-0.19	Pass
9	12:00 pm	5.5* δ <sub>0.3 q</sub>	202	-52.37	-2.03	-0.12	3.88	Pass	0.22	Pass
10	12:03 pm	6.0* δ <sub>0.3 g</sub>	221	-52.58	-0.79	0.00	1.51	Pass	-0.01	Pass
11	12:06 pm	<b>6.5</b> * δ <sub>0.3 g</sub>	239	-48.29	0.20	-0.18	-0.41	Pass	0.37	Pass
12	12:08 pm	<b>7.0*</b> δ <sub>0.3 g</sub>	258	-49.69	0.05	-0.06	-0.11	Pass	0.13	Pass
13	12:11 pm	<b>7.3*</b> δ <sub>0.3 g</sub>	270	-50.16	0.07	-0.06	-0.13	Pass	0.11	Pass

#### Lateral Stability Test Series No. 2 - Clockwise Initial Steer Direction

 Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5<sup>\*</sup>δ<sub>0.3.g, overall</sub> or 270 degrees is utilized, whichever is greater provided the calculated 6.5<sup>\*</sup>δ<sub>0.3.g, overall</sub> is less than or equal to 300 degrees. If 6.5<sup>\*</sup>δ<sub>0.3.g, overall</sub> is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5<sup>\*</sup>δ<sub>0.3.g, overall</sub> without exceeding the 270 degree steering wheel angle.

During execution of the sine with dwell maneuvers were any of the following events observed?

Rim-to-pavement contact	Yes	<u> </u>	No
Tire debeading	Yes	Χ	_ No
Loss of pavement contact of vehicle tires	Yes	Χ	_ No
Did the test driver experience any vehicle	Yes	X	No
loss of control or spinout?			

If "Yes" explain the event and consult with the COTR.

#### DATA SHEET 7 (3 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

#### **Responsiveness – Lateral Displacement**

		Commanded Steer (5.0* $\delta_{0.3 \text{ g, overall}}$	• •	Calculated Later	al Displacement <sup>1</sup>
Maneuver #	Initial Steer Direction	Scalar	Angle (degrees)	Distance (m)	Pass/Fail
8	Counter Clockwise	<b>5.0*</b> δ <sub>0.3 g</sub>	184	2.91	Pass
9	Counter Clockwise	5.5*δ <sub>0.3 g</sub>	202	2.98	Pass
10	Counter Clockwise	6.0*δ <sub>0.3 g</sub>	221	2.98	Pass
11	Counter Clockwise	6.5*δ₀.₃ ց	239	3.01	Pass
12	Counter Clockwise	7.0* δ <sub>0.3 g</sub>	258	3.06	Pass
13	Counter Clockwise	<b>7.3</b> * δ <sub>0.3 g</sub>	270	2.99	Pass
	Counter Clockwise				
	Counter Clockwise				
8	Clockwise	<b>5.0*</b> δ <sub>0.3 g</sub>	184	2.97	Pass
9	Clockwise	5.5*δ <sub>0.3 g</sub>	202	3.05	Pass
10	Clockwise	<b>6.0</b> *δ <sub>0.3 g</sub>	221	3.01	Pass
11	Clockwise	6.5*δ₀.₃ ց	239	3.06	Pass
12	Clockwise	<b>7.0</b> <sup>*</sup> δ <sub>0.3 g</sub>	258	3.04	Pass
13	Clockwise	7.3* δ <sub>0.3 g</sub>	270	3.07	Pass
	Clockwise				
	Clockwise				

1. Lateral displacement should be ≥ 1.83 m (6 ft) for vehicles with a GVWR of 3,500 kg (7,716 lb) or less; and ≥ 1.52 m (5ft) for vehicles with a GVWR greater than 3,500 kg (7,716 lb).

#### DATA INDICATES COMPLIANCE:

PASS/FAIL PASS

**REMARKS**:

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

# DATA SHEET 8 MALFUNCTION WARNING TEST

VEHICLE MAKE/M	IODEL/	BODY STYLE:	Toyota / Highland	er / MP	V		
VEHICLE NHTSA	No.:	C85104	TEST DATE	:	10-19-0	7	
Before simulating a	an ESC	system malfur	LB CHECK FUNC Inction activate the v he bulb check and t	ehicle i		s.	)
METHOD OF MAL Describe method o			FION: on: 1) Remove	<u>ECU B</u>	Fuse to s	simulate	
steering angle sense	sor failu	ire. 2) Disc	connect LR Wheel	Speed	Sensor_		
if necessary the ve	and rei hicle is illumina	mains illuminat driven at least te after ignitior	FION: ed after ignition loc 2 minutes n system is activate	<u>X</u>	Yes _	No	
SEE REMARKS	Secor	nds (must be w	ithin 2 minutes)	X	Pass _	Fa	il
Cycle ignition locking telltale illuminates a			e vehicle's engine.	Verify X	that the r _Yes	nalfuncti No	on )
After the ESC systemeter remain illuminated.		estored to norm	nal operation verify		telltale c Yes		)
DATA INDICATES	COMP	LIANCE:		PASS	/FAIL <u>P</u>	ASS	
REMARKS: Malfunction without drivi			nediately upon cycl	ing igni	tion locki	ng syster	m
	Alan I	da			· 1	0-26-07	

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

# 4.0 TEST EQUIPMENT LIST AND CALIBRATION INFORMATION

Туре	Output	Range	Resolu tion	Accuracy	Specifics	Serial Number	Calibration
Tire Pressure Gage	Vehicle Tire Pressure	0-100psi	1 psi	±2.0% of applied pressure	Marsh Model: Series J 0-100psi	_AG-102_	By: <u>TRC</u> Date: <u>11-6-06</u> Due: <u>11-6-07</u>
Platform Scales	Vehicle Total, Wheel, and Axle Load	0-2500 lb per each of four pads	0.5 lb	±1.0% of applied load	Mettler Toledo Model: JXGA1000	<u>5225831-</u> <u>5JC</u>	By: <u>_Mettler</u> Date: <u>8-20-07</u> Due: <u>11-20-07</u>
Automated Steering Machine with Steering Angle Encoder	Handwheel Angle	±800 deg	0.25 deg	±0.25 deg	Heitz Automotive Testing Model: Sprint 3	_60303_	By: <u>TRC</u> Date: <u>6-18-07</u> Due: <u>6-18-08</u>
Multi-Axis Inertial Sensing System	Longitudinal, Lateral, and Vertical Acceleration Roll, Yaw, and Pitch Rate	Accelero meters: ±2 g Angular Rate Sensors: ±100 deg /s	Acceler ometers : ≤10 ug Angular Rate Sensor s: ≤0.004 deg/s	Accelerome ters: ≤0.05% of full range Angular Rate Sensors: 0.05% of full range	BEI Technologies Model: MotionPAK MP- 1	_0767	By: <u>BEI Tech.</u> Date: <u>6-21-07</u> Due: <u>6-21-08</u>
Radar Speed Sensor and Dashboard Display	Vehicle Speed	0-125 mph	0.009 mph	±0.25% of full scale	A-DAT Corp. Radar Model: DRS-6 Display Model: RD-2	_1400603	By: <u>A-DAT</u> Date: <u>9-9-06</u> Due: <u>9-9-07</u>
Ultrasonic Distance Measuring System	Left and Right Side Vehicle Height	5-24 inches	0.01 inches	±0.25% of maximum distance	Massa Products Corporation Model: M- 5000/220	_ <u>104619</u> <u>&amp; 104613</u>	By: <u>TRC</u> Date: <u>per test</u> Due: <u>per test</u>
Data Acquisition System [Amplify, Anti- Alias, and Digitize]	Record Time; Velocity; Distance; Lateral, Longitudinal, and Vertical Accelerations; Roll, Yaw, and Pitch Rates; Steering Wheel Angle.	Sufficient to meet or exceed individual sensors	200 Hz	Sufficient to meet or exceed individual sensors	Dewetron Sidehand DAS Model: DA-121-16 Digitizer Model: Dewe-Orion- 1616-100 Amplifier/AntiAli asing: MDAQ- FILT-10-S	<u>   12060    1105                             </u>	By: <u>Dewetron</u> Date: <u>3-20-07</u> Due: <u>3-20-08</u>
Load Cell	Vehicle Brake Pedal Force	0-300 lb	1 lb	±0.05% of full scale	DATRON Model: DTM- LPA	_ <u>4970-</u> 1103_	By: <u>TRC</u> Date: <u>per test</u> Due: <u>per test</u>
Coordinate Measurement Machine	Inertial Sensing System Location	0-10 feet	0.001 inch	±0.003% of full scale	FARO International Model: Faro Arm N10	_ <u>N10-02-03-</u> 	By: <u>FARO</u> Date: <u>12-04-06</u> Due: <u>12-04-07</u>
Outriggers	No output. Safety Item.	N/A	N/A	N/A	NHTSA Titanium Outriggers Model: Docket 2007-27662-11	N/A	N/A

#### 5.0 PHOTOGRAPHS

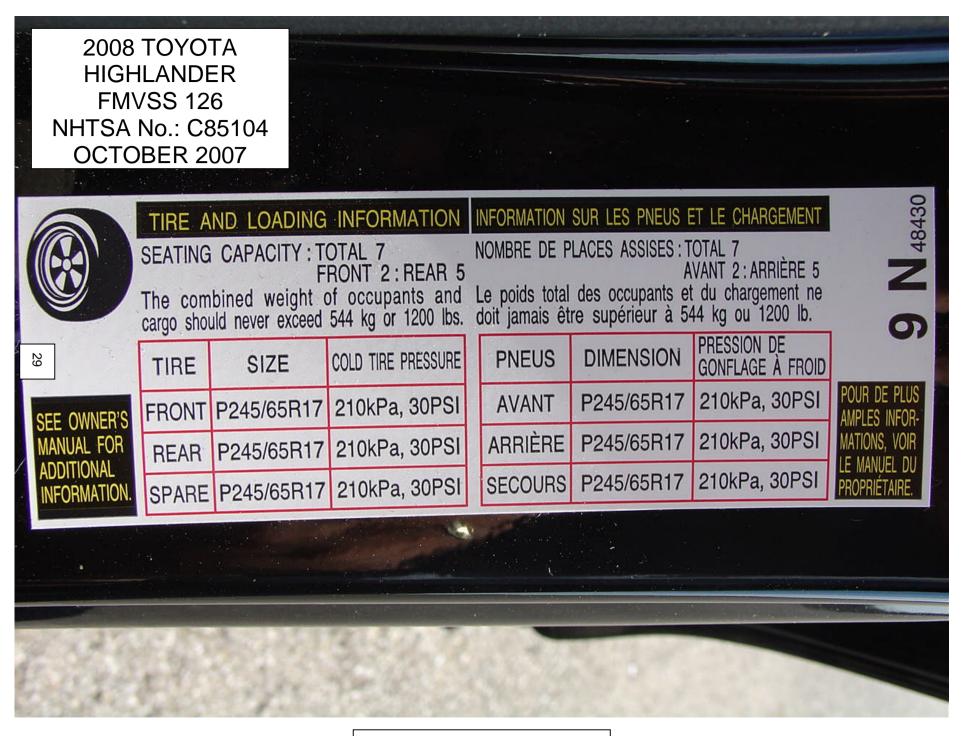
- 5.1 ¾ FRONTAL VIEW FROM LEFT SIDE OF VEHICLE
- 5.2 VEHICLE CERTIFICATION LABEL
- 5.3 VEHICLE PLACARD
- 5.4 WINDOW STICKER (MONRONEY LABEL)
- 5.5 ESC MALFUNCTION AND ESC OFF TELLTALE
- 5.6 ESC OFF CONTROL
- 5.7 TEST VEHICLE WITH OUTRIGGERS
- 5.8 TEST INSTRUMENTATION STEERING WHEEL CONTROLLER AND DATA ACQUISITION SYSTEM
- 5.9 TEST INSTRUMENTATION STEERING CONTROLLER BATTERY BOX AND BALLAST
- 5.10 TEST INSTRUMENTATION VEHICLE SPEED SENSOR
- 5.11 TEST INSTRUMENTATION BODY ROLL SENSOR (DRIVER SIDE)
- 5.12 TEST INSTRUMENTATION BODY ROLL SENSOR (PASSENGER SIDE)



5.1 ¾ FRONTAL VIEW FROM LEFT SIDE OF VEHICLE



5.2 VEHICLE CERTIFICATION LABEL



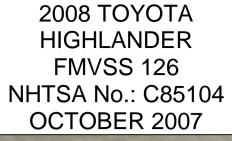
5.3 VEHICLE PLACARD

a di serie		HIGHLANDER		4-DOOR	4X4 SUV	191	MANU	FACTURER'S		RETAIL PRICE	\$28,750.00	
<b>ΤΟΥΟΤΑ</b>	VIN:	JTEES41A58		-			CQ			ack Roof Rails and	240.00	
toving forward >	YR/MDL: PORT/PLAN		LR: BLAC	CK/FC40		(0202/40)	EH	Power Outsid	er Package In de Mirrors, W	cludes: Heated Indshield Wiper	60.00	
	ST	ANDARD EQUIPM	ENT				FE	De-icer Grid 50 State Em	issions			
HANICAL & PERFORMANCE		- Color-	Keyed Burn	pers/Dr Hand	les/Foldable		TO	w/ Rear Ven	r Air Conditio	3Rd Row	415.00	
iL 270HP 24-Valve V6 Eng w/D Wheel Drive/4-WhI ind Suspen -Spd Automatic Trans w/Seque Electronic Power Steering Syste	sion ntial Shift	- Sivr P - Bik Fo	ainted Fr Gr g Lamp & F	ors/Small Rea rille/Rr Lic Ga Rr Step/Bump Intermittent W	arnish er Lower Cvr	rs	10	towing capa w/Engine Oil coupling, Tra Cooler,150 a	ickage includi city, Heavy D I Cooler, 200 ansmission O emp alternato	watt fan il Cooler w/ Water r, and Pre-Wire	220.00	
4WhI Pwr Ast Vent Fr/Solid Rr D Hill-Start Assist & Downhill Assi	isc Brake	- Flexib	le Mast Ant	tenna / Rr Priv uto-off Headla	vacy Glass		H8.	Harness Fleet Credit				
17' 6-Spoke Alloy Wheels/245/6 Full Size Spare Tire on 17' Alloy	R17 Tires	COMFO	RT AND CO	ONVENIENCE								
SAFETY - Star Safety System Includes:		- AM/FI	M/CD w/6 S	pks, Mini Plug Door Locks/	3		ð 14.					
Enhanced Veh Stability Ctrl w/T		- Remo	te Keyless I	Entry/Convers	sation Mirror							
Anti-Lock Brakes w/Brake Assi: - Dr & Fr Pass Advanced Front Ai	rbags/	- Cloth	Int, 8-way F	lescopic Steer rt Dr/ 4-way F	Pass,							
Driver Knee Airbag, Dr & Fr Pas Mounted Side Airbags, 3 Row				Row Seat,w/								
Roll-Sensing Side Curtain Airbag - Dr & Fr Pass Active Headrests	js.			+ Center Sto sole, 3rd Row						200	0YOT 80	TA
- Direct Tire Pressure Monitoring		w/fold	headrests	/ Fold Flat Int	to Floor				ŝ.		GHLAND	
3 Pt Seat Balte All Section Por												
- 3-Pt Seat Belts - All Seating Pos - 2nd Row CRS Lower/Top Tether				s/10 Cup/4 Bo ted instrument					- <u>#</u>			
									. <u>#</u>		MVSS 12	
- 2nd Row CRS Lower/Top Tether EXTERIOR	Anchors	- Optitr	on illuminat	ted instrument	t meters				<u>ă</u> .	FI	MVSS 12	6
- 2nd Row CRS Lower/Top Tether	Anchors	- Optitr rehensive coverage, Sysenföl det for details. An ascended ndet pre-follwary samica, Ga	on illuminat 1,000-mile powert service contract m soline, licenze pr	ted instrument	t meters 5-year body panel the vahicle.					FI NHTS	MVSS 12 A No.: C8	26 85104
- 2nd Row CRS Lower/Top Tether EXTERIOR The New Vabicle Limited Warranty provides 36-m correction particular warranty. See Dwase's War Ask dealer for deals. Manufacture's suggested retail price includes m state and local taxes and dealer and estimitator in	Anchors	- Optitr rehensive coverage, 5-year/50 for for details. An exercised nated pre-follwary service, Ga cessories are not included in	on illuminat 1,000-mile sowert service contract m colline, licence at the manufacture?	ted instrument train coverage, plus t may be available for ad title feat, applica 's suggested retail p	t meters S-year body panel the vehicle, able federal, price,	dealer.	I		ă.	FI NHTS	MVSS 12	26 85104
- 2nd Row CRS Lower/Top Tether EXTERIOR The New Vabicle Limited Warranty provides 38-m correctors partoration warranty. See Owner's With Ask dealer for details. Manufacture's suggested retail and includes m state and local taxes and dealer and distributed in Compare this vehicle to o	Anchors	- Optitr rehensive coverage, 5-year/50 for for details. An exercised nated pre-follwary service, Ga cessories are not included in	on illuminat	ted instrument train coverage, plus train coverage,	t meters S-year body panel the vehicle, relie factors, price, ible at the (	dealer.			<u>a</u> .	FI NHTS	MVSS 12 A No.: C8	26 85104
- 2nd Row CRS Lower/Top Tether EXTERIOR The New Vabicle Limited Warranty provides 38-m correctors partoration warranty. See Owner's With Ask dealer for details. Manufacture's suggested retail and includes m state and local taxes and dealer and distributed in Compare this vehicle to o	Anchors	- Optitr	on illuminat	trein coverese, plus i may be realized for a state for a specie UIDE availai a 2008 models.	t meters S-year body panel the vehicle, relie factors, price, ible at the (	dealer.			ă.	FI NHTS	MVSS 12 A No.: C8	26 85104
- 2nd Row CRS Lower/Top Tether EXTERIOR The New Vehicle Limited Warrenty provides 38-m correction particulation annuals. See Dense's We New Vehicle See Dense's We have been a set of the set of the set of the set of the set of the set of the set of the set of the set of the Compare this vehicle to o These estin	Anchors	- Optitr minimize coverage, Sysenfol the for dealth. An examined mode pre-fold that a same of cessories are not included in FREE FUEL ECO aw EPA methods beg FUEL ECONOM	on illuminat	trein coverese, plus i may be realized for a state for a specie UIDE availai a 2008 models.	t meters Sysar key parel the valicie. able federal, rrice. ble at the r	dealer.			ž.	FI NHTS	MVSS 12 A No.: C8	26 85104
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5.4 WINDOW STICKER (MONRONEY LABEL)



# 5.5 ESC MALFUNCTION AND ESC OFF TELLTALE





5.6 ESC OFF CONTROL

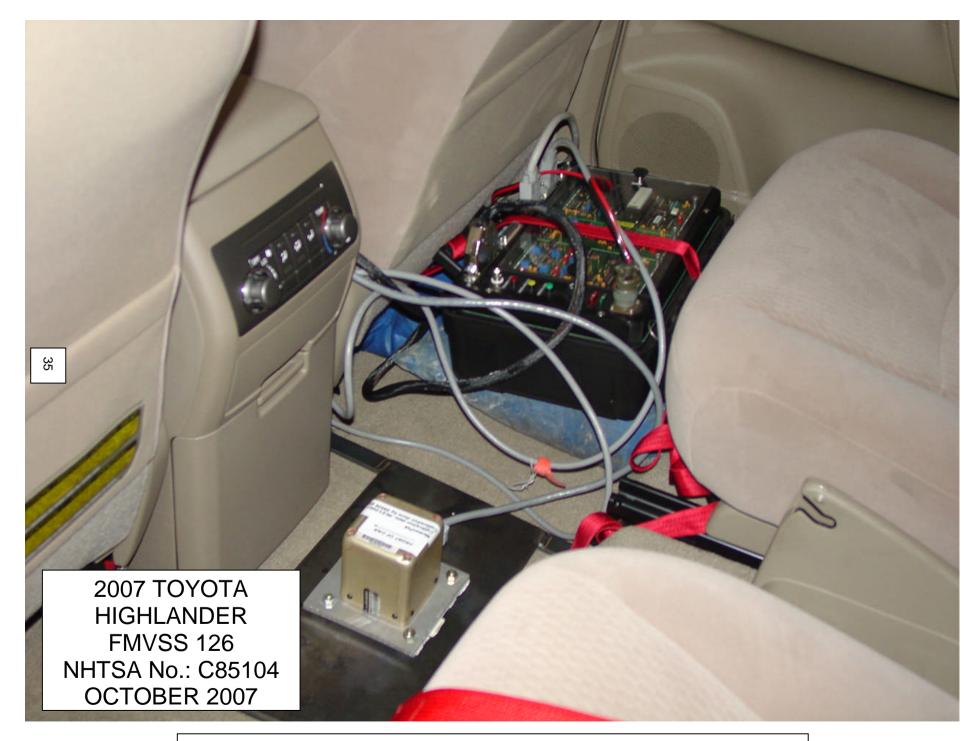
32



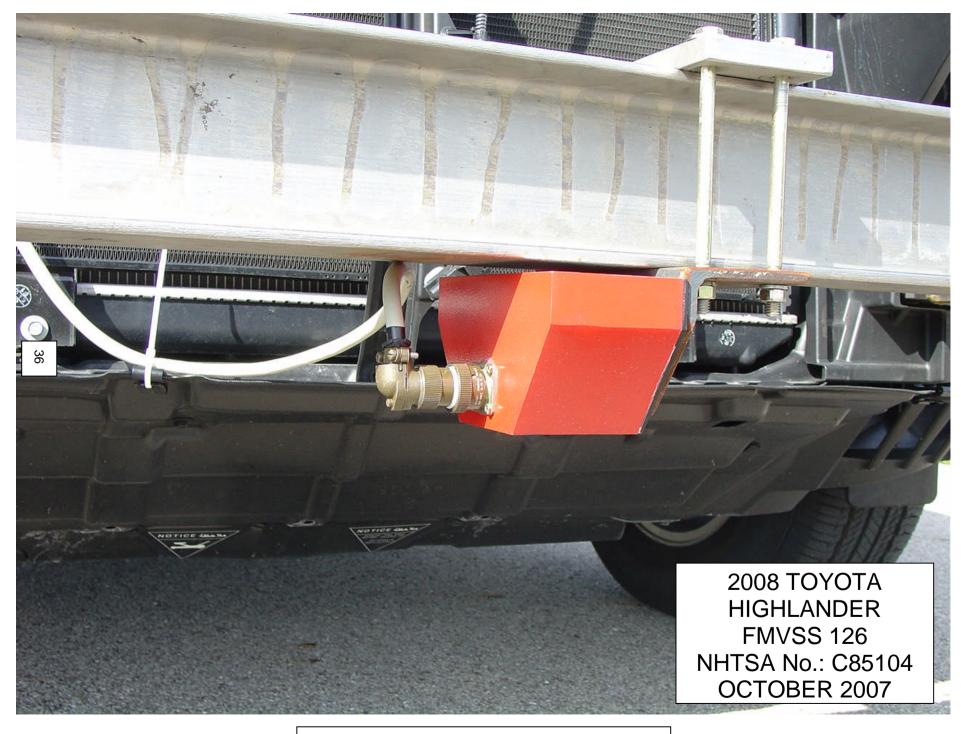
### 5.7 TEST VEHICLE WITH OUTRIGGERS



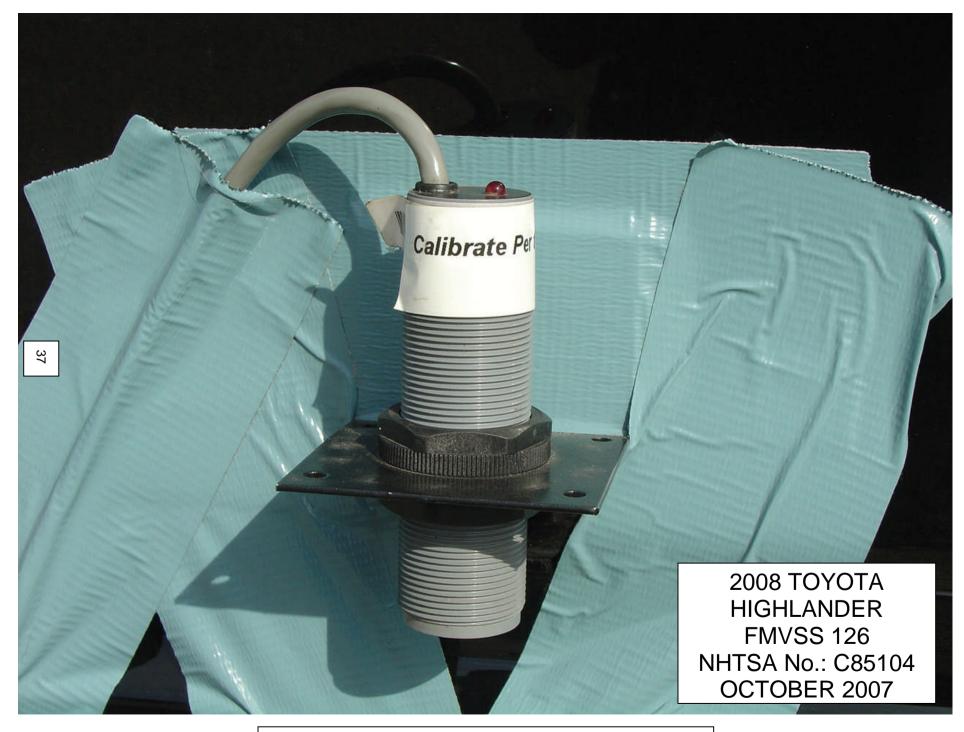
5.8 STEERING WHEEL CONTROLLER AND DATA ACQUISITION SYSTEM



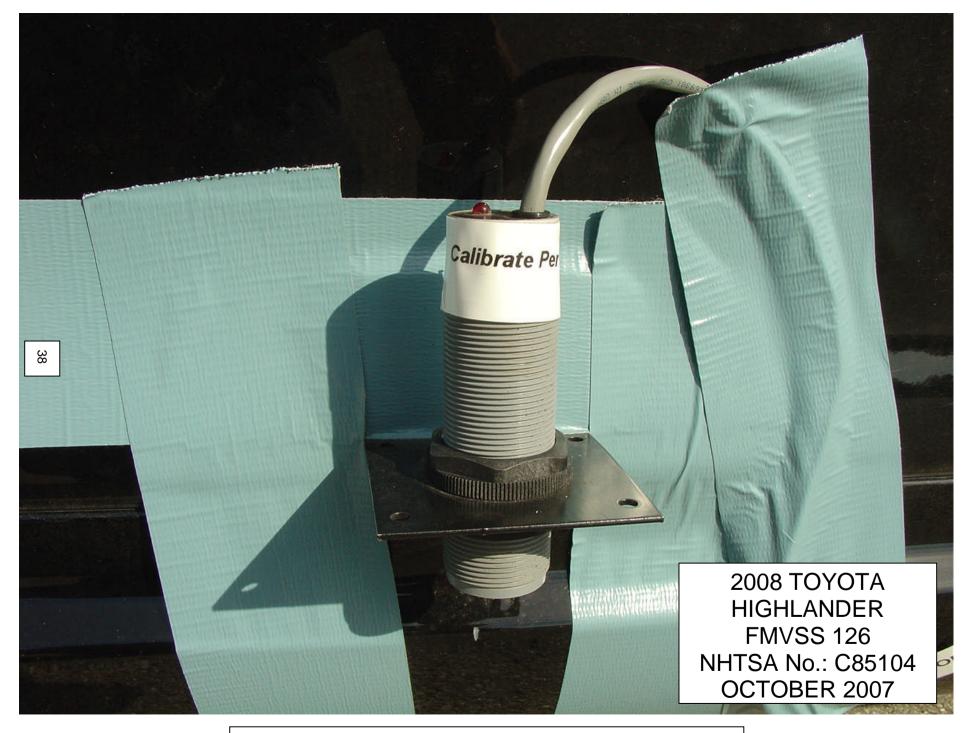
5.9 STEERING CONTROLLER BATTERY BOX AND BALLAST



5.10 VEHICLE SPEED SENSOR



5.11 BODY ROLL SENSOR (DRIVER SIDE)



5.12 BODY ROLL SENSOR (PASSENGER SIDE)

### 6.0 DATA PLOTS

Figure 1.	Steering Angle and Yaw Rate Time History, Counter-Clockwise Initial Steer Tests
Figure 2.	Steering Angle, Lateral Acceleration, and Lateral Displacement Time History, Counter-Clockwise Initial Steer Tests
Figure 3.	Steering Angle and Yaw Rate Time History, Clockwise Initial Steer Tests
Figure 4.	Steering Angle, Lateral Acceleration, and Lateral Displacement Time History, Clockwise Initial Steer Tests

### 6.0 DATA PLOTS

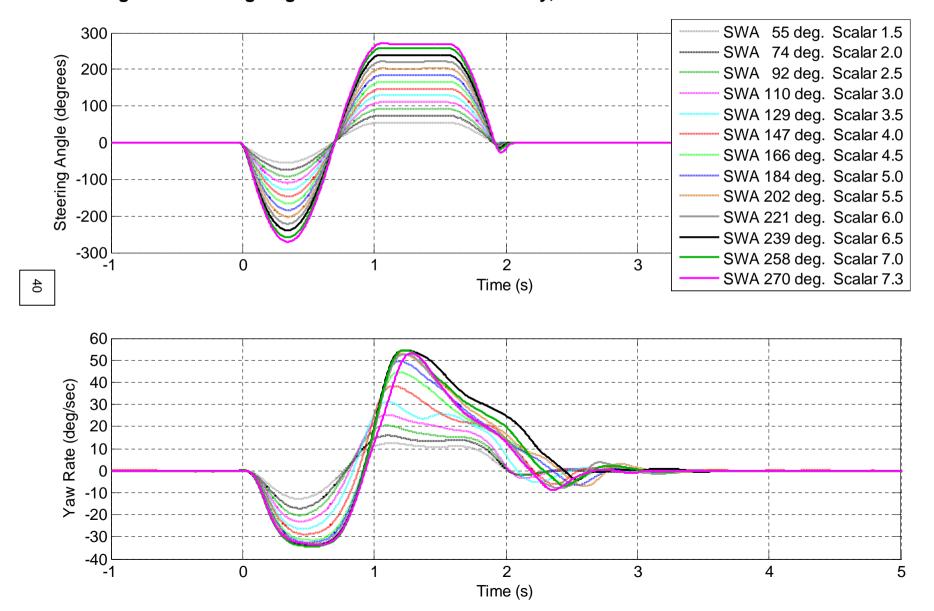
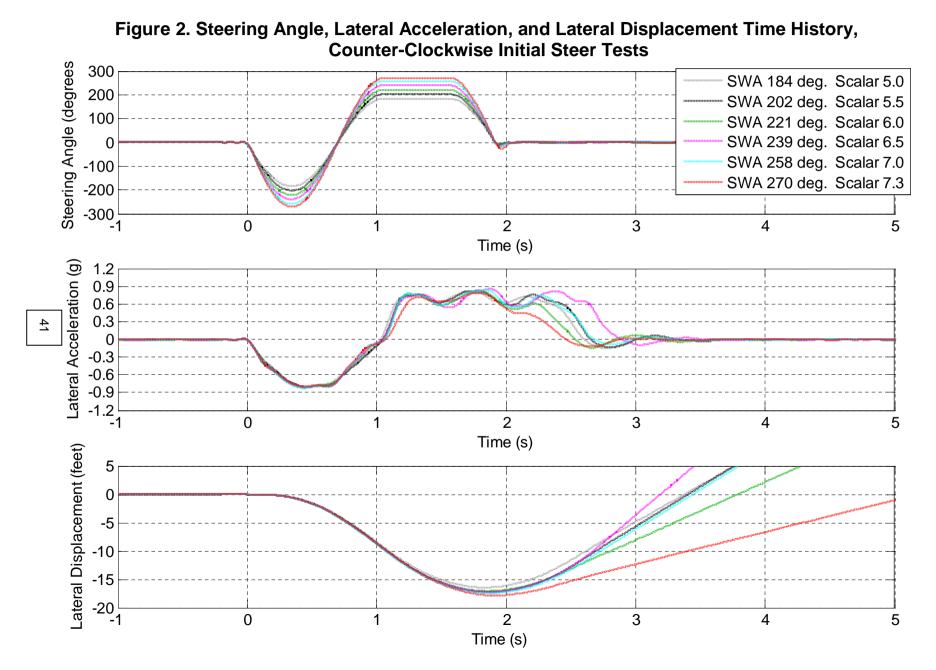


Figure 1. Steering Angle and Yaw Rate Time History, Counter-Clockwise Initial Steer Tests



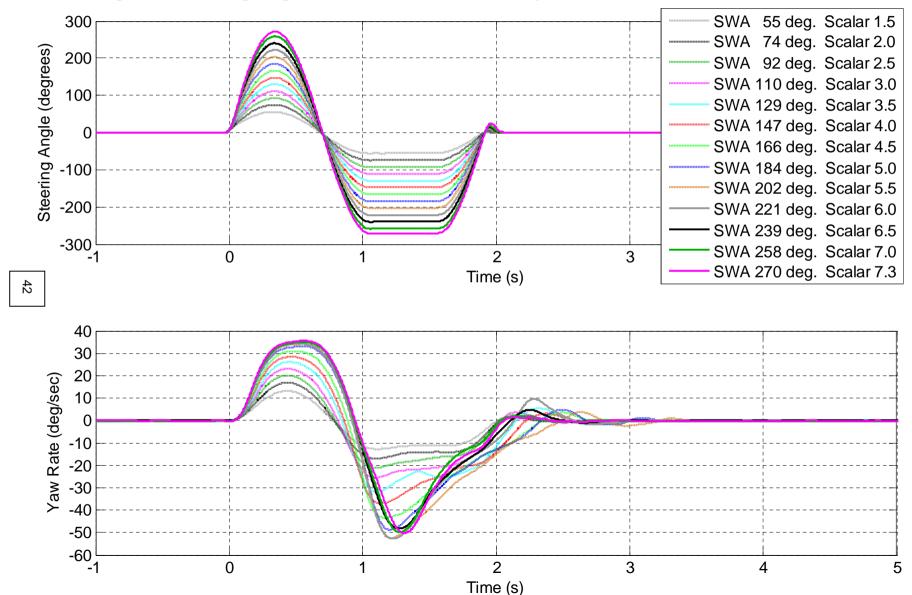
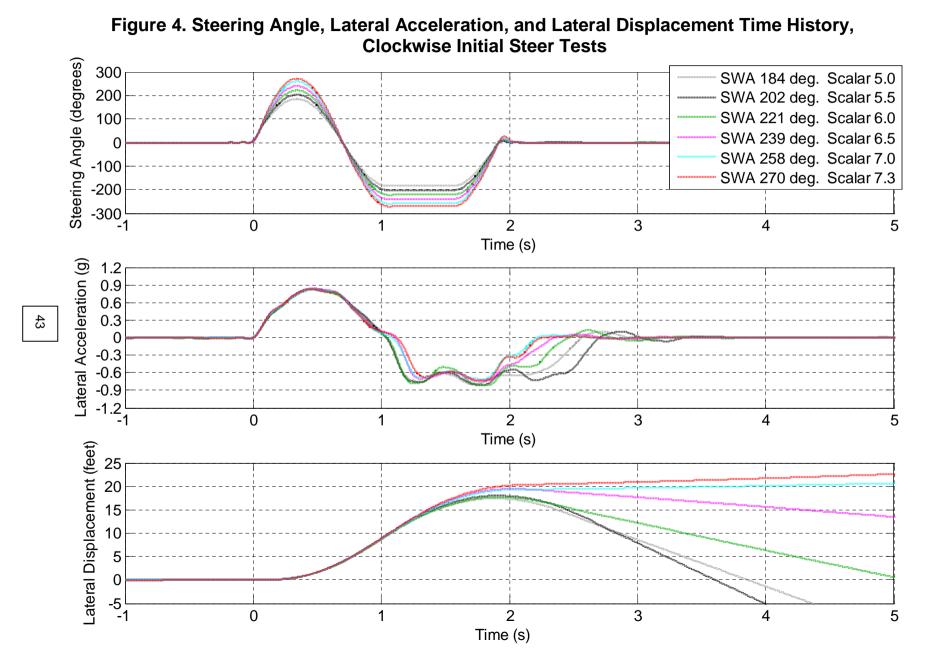


Figure 3. Steering Angle and Yaw Rate Time History, Clockwise Initial Steer Tests

### 6.0 DATA PLOTS...continued



### 7.0 OTHER DOCUMENTATION

- 7.1 OWNER'S MANUAL PAGES
- 7.2 VEHICLE ARRIVAL CONDITION REPORT
- 7.3 VEHICLE COMPLETION CONDITION REPORT
- 7.4 SINE WITH DWELL TEST RESULTS
- 7.5 SLOWLY INCREASING STEER TEST RESULTS
- 7.6 INERTIAL SENSING SYSTEM LOCATION COORDINATES

### 7.1 OWNER'S MANUAL PAGES

# 2-4. Using other driving systems

ontrol system indicator does not come on the OP\* switch or the engine switch is turned to introl system indicator does not come on whe ed. In the above cases have your vehicle de

affect the downhill assist control system ate on the following surfaces, which may lead serious injury.

s wet or muddy roads

46

# To help enhance driving safety and performance, the following sys-

tems operate automatically in response to various driving situations. Be aware, however, that these systems are supplementary and should not be relied upon too heavily when operating the vehicle.

#### ABS (Anti-lock Brake System)

Restrains the vehicle from slipping when driving on slick road surfaces. or in the event of sudden braking.

BA (Brake Assist)

Generates an increased level of braking force after the brake pedal is depressed, when the system detects a panic stop situation.

VSC (Vehicle Stability Control)

Helps the driver to control skidding when swerving suddenly or turning on slippery road surfaces.

#### TRAC (Traction Control)

Maintains drive power and prevents the front wheels (2WD models) or four wheels (4WD models) from spinning when starting the vehicle or accelerating on slippery roads.

#### Hill-start assist control

Prevents the vehicle from rolling backwards when starting on incline or slippery slope.

#### EPS (Electric Power Steering)

Employs an electric motor to reduce the amount of effort needed to turn the steering wheel.

## **2008 TOYOTA** HIGHLANDER **FMVSS 126** NHTSA No.: C85104 **OCTOBER 2007**

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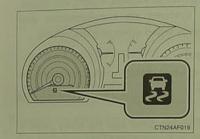
When driving

#### **OWNERS MANUAL PAGES** 7.1

# **2008 TOYOTA** HIGHLANDER **FMVSS 126** NHTSA No.: C85104 OCTOBER 2007

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### When the VSC/TRAC/hill-start assist control systems are operation



If the vehicle is in danger of slip. ping, rolling backwards when starting on an incline, or the front wheels (2WD models) or four wheels (4WD models) spin, the indicator flashes to indicate that the VSC/TRAC/hill-start assist control systems have been engaged.

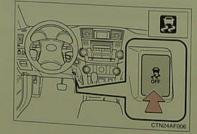
A buzzer (intermittent) sounds to indicate that VSC is operating.

The stop lights and high mounted stoplight turn on when the hillstart assist control system is operating.

#### To disable TRAC and/or VSC

If the vehicle gets stuck in fresh snow or mud, TRAC and VSC may reduce power from the engine to the wheels. You may need to turn the system off to enable you to rock the vehicle in order to free it.

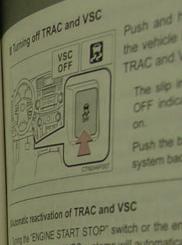
#### Turning off TRAC



Quickly push and release the button to turn off TRAC.

The slip indicator light should come on.

Push the button again to turn the system back on.



mainter TRAC and VSC systems will automatic

unatic TRAC reactivation

in the TRAC system is turned off, the TRAC system

kinzle TRAC and VSC reactivation

It RAC and VSC systems are turned off, the systems with which speed increases.

its and vibrations caused by the ABS, TRAC masist control

sourcey be heard from the engine compartment estimation of the vehicle begins to move. This etaanaturction has occurred in any of these tiftelologing conditions may occur when the ers live of these indicates that a malfunction vatrs nay be feit through the vehicle body and corsund may be heard after the vehicle come reapedal may pulsate slightly when the ABS seepedal may move down slightly after the A

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# **OWNERS MANUAL PAGES**



If the vehicle is in day ping, rolling backie starting on an incline wheels (2WD model wheels (4WD models indicator flashes to m the VSC/TRAC/hile control systems

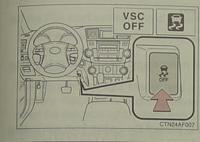
A buzzer (intermitter)

start assist control a

operating.

engaged.

#### Turning off TRAC and VSC



Push and hold the button while the vehicle is stopped to turn off TRAC and VSC.

The slip indicator light and VSC OFF indicator light should come on.

Push the button again to turn the system back on.

#### Automatic reactivation of TRAC and VSC

Turning the "ENGINE START STOP" switch or the engine switch OFF after turning off the TRAC and VSC systems will automatically re-enable them.

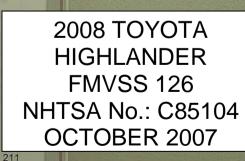
#### Automatic TRAC reactivation

If only the TRAC system is turned off, the TRAC system will turn on when vehicle speed increases.

#### Automatic TRAC and VSC reactivation

If the TRAC and VSC systems are turned off, the systems will not turn on even when vehicle speed increases.

- Sounds and vibrations caused by the ABS, TRAC, VSC, BA and hillstart assist control
- A sound may be heard from the engine compartment when the engine is started or just after the vehicle begins to move. This sound does not indicate that a malfunction has occurred in any of these systems.
- Any of the following conditions may occur when the above systems are operating. None of these indicates that a malfunction has occurred.
- · Vibrations may be felt through the vehicle body and steering.
- · A motor sound may be heard after the vehicle comes to a stop.
- . The brake pedal may pulsate slightly when the ABS is activated.
- The brake pedal may move down slightly after the ABS is activated.

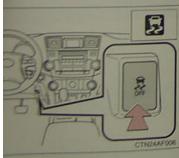


## **OWNERS MANUAL PAGES**

ble TRAC and/or VSC

vehicle gets stuck in fresh snow or mud, TRAC and power from the engine to the wheels. You may ret tem off to enable you to rock the vehicle in order to be

#### ing off TRAC



Quickly push and read button to turn off TRAD

The slip indicator come on. Push the button ag

system back on

indicate that VSC is the The stop lights and how stoplight turn on whether

48

start assist control is operational when

e shift lever is in the D or S position.

te brake pedal is not depressed.

#### operation sound

an the steering wheel operates, a motor sound (whirring sound) real does not indicate a malfunction.

#### uced effectiveness of EPS

effectiveness of EPS is reduced to prevent the system from overhal in there is frequent steering input over an extended period of time 1 ring wheel may feel heavy as a result. Should this occur, refrantessive steering input or stop the vehicle and turn the engine off. The su should return to normal within 10 minutes.

### CAUTION

49 not operate effectively when

dequate gripping ability are used (such as excessively wo es on a snow covered road). he vehicle hydroplanes while driving at high speed on wet or slick roat

upping distance when the ABS is operating on the wet or slick road ABS is not designed to shorten the vehicle's stopping distance. Alward Intain a safe distance from the vehicle in front of you in the following suns.

then driving on dirt, gravel or snow-covered roads hen driving with tire chains

hen driving over bumps in the road

hen driving over roads with potholes or uneven roads C may not operate effectively when

tional control and power may not be achievable while driving on st road surfaces, even if the control of the surfaces even if the surfaces even road surfaces, even if the TRAC system is operating It drive the vehicle in conditions where stability and power may be los

### A CAUTION

#### If the hill- start assist control does not operate effectively

The hill start assist control may not operate effectively on steep inclines and roads covered in ice.

#### When the VSC is activated

The slip indicator light flashes and a warning buzzer sounds. Always drive carefully. Reckless driving may cause an accident. Exercise particular care when the indicator light flashes and a buzzer sounds.

#### When TRAC and VSC are off

Be especially careful and drive at a speed appropriate to the road conditions. As these are systems to ensure vehicle stability and driving force, do not turn off TRAC and VSC unless necessary.

#### Replacing tires

Make sure that all tires are of the same size, brand, tread pattern and total load capacity. In addition, make sure that the tires are inflated to the appropriate tire pressure level.

The ABS and VSC systems will not function correctly if different tires are fitted on the vehicle.

Contact your Toyota dealer for further information when replacing tires or wheels.

#### Handling of tires and suspension

Using tires with any kind of problem or modifying the suspension will affect the driving assist systems, and may cause the system to malfunction.

# **2008 TOYOTA HIGHI ANDER FMVSS 126** NHTSA No.: C85104 OCTOBER 2007

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When driving

### **OWNERS MANUAL PAGES**

#### 7.2 VEHICLE ARRIVAL CONDITION REPORT

CONTRACT NO. <u>DTNH22- 07-P-00332</u> DATE: <u>9/21/07</u>

FROM: Event Vehicles (Leasing Company)

TO: <u>TRC</u> PURPOSE: (X) Initial () Received () Present Receipt via Transfer vehicle condition MODEL YEAR/MAKE/MODEL/BODY STYLE: <u>2008 / Toyota / Highlander / MPV</u>

MANUFACTURE DATE: 06/07 NHTSA NO.: C85104

BODY COLOR: black VIN: JTEES41A582004636

ODOMETER READING: <u>3314</u> miles GVWR: <u>2,720 KG</u>

PURCHASE PRICE: \$ (leased) DEALER'S NAME: (leased)

- X ALL OPTIONS LISTED ON "WINDOW STICKER" ARE PRESENT ON THE TEST VEHICLE
- X TIRES AND WHEEL RIMS ARE NEW AND THE SAME AS LISTED
- X THERE ARE NO DENTS OR OTHER INTERIOR OR EXTERIOR FLAWS
- X THE VEHICLE HAS BEEN PROPERLY PREPARED AND IS IN RUNNING CONDITION
- X THE GLOVE BOX CONTAINS AN OWNER'S MANUAL, WARRANTY DOCUMENT, CONSUMER INFORMATION, AND EXTRA SET OF KEYS
- X PROPER FUEL FILLER CAP IS SUPPLIED ON THE TEST VEHICLE
- X PLACE VEHICLE IN STORAGE AREA
- X INSPECT THE VEHICLE'S INTERIOR AND EXTERIOR, INCLUDING ALL WINDOWS, SEATS, DOORS, ETC., TO CONFIRM THAT EACH SYSTEM IS COMPLETE AND FUNCTIONAL PER THE MANUFACTURER'S SPECIFICATIONS. ANY DAMAGE, MISADJUSTMENT, OR OTHER UNUSUAL CONDITION THAT COULD INFLUENCE THE TEST PROGRAM OR TEST RESULTS SHALL BE RECORDED. REPORT ANY ABNORMAL CONDITION TO THE NHTSA COTR BEFORE BEGINNING ANY TEST

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

#### 7.3 VEHICLE COMPLETION CONDITION REPORT

CONTRACT NO. <u>DTNH22- 07-P-00332</u> DATE: <u>10/21/07</u>
MODEL YEAR/MAKE/MODEL/BODY STYLE: 2008 / Toyota / Highlander / MPV
MANUFACTURE DATE: 06/07 NHTSA NO.: C85104
BODY COLOR: <u>black</u> VIN: <u>JTEES41A582004636</u>
ODOMETER READING: <u>3,374</u> miles GVWR: <u>2,720 KG</u>
LIST OF FMVSS TESTS PERFORMED BY THIS LAB:126

- X THERE ARE NO DENTS OR OTHER INTERIOR OR EXTERIOR FLAWS
- X THE VEHICLE HAS BEEN PROPERLY MAINTAINED AND IS IN RUNNING CONDITION
- X THE GLOVE BOX CONTAINS AN OWNER'S MANUAL, WARRANTY DOCUMENT, CONSUMER INFORMATION, AND EXTRA SET OF KEYS
- X PROPER FUEL FILLER CAP IS SUPPLIED ON THE TEST VEHICLE

#### **REMARKS**:

- Equipment that is no longer on the test vehicle as noted on Vehicle Arrival Condition Report: None.
- Explanation for equipment removal: N/A
- Test Vehicle Condition: Like new.

RECORDED BY:	Alan Ida	DATE:	10-26-07
APPROVED BY:	Jeff Sankey	DATE:	10-26-07

### 7.4 SINE WITH DWELL TEST RESULTS 2008 Toyota Highlander NHTSA No.: C85104

	Date Created 28-Sep		28-Sep-07									
File	SWA @ 5deg Ct		Time@5deg	COS	Time@COS	MOS	Time@MOS	YRR1(%)	YR1 (deg/sec)	YRR1 Ct	YRR175(%)	YR175 (deg/sec)
14	1336	50.35287	6.67183409	1718	8.58048254	1474	7.3603153	-3.34155	-0.418221188	1918	-2.0464843	-0.256133237
15	1963	50.2523	9.80800314	2346	11.7217771	2102	10.5024782	-1.07308	-0.173515441	2546	-0.1615136	-0.026116593
16	1294	50.18086	6.46034841	1677	8.37729518	1433	7.15781439	-0.21667	-0.044327769	1877	-0.1120791	-0.022929827
17	1423	50.53729	7.10812267	1807	9.02664525	1563	7.80789015	-0.6019	-0.153440574	2007	-0.0247002	-0.006296779
18	1170	50.55209	5.84217783	1554	7.76069044	1310	6.54311025	-0.80381	-0.251433729	1754	-0.5644588	-0.176563544
19	1310	50.3161	6.54497547	1694	8.4634531	1451	7.24631029	0.497559	0.190470006	1894	0.1377384	0.052727513
20	1302	50.29846	6.50484161	1686	8.42375739	1443	7.20656628	2.591054	1.157667514	1886	0.2062441	0.092148644
21	1760	50.23561	8.79338939	2144	10.7119523	1901	9.49530921	2.446715	1.215043082	2344	-0.1642748	-0.081579173
22	1527	50.37615	7.62871739	1911	9.54645755	1668	8.33047937	5.096837	2.706252464	2111	0.2624135	0.139332934
23	1183	50.44118	5.90664649	1566	7.82351856	1323	6.60818544	1.781624	0.944957116	1766	-0.1070086	-0.056756359
24	1998	50.36339	9.98124927	2381	11.8977911	2138	10.6824784	0.806362	0.440412929	2581	0.1377116	0.075214367
25	1479	50.44882	7.38783871	1862	9.30454964	1619	8.08907741	2.862816	1.565146507	2062	0.1825769	0.099817649
26	1697	50.24941	8.47944804	2081	10.396341	1838	9.18066888	-1.57295	-0.838078185	2281	-0.1650176	-0.087922599
27	1258	50.35521	6.28256333	1640	8.19154334	1396	6.97097387	0.17225	-0.022143794	1840	0.2750597	-0.035360595
28	1584	50.24713	7.91237104	1967	9.82673597	1723	8.6059945	-0.03622	0.006130778	2167	0.6765707	-0.114532988
29	1497	50.10659	7.47671096	1880	9.39405279	1636	8.17403588	-0.80313	0.167490216	2080	-0.5274894	0.110006874
30	1513	50.31676	7.55774635	1897	9.47635944	1653	8.25712282	-0.2508	0.063896666	2097	0.2303611	-0.058690495
31	1452	50.24453	7.25411448	1836	9.17266365	1592	7.95494554	0.645692	-0.20547284	2036	0.1357054	-0.04318431
32	1549	50.33576	7.7363704	1933	9.6555194	1689	8.4375794	1.152526	-0.426416975	2133	0.2466498	-0.091256642
33	1618	50.39916	8.08304691	2002	10.0019482	1758	8.78451737	2.228002	-0.966775234	2202	0.4084412	-0.177230944
34	1681	50.45794	8.39531141	2064	10.3137415	1821	9.09674994	3.358998	-1.637643835	2264	-0.1923019	0.093754731
35	1483	50.3661	7.40708502	1866	9.32479124	1623	8.10854238	3.877222	-2.030339695	2066	0.2236727	-0.11712808
36	1513	50.17387	7.55810014	1896	9.47480756	1653	8.25924366	1.505072	-0.79138522	2096	-0.0050554	0.002658178
37	1092	50.22345	5.45263764	1475	7.36893641	1232		-0.40564	0.195899593	1675	0.3678251	-0.177638793
38	1305	50.32246	6.51897987	1689	8.43520817	1446	7.22030737	-0.10599	0.052671383	1889	0.1293879	-0.064298871
39	1923	50.11842	9.60865997	2307	11.5254061	2064	10.3102851	-0.13403	0.067230246	2507	0.1139941	-0.057178565

# 7.4 SINE WITH DWELL TEST RESULTS 2008 Toyota Highlander NHTSA No.: C85104

	Date Created	1	28-Sep-07					
File	YRR175 Ct	2nd Yaw Peak(deg/sec)	2nd Yaw Peak Ct	Lat Disp (ft)	Lat. Acc. 1.07s (g)	1st SWA Peak(deg)	1st SWA Peak Ct	2nd SWA Mean(deg)
14	2068	12.51576845	1561	-3.9996353	0.387640496	54.96414341	1402	55.0060593
15	2696	16.16990118	2185	-5.2103978	0.475908422	73.86165598	2030	73.82237915
16	2027	20.45860251	1513	-6.2705909	0.530522359	91.72023703	1362	91.78527463
17	2157	25.4928247	1643	-7.1550766	0.563287805	110.0146459	1492	110.0001333
18	1904	31.28014702	1391	-8.0794526	0.568674431	128.9836835	1239	129.0573852
19	2044	38.28091455	1539	-8.7432745	0.462604853	146.9352894	1379	147.0249315
20	2036	44.67940027	1540	-9.3626565	0.218248533	165.7251672	1372	166.0021774
21	2494	49.66017329	1998	-9.5418456	0.180712685	184.1189722	1829	183.9392804
22	2261	53.09670455	1769	-9.7758799	0.079032802	202.4360344	1596	202.218944
23	1916	53.03907506	1429	-9.7792991	0.051835005	221.561067	1251	221.0465636
24	2731	54.6172936	2245	-9.8615336	0.077832091	239.5231784	2066	239.0551247
25	2212	54.67157733	1725	-10.024013	0.026302845	258.6525909	1547	258.0190582
26	2431	53.28073801	1954	-9.8114356	0.001370068	270.5151653	1766	269.8599042
27	1990	-12.85560559	1481	4.0927071	-0.395788993	55.6818774	1324	55.46534357
28	2317	-16.9284572	1805	5.2122404	-0.482125017	74.5683289	1651	74.40787238
29	2230	-20.8548041	1717	6.3347205	-0.532542611	92.50611169	1565	92.25567379
30	2247	-25.47760293	1733	7.0193885	-0.576857133	110.7903962	1581	110.5976792
31	2186	-31.82209286	1675	7.8596755	-0.583155021	129.8643484	1521	129.5490716
32	2283	-36.99846813	1776	8.6298972	-0.518302326	147.7295888	1617	147.61176
33	2352	-43.39202888	1852	9.2448203	-0.370784959	166.8085516	1687	166.5680503
34	2414	-48.75393446	1922	9.7406495	-0.090172515	185.028724	1749	184.4344995
35	2216	-52.36583425	1726		-0.085473401	203.2607378	1551	202.6824442
36	2246	-52.58120445	1759	9.8662297	-0.055321624	222.2136364	1582	221.6565103
37	1825	-48.29436329	1347	10.040385	0.056286086	240.4257419	1160	239.552181
38	2039	-49.69464442	1561	9.9866329	0.020806108	259.3339088	1374	258.3328309
39	2657	-50.15921259	2186	10.068616	0.072641579	271.3590917	1992	270.2414164

### 7.5 SLOWLY INCREASING STEER TEST RESULTS

2008 Toyota Highlander NHTSA No.: C85104

Date Created			28-Sep-07							
File Vehicle	EventPt	DOS	MES [mph]	Mean SPD [mph]	AYcount_	THETAENC [degree]	AYCG [g]	r_squared	ZeroBegin	ZeroEnd
6 2008 Toyota Highlander	1800	1	49.316429	49.58965835	2350	-37.08287741	-0.30368	0.996557	1600	1800
8 2008 Toyota Highlander	1635	1	49.67412	49.92447386	2176	-36.44449039	-0.30148	0.999631	1435	1635
9 2008 Toyota Highlander	1292	1	49.657496	49.78635623	1836	-36.68911726	-0.3037	0.99731	1092	1292
10 2008 Toyota Highlander	1293	0	49.428071	49.75390576	1849	37.74113407	0.304508	0.996949	1093	1293
11 2008 Toyota Highlander	1642	0	50.203326	50.30838145	2188	36.7721179	0.305091	0.996646	1442	1642
12 2008 Toyota Highlander	1869	0	49.219816	49.59087297	2408	36.19727003	0.303305	0.998522	1669	1869
Averages						36.8	0.303627			

Б	Scalars	Steering Angles (deg)
-4	Ocalars	Oleening Angles (deg)

	•
1.5	55
2	74
2.5	92
3	110
3.5	129
4	147
4.5	166
5	184
5.5	202
6	221
6.5	239
7	258
7.3	270

### 7.6 INERTIAL SENSING SYSTEM LOCATION COORDINATES 2008 Toyota Highlander NHTSA No.: C85104

device version device certification date today is		0		
Label		ActualX	ActualY	ActualZ
C_DEVICEPOS001 M_PLANE001 M_LINE001 M_FRONT_AXLEORI C_COORDSYS001 M_LEFT_FRT_TIRE_TRI M_TOP_OF_SENSOR M_TOP_OF_ROOF M_FLOOR Track Width		695.9805 0 350.4818 1768.141 2176.578	-196.689 49.0924 0 89.916 886.1192 910.6262 -489.4826 1625	36.5446 0 0 -139.1184 178.4596 1349.12
Roof Height (relative to	ground)			1698.425
Motion Pak - x-distance Motion Pak - y-distance Motion Pak - z-distance		1768.141	-16.2968	438.8647